

GAMETOOLS

ADVANCED TOOLS FOR DEVELOPING HIGHLY REALISTIC COMPUTER GAMES

DUMMY VISIBILITY MODULES

Document identifier: **GameTools-3-D3.1-01-1-0-
Dummy Visibility Modules**

Date: **29/04/2005**

Work package: **WP03: Visibility**

Partner(s): **VUT**

Leading Partner: **VUT**

Document status: **DRAFT**

Deliverable identifier: **D3.1**

Abstract: Dummy Modules Report for Visibility



Delivery Slip

	Name	Partner	Date	Signature
From	Michael Wimmer	VUT	29-04-05	
Reviewed by	Moderator and reviewers			
Approved by				

Document Log

Issue	Date	Comment	Author
1-0	29-04-05	First draft	Jiri Bittner (VUT)

Document Change Record

Issue	Item	Reason for Change

Files

Software Products	User files / URL
Word	gametools-ist-2-004363-3-d3.1-01-1-0-dummy visibility modules.doc

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Chapter 1

Overview

The visibility workpackage aims to develop methods for making use of restricted visibility in large scenes. The major goal of these methods is to avoid wasting computational power on currently invisible parts of the scene. To address this goal, we develop new methods for online visibility culling and offline visibility preprocessing. The online visibility culling is either used to render only visible part of the scene or to provide queries which determine visible parts of the scene in runtime. Visibility preprocessing provides partitioning of the view space into view cells, and for each view cell it calculates a potentially visible set.

1.1 Module Class Hierarchy

The visibility workpackage consists of a module which is integrated into the game engine and an external module which deals with preprocessing. One of the goals of the design of the module class hierarchy has been easy portability of the developed methods to other game engines. The resulting class structure clearly separates the actual engine-dependent parts from the game engine independent algorithmic parts. We have used name spaces to separate the engine dependent parts (name space Ogre) from the engine independent parts (name space GtpVisibility). The external visibility preprocessing module defines its own name space (GtpVisibilityPreprocessor).

An overview of the important classes of the visibility work package and their integration into the Ogre engine is depicted in Figure 1.1.

The diagram shows that the module integrated into the engine consists of three main parts (CullingManager, QueryManager, PreprocessingManager), which are encapsulated in a helper class (Visibility Manager). The helper class then deals with the initialization of the contained parts and allows easy communication between them.

1.2 Visibility Culling

Visibility culling seamlessly integrates into the rendering loop and eliminates most invisible objects from being sent to the pipeline. Visibility culling is implemented by instances of the CullingManager class. We will provide several implementations which can be easily switched at runtime and so the best technique for the particular scene and scene representation can be selected. Note that the Ogre integration design allows to exploit all already existing methods for scene management, such as octree, BSP tree, or plain scene graph.

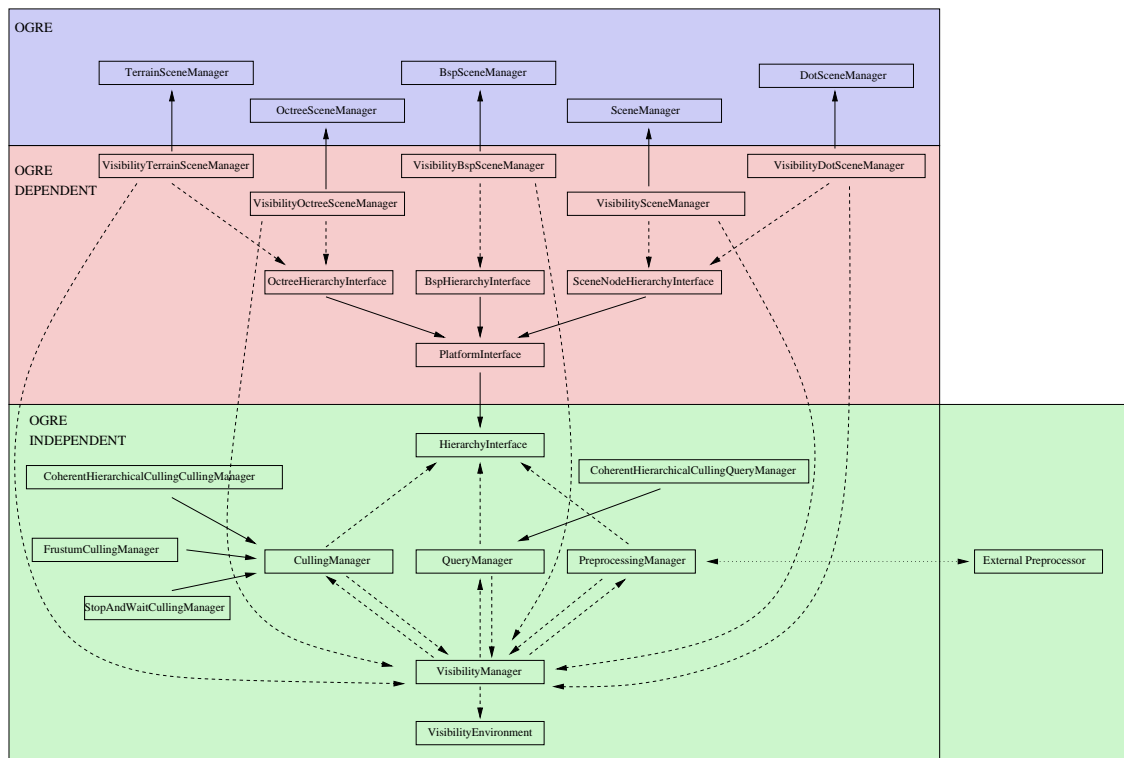


Figure 1.1: Overview of the visibility work packages classes and their integration into the Ogre game engine.

1.3 Visibility Queries

Visibility queries determine the visible geometry for a given view point in the scene. Additionally they can also report the visible scene hierarchy nodes. Visibility queries are implemented by instances of the QueryManager class. Note that some of these instances will make use of the preprocessed visibility data through the use of PreprocessingManager.

1.4 Visibility Preprocessing

Visibility preprocessing precalculates visibility for all viewpoints corresponding to cells of a view space partitioning. The visibility preprocessor is implemented as a standalone module which imports files generated by the PreprocessingManager. The results of the visibility computation will be exported to the file which can then be loaded by the PreprocessingManager and used inside the engine.

Apart from the scene definition file, the preprocessor will be able to import the view cell definition. In this case it will assume the view cells have to be described as meshes satisfying a set of requirements. Alternatively, the module can generate view cells by automatic view space partitioning.

Chapter 2

GameTools Visibility Modules Hierarchical Index

2.1 GameTools Visibility Modules Class Hierarchy

This inheritance list is sorted roughly, but not completely, alphabetically:

GtpVisibilityPreprocessor::AxisAlignedBox3	85
GtpVisibilityPreprocessor::BSPNode	90
GtpVisibilityPreprocessor::BSPInterior	86
GtpVisibilityPreprocessor::BSPLeaf	88
GtpVisibilityPreprocessor::BSPTree	92
GtpVisibility::CullingManager	47
GtpVisibility::CoherentHierarchicalCullingManager	44
GtpVisibility::FrustumCullingManager	56
GtpVisibility::StopAndWaitCullingManager	79
GtpVisibility::GreaterDistance< T >	59
GtpVisibility::HierarchyInterface	61
Ogre::PlatformHierarchyInterface	14
Ogre::BspHierarchyInterface	5
Ogre::OctreeHierarchyInterface	9
Ogre::SceneNodeHierarchyInterface	23
GtpVisibilityPreprocessor::KdNode	101
GtpVisibilityPreprocessor::KdInterior	97
GtpVisibilityPreprocessor::KdLeaf	99
GtpVisibilityPreprocessor::KdTree	103
GtpVisibilityPreprocessor::Mesh	105
GtpVisibility::MeshInfo	67
GtpVisibility::NodeInfo	68
GtpVisibility::OcclusionQuery	69
Ogre::PlatformOcclusionQuery	20
GtpVisibilityPreprocessor::Patch	107
GtpVisibilityPreprocessor::Plane3	108
GtpVisibility::PreprocessingManager	71
GtpVisibility::DummyPreprocessingManager	50
GtpVisibilityPreprocessor::Preprocessor	109

GtpVisibilityPreprocessor::ExactPreprocessor	94
GtpVisibilityPreprocessor::SamplingPreprocessor	113
GtpVisibility::QueryManager	76
GtpVisibility::DummyQueryManager	53
GtpVisibilityPreprocessor::SceneGraph	116
GtpVisibilityPreprocessor::SceneGraphNode	117
Ogre::SolidHalfBoundingBox	27
GtpVisibilityPreprocessor::Vector3	118
Ogre::VisibilityBspSceneManager	29
Ogre::VisibilityDotSceneManager	32
GtpVisibility::VisibilityEnvironment	82
GtpVisibility::VisibilityManager	83
Ogre::VisibilityOctreeSceneManager	35
Ogre::VisibilitySceneManager	38
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Chapter 3

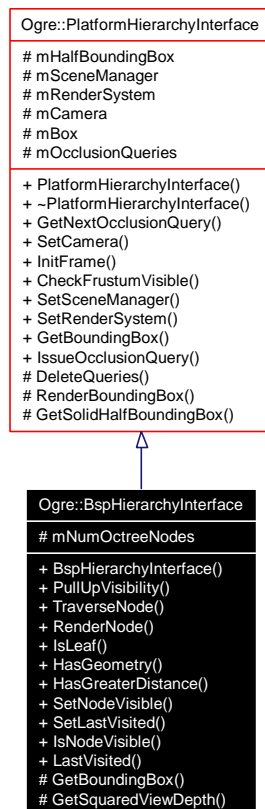
GameTools Visibility Modules Class Documentation

3.1 Ogre::BspHierarchyInterface Class Reference

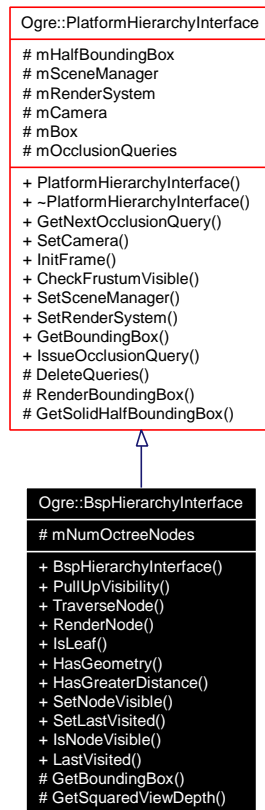
```
#include <Ogre/include/OgreBspHierarchyInterface.h>
```

Inherits [Ogre::PlatformHierarchyInterface](#).

Inheritance diagram for `Ogre::BspHierarchyInterface`:



Collaboration diagram for Ogre::BspHierarchyInterface:



Public Member Functions

- [BspHierarchyInterface](#) (SceneManager *sm, RenderSystem *rsys)
- void [PullUpVisibility](#) (GtpVisibility::HierarchyNode *node)
- void [TraverseNode](#) (GtpVisibility::HierarchyNode *node)
- void [RenderNode](#) (GtpVisibility::HierarchyNode *node)
- bool [IsLeaf](#) (GtpVisibility::HierarchyNode *node)
- bool [HasGeometry](#) (GtpVisibility::HierarchyNode *node)
- bool [HasGreaterDistance](#) (GtpVisibility::HierarchyNode *node1, GtpVisibility::HierarchyNode *node2)
- void [SetNodeVisible](#) (GtpVisibility::HierarchyNode *node, const bool visible)
- void [SetLastVisited](#) (GtpVisibility::HierarchyNode *node, const int frameId)
- bool [IsNodeVisible](#) (GtpVisibility::HierarchyNode *node)
- int [LastVisited](#) (GtpVisibility::HierarchyNode *node)

Protected Member Functions

- AxisAlignedBox * [GetBoundingBox](#) (GtpVisibility::HierarchyNode *node)
- Real [GetSquaredViewDepth](#) (const Camera *cam, const AxisAlignedBox *box) const

Protected Attributes

- unsigned int [mNumOctreeNode](#)s

3.1.1 Detailed Description

This class implements the hierarchy interface for the [Ogre](#) bsp hierarchy.

3.1.2 Constructor & Destructor Documentation

3.1.2.1 [Ogre::BspHierarchyInterface::BspHierarchyInterface](#) ([SceneManager](#) * *sm*, [RenderSystem](#) * *rsys*)

3.1.3 Member Function Documentation

3.1.3.1 [void](#) [Ogre::BspHierarchyInterface::PullUpVisibility](#) ([GtpVisibility::HierarchyNode](#) * *node*)

Gets the given option for the scene traverser.

Remarks:

See [setOption](#)

3.1.3.2 [void](#) [Ogre::BspHierarchyInterface::TraverseNode](#) ([GtpVisibility::HierarchyNode](#) * *node*)

Traverses given node.

Parameters:

node current node

Remarks:

pushes children on distance queue

- 3.1.3.3 void `Ogre::BspHierarchyInterface::RenderNode` (`GtpVisibility::HierarchyNode * node`)
- 3.1.3.4 bool `Ogre::BspHierarchyInterface::IsLeaf` (`GtpVisibility::HierarchyNode * node`)
- 3.1.3.5 bool `Ogre::BspHierarchyInterface::HasGeometry` (`GtpVisibility::HierarchyNode * node`)
- 3.1.3.6 bool `Ogre::BspHierarchyInterface::HasGreaterDistance` (`GtpVisibility::HierarchyNode * node1`, `GtpVisibility::HierarchyNode * node2`)
- 3.1.3.7 void `Ogre::BspHierarchyInterface::SetNodeVisible` (`GtpVisibility::HierarchyNode * node`, const bool *visible*)
- 3.1.3.8 void `Ogre::BspHierarchyInterface::SetLastVisited` (`GtpVisibility::HierarchyNode * node`, const int *frameId*)
- 3.1.3.9 bool `Ogre::BspHierarchyInterface::IsNodeVisible` (`GtpVisibility::HierarchyNode * node`)
- 3.1.3.10 int `Ogre::BspHierarchyInterface::LastVisited` (`GtpVisibility::HierarchyNode * node`)
- 3.1.3.11 `AxisAlignedBox * Ogre::BspHierarchyInterface::GetBoundingBox` (`GtpVisibility::HierarchyNode * node`) [protected, virtual]

Returns pointer to the bounding box of the node.

Parameters:

node current hierarchy node

Returns:

bounding box of current node

Implements [Ogre::PlatformHierarchyInterface](#).

- 3.1.3.12 Real `Ogre::BspHierarchyInterface::GetSquaredViewDepth` (const `Camera * cam`, const `AxisAlignedBox * box`) const [protected]

Returns squared distance of center of box with respect to the camera .

Parameters:

cam current camera

box axis aligned box

3.1.4 Member Data Documentation

- 3.1.4.1 unsigned int `Ogre::BspHierarchyInterface::mNumOctreeNode`s [protected]

The documentation for this class was generated from the following files:

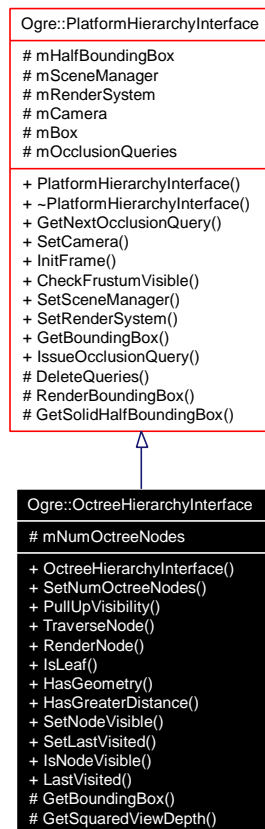
- [OgreBspHierarchyInterface.h](#)
- [OgreBspHierarchyInterface.cpp](#)

3.2 Ogre::OctreeHierarchyInterface Class Reference

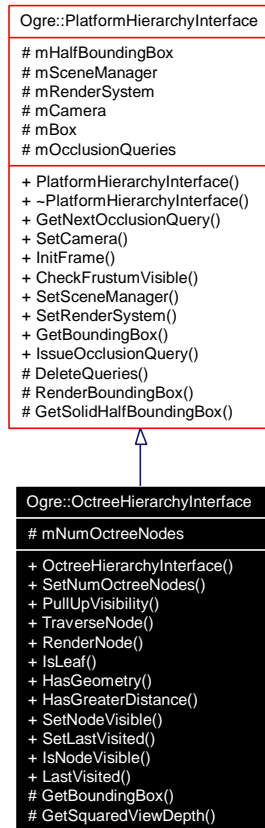
```
#include <Ogre/include/OgreOctreeHierarchyInterface.h>
```

Inherits [Ogre::PlatformHierarchyInterface](#).

Inheritance diagram for `Ogre::OctreeHierarchyInterface`:



Collaboration diagram for `Ogre::OctreeHierarchyInterface`:



Public Member Functions

- [OctreeHierarchyInterface](#) (SceneManager *sm, RenderSystem *rsys)
- void [SetNumOctreeNodes](#) (unsigned int num)
- void [PullUpVisibility](#) (GtpVisibility::HierarchyNode *node)
- void [TraverseNode](#) (GtpVisibility::HierarchyNode *node)
- void [RenderNode](#) (GtpVisibility::HierarchyNode *node)
- bool [IsLeaf](#) (GtpVisibility::HierarchyNode *node)
- bool [HasGeometry](#) (GtpVisibility::HierarchyNode *node)
- bool [HasGreaterDistance](#) (GtpVisibility::HierarchyNode *node1, GtpVisibility::HierarchyNode *node2)
- void [SetNodeVisible](#) (GtpVisibility::HierarchyNode *node, const bool visible)
- void [SetLastVisited](#) (GtpVisibility::HierarchyNode *node, const int frameId)
- bool [IsNodeVisible](#) (GtpVisibility::HierarchyNode *node)
- int [LastVisited](#) (GtpVisibility::HierarchyNode *node)

Protected Member Functions

- [AxisAlignedBox](#) * [GetBoundingBox](#) (GtpVisibility::HierarchyNode *node)
- Real [GetSquaredViewDepth](#) (const [Camera](#) *cam, const [AxisAlignedBox](#) *box) const

Protected Attributes

- unsigned int [mNumOctreeNodes](#)

3.2.1 Detailed Description

This class implements the hierarchy interface for the [Ogre](#) octree hierarchy.

3.2.2 Constructor & Destructor Documentation

3.2.2.1 `Ogre::OctreeHierarchyInterface::OctreeHierarchyInterface (SceneManager * sm, RenderSystem * rsys)`

3.2.3 Member Function Documentation

3.2.3.1 `void Ogre::OctreeHierarchyInterface::SetNumOctreeNode (unsigned int num)`

Sets the number of nodes in this octree

Remarks:

do not confuse this with the OctreeNode class which is derived from SceneNode

Parameters:

num number of nodes in the octree

3.2.3.2 `void Ogre::OctreeHierarchyInterface::PullUpVisibility (GtpVisibility::HierarchyNode * node)`

Gets the given option for the scene traverser.

Remarks:

See setOption

3.2.3.3 `void Ogre::OctreeHierarchyInterface::TraverseNode (GtpVisibility::HierarchyNode * node)`

Traverses given node.

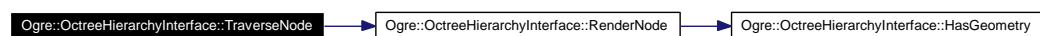
Parameters:

node current node

Remarks:

pushes children on distance queue

Here is the call graph for this function:



3.2.3.4 void Ogre::OctreeHierarchyInterface::RenderNode ([GtpVisibility::HierarchyNode](#) * *node*)

Here is the call graph for this function:



3.2.3.5 bool Ogre::OctreeHierarchyInterface::IsLeaf ([GtpVisibility::HierarchyNode](#) * *node*)

3.2.3.6 bool Ogre::OctreeHierarchyInterface::HasGeometry ([GtpVisibility::HierarchyNode](#) * *node*)

3.2.3.7 bool Ogre::OctreeHierarchyInterface::HasGreaterDistance ([GtpVisibility::HierarchyNode](#) * *node1*, [GtpVisibility::HierarchyNode](#) * *node2*)

Here is the call graph for this function:



3.2.3.8 void Ogre::OctreeHierarchyInterface::SetNodeVisible ([GtpVisibility::HierarchyNode](#) * *node*, const bool *visible*)

3.2.3.9 void Ogre::OctreeHierarchyInterface::SetLastVisited ([GtpVisibility::HierarchyNode](#) * *node*, const int *frameId*)

3.2.3.10 bool Ogre::OctreeHierarchyInterface::IsNodeVisible ([GtpVisibility::HierarchyNode](#) * *node*)

3.2.3.11 int Ogre::OctreeHierarchyInterface::LastVisited ([GtpVisibility::HierarchyNode](#) * *node*)

3.2.3.12 [AxisAlignedBox](#) * [Ogre::OctreeHierarchyInterface::GetBoundingBox](#) ([GtpVisibility::HierarchyNode](#) * *node*) [protected, virtual]

Returns pointer to the bounding box of the node.

Parameters:

node current hierarchy node

Returns:

bounding box of current node

Implements [Ogre::PlatformHierarchyInterface](#).

3.2.3.13 Real [Ogre::OctreeHierarchyInterface::GetSquaredViewDepth](#) (const [Camera](#) * *cam*, const [AxisAlignedBox](#) * *box*) const [protected]

Returns squared distance of center of box with respect to the camera .

Parameters:

cam current camera

box axis aligned box

3.2.4 Member Data Documentation**3.2.4.1 unsigned int [Ogre::OctreeHierarchyInterface::mNumOctreeNodes](#) [protected]**

The documentation for this class was generated from the following files:

- [OgreOctreeHierarchyInterface.h](#)
- [OgreOctreeHierarchyInterface.cpp](#)

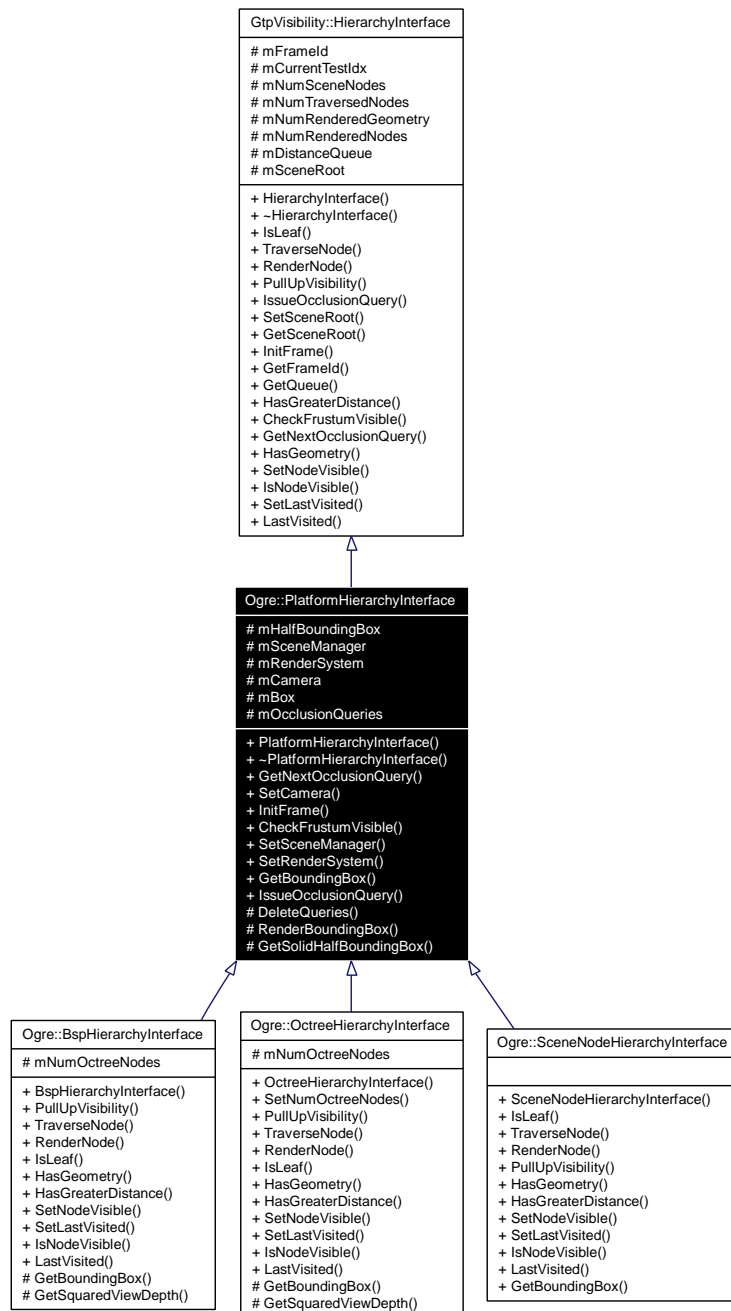
3.3 Ogre::PlatformHierarchyInterface Class Reference

#include <Ogre/include/OgrePlatformHierarchyInterface.h>

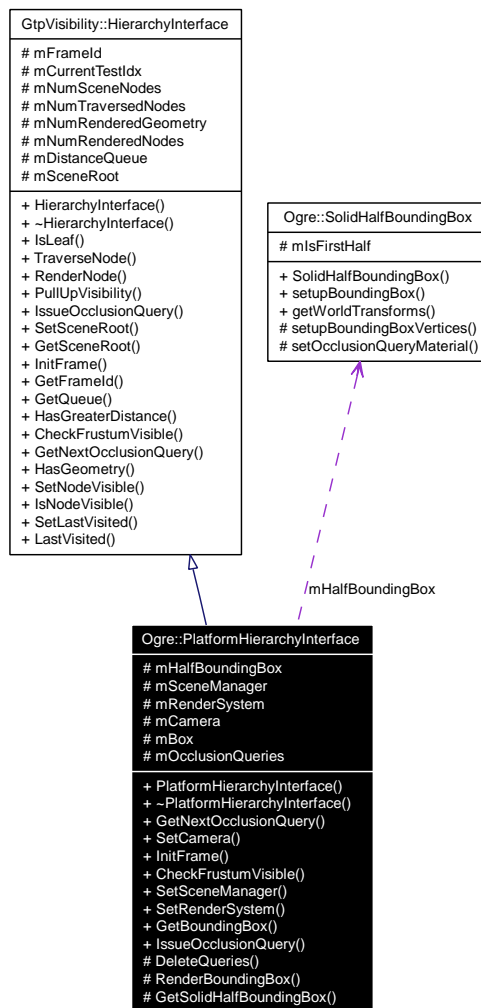
Inherits [GtpVisibility::HierarchyInterface](#).

Inherited by [Ogre::BspHierarchyInterface](#), [Ogre::OctreeHierarchyInterface](#), and [Ogre::SceneNodeHierarchyInterface](#).

Inheritance diagram for [Ogre::PlatformHierarchyInterface](#):



Collaboration diagram for Ogre::PlatformHierarchyInterface:



Public Member Functions

- [PlatformHierarchyInterface](#) (SceneManager *sm, RenderSystem *rsys)
- [~PlatformHierarchyInterface](#) ()
- [GtpVisibility::OcclusionQuery * GetNextOcclusionQuery](#) ()
- void [SetCamera](#) (Camera *cam)
- void [InitFrame](#) (GtpVisibility::HierarchyNode *root, Ogre::Camera *cam)
- bool [CheckFrustumVisible](#) (GtpVisibility::HierarchyNode *node, bool &intersects)
- void [SetSceneManager](#) (SceneManager *sm)
- void [SetRenderSystem](#) (RenderSystem *rsys)
- virtual AxisAlignedBox * [GetBoundingBox](#) (GtpVisibility::HierarchyNode *node)=0
- [GtpVisibility::OcclusionQuery * IssueOcclusionQuery](#) (GtpVisibility::HierarchyNode *node)

Protected Member Functions

- void [DeleteQueries](#) ()

- void [RenderBoundingBox](#) ([AxisAlignedBox](#) *box)
- [SolidHalfBoundingBox](#) * [GetSolidHalfBoundingBox](#) (int half)

Protected Attributes

- [SolidHalfBoundingBox](#) * [mHalfBoundingBox](#) [2]
- [SceneManager](#) * [mSceneManager](#)
- [RenderSystem](#) * [mRenderSystem](#)
- [Camera](#) * [mCamera](#)
- [AxisAlignedBox](#) [mBox](#)
- std::vector< [PlatformOcclusionQuery](#) * > [mOcclusionQueries](#)

3.3.1 Detailed Description

Class which implements a hierarchy interface for a specific type of hierarchy.

Remarks:

also provides methods for using occlusion queries on the hierarchy nodes

3.3.2 Constructor & Destructor Documentation

3.3.2.1 [Ogre::PlatformHierarchyInterface::PlatformHierarchyInterface](#) ([SceneManager](#) * *sm*, [RenderSystem](#) * *rsys*)

Construction taking the current scene manager and the current rendersystem as argument

Parameters:

sm current scene manager
rsys current render system

3.3.2.2 [Ogre::PlatformHierarchyInterface::~~PlatformHierarchyInterface](#) ()

Here is the call graph for this function:



3.3.3 Member Function Documentation

3.3.3.1 [GtpVisibility::OcclusionQuery](#) * [Ogre::PlatformHierarchyInterface::GetNextOcclusionQuery](#) () [virtual]

Returns next available occlusion query or creates new one.

Returns:

the next occlusion query

Implements [GtpVisibility::HierarchyInterface](#).

3.3.3.2 void Ogre::PlatformHierarchyInterface::SetCamera ([Camera](#) * *cam*)

Sets the current camera.

Parameters:

cam the current camera

3.3.3.3 void Ogre::PlatformHierarchyInterface::InitFrame ([GtpVisibility::HierarchyNode](#) * *root*, [Ogre::Camera](#) * *cam*)

Initialises this scene traverser for the current frame.

Parameters:

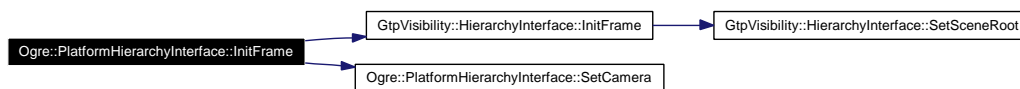
root root of the hierarchy

cam current camera

Remarks:

convenience method wich calls `VisibilitySceneTraverser::initFrame`, sets the current camera, and initialises the distance queue.

Here is the call graph for this function:



3.3.3.4 bool Ogre::PlatformHierarchyInterface::CheckFrustumVisible ([GtpVisibility::HierarchyNode](#) * *node*, bool & *intersects*)

Checks if the node is visible from the current view frustum.

Parameters:

node the current node

intersects returns true if the current node intersects the near plane

Here is the call graph for this function:



3.3.3.5 void Ogre::PlatformHierarchyInterface::SetSceneManager ([SceneManager](#) * *sm*)

Sets pointer to the current scene manager.

Parameters:

sm the scene manager

3.3.3.6 void `Ogre::PlatformHierarchyInterface::SetRenderSystem (RenderSystem * rsys)`

Sets pointer to the current render system

Parameters:

rsys the rendersystem

3.3.3.7 virtual `AxisAlignedBox* Ogre::PlatformHierarchyInterface::GetBoundingBox (GtpVisibility::HierarchyNode * node)` [pure virtual]

Returns pointer to bounding box of node.

Parameters:

node current hierarchy node

Returns:

bounding box of current node

Implemented in [Ogre::BspHierarchyInterface](#), [Ogre::OctreeHierarchyInterface](#), and [Ogre::SceneNodeHierarchyInterface](#).

3.3.3.8 `GtpVisibility::OcclusionQuery * Ogre::PlatformHierarchyInterface::IssueOcclusionQuery (GtpVisibility::HierarchyNode * node)`

Issue a occlusion query for this node.

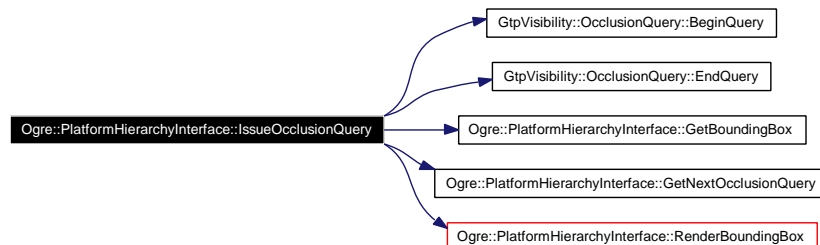
Parameters:

node the current hierarchy node

Returns:

occlusion query for this node

Here is the call graph for this function:



3.3.3.9 void `Ogre::PlatformHierarchyInterface::DeleteQueries ()` [protected]

Deletes all occlusion queries.

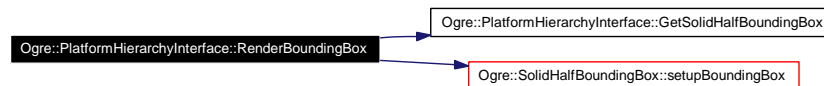
3.3.3.10 void Ogre::PlatformHierarchyInterface::RenderBoundingBox ([AxisAlignedBox](#) * *box*) [protected]

Renders bounding box of specified node.

Parameters:

box the bounding box of the scene node to be rendered

Here is the call graph for this function:



3.3.3.11 [SolidHalfBoundingBox](#) * [Ogre::PlatformHierarchyInterface::GetSolidHalfBoundingBox](#) (*int half*) [protected]

Returns one half of the bounding box.

Parameters:

half the half index of the bounding box (0 or 1)

3.3.4 Member Data Documentation

3.3.4.1 [SolidHalfBoundingBox](#)* [Ogre::PlatformHierarchyInterface::mHalfBoundingBox](#)[2] [protected]

two halves of an aabb.

3.3.4.2 [SceneManager](#)* [Ogre::PlatformHierarchyInterface::mSceneManager](#) [protected]

3.3.4.3 [RenderSystem](#)* [Ogre::PlatformHierarchyInterface::mRenderSystem](#) [protected]

3.3.4.4 [Camera](#)* [Ogre::PlatformHierarchyInterface::mCamera](#) [protected]

3.3.4.5 [AxisAlignedBox](#) [Ogre::PlatformHierarchyInterface::mBox](#) [protected]

3.3.4.6 `std::vector<PlatformOcclusionQuery *>` [Ogre::PlatformHierarchyInterface::mOcclusionQueries](#) [protected]

The documentation for this class was generated from the following files:

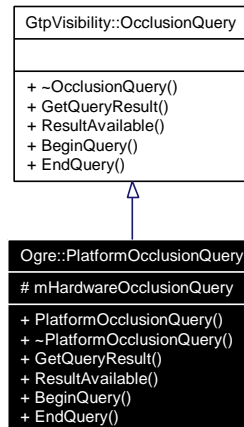
- [OgrePlatformHierarchyInterface.h](#)
- [OgrePlatformHierarchyInterface.cpp](#)

3.4 Ogre::PlatformOcclusionQuery Class Reference

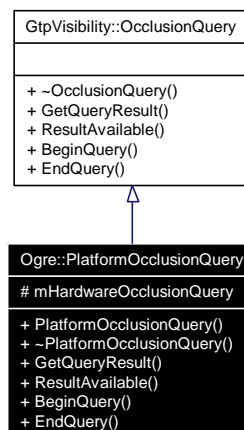
```
#include <Ogre/include/OgrePlatformOcclusionQuery.h>
```

Inherits [GtpVisibility::OcclusionQuery](#).

Inheritance diagram for `Ogre::PlatformOcclusionQuery`:



Collaboration diagram for `Ogre::PlatformOcclusionQuery`:



Public Member Functions

- `PlatformOcclusionQuery` (`RenderSystem *rsys`)
- virtual `~PlatformOcclusionQuery` ()
- virtual unsigned int `GetQueryResult` () const
- virtual bool `ResultAvailable` () const
- virtual void `BeginQuery` () const
- virtual void `EndQuery` () const

Protected Attributes

- `HardwareOcclusionQuery * mHardwareOcclusionQuery`

3.4.1 Detailed Description

This class is an implementation for occlusion queries using [Ogre](#).

Remarks:

the class encapsulates [Ogre](#) occlusion query calls.

3.4.2 Constructor & Destructor Documentation

3.4.2.1 `Ogre::PlatformOcclusionQuery::PlatformOcclusionQuery (RenderSystem * rsys)`

3.4.2.2 `Ogre::PlatformOcclusionQuery::~~PlatformOcclusionQuery () [virtual]`

3.4.3 Member Function Documentation

3.4.3.1 `unsigned int Ogre::PlatformOcclusionQuery::GetQueryResult () const [virtual]`

Returns the result of an occlusion query in terms of visible pixels.

Returns:

number of visible pixels

Implements [GtpVisibility::OcclusionQuery](#).

3.4.3.2 `bool Ogre::PlatformOcclusionQuery::ResultAvailable () const [virtual]`

Returns true if the result of the query is available, false otherwise.

Returns:

if result is available

Implements [GtpVisibility::OcclusionQuery](#).

3.4.3.3 `void Ogre::PlatformOcclusionQuery::BeginQuery () const [virtual]`

Begins occlusion query.

Remarks:

the query counts the number of visible pixels between it's begin and end

Implements [GtpVisibility::OcclusionQuery](#).

3.4.3.4 `void Ogre::PlatformOcclusionQuery::EndQuery () const [virtual]`

Ends occlusion query.

Implements [GtpVisibility::OcclusionQuery](#).

3.4.4 Member Data Documentation

3.4.4.1 HardwareOcclusionQuery* [Ogre::PlatformOcclusionQuery::mHardwareOcclusionQuery](#) [protected]

The documentation for this class was generated from the following files:

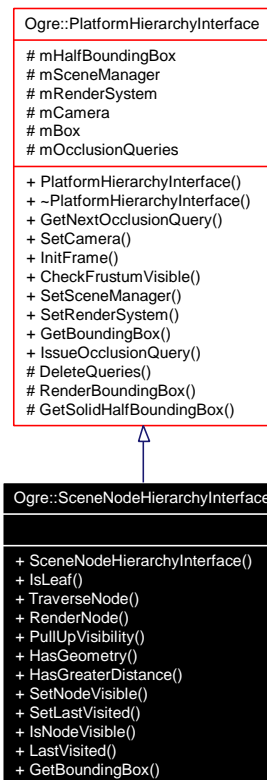
- [OgrePlatformOcclusionQuery.h](#)
- [OgrePlatformOcclusionQuery.cpp](#)

3.5 Ogre::SceneNodeHierarchyInterface Class Reference

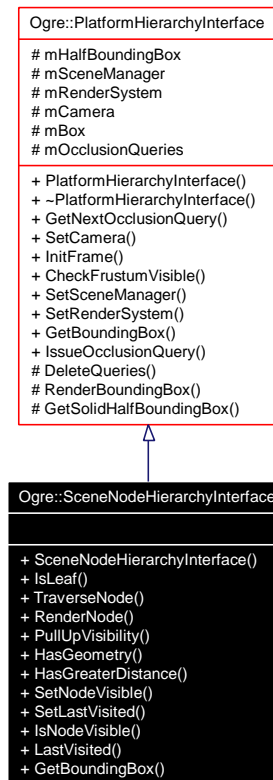
```
#include <Ogre/include/OgreSceneNodeHierarchyInterface.h>
```

Inherits [Ogre::PlatformHierarchyInterface](#).

Inheritance diagram for Ogre::SceneNodeHierarchyInterface:



Collaboration diagram for Ogre::SceneNodeHierarchyInterface:



Public Member Functions

- [SceneNodeHierarchyInterface](#) (SceneManager *sm, RenderSystem *rsys)
- bool [IsLeaf](#) (GtpVisibility::HierarchyNode *node)
- void [TraverseNode](#) (GtpVisibility::HierarchyNode *node)
- void [RenderNode](#) (GtpVisibility::HierarchyNode *node)
- void [PullUpVisibility](#) (GtpVisibility::HierarchyNode *node)
- bool [HasGeometry](#) (GtpVisibility::HierarchyNode *node)
- bool [HasGreaterDistance](#) (GtpVisibility::HierarchyNode *node1, GtpVisibility::HierarchyNode *node2)
- void [SetNodeVisible](#) (GtpVisibility::HierarchyNode *node, const bool visible)
- void [SetLastVisited](#) (GtpVisibility::HierarchyNode *node, const int frameId)
- bool [IsNodeVisible](#) (GtpVisibility::HierarchyNode *node)
- int [LastVisited](#) (GtpVisibility::HierarchyNode *node)
- AxisAlignedBox * [GetBoundingBox](#) (GtpVisibility::HierarchyNode *node)

3.5.1 Detailed Description

This class implements the hierarchy interface for the [Ogre](#) scene node hierarchy.

3.5.2 Constructor & Destructor Documentation

3.5.2.1 Ogre::SceneNodeHierarchyInterface::SceneNodeHierarchyInterface (SceneManager * *sm*, RenderSystem * *rsys*)

Construction taking the current scene manager and the current rendersystem as argument

Parameters:

sm current scene manager

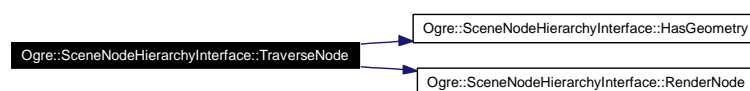
rsys current render system

3.5.3 Member Function Documentation

3.5.3.1 bool Ogre::SceneNodeHierarchyInterface::IsLeaf (GtpVisibility::HierarchyNode * *node*)

3.5.3.2 void Ogre::SceneNodeHierarchyInterface::TraverseNode (GtpVisibility::HierarchyNode * *node*)

Here is the call graph for this function:



- 3.5.3.3 `void Ogre::SceneNodeHierarchyInterface::RenderNode (GtpVisibility::HierarchyNode * node)`
- 3.5.3.4 `void Ogre::SceneNodeHierarchyInterface::PullUpVisibility (GtpVisibility::HierarchyNode * node)`
- 3.5.3.5 `bool Ogre::SceneNodeHierarchyInterface::HasGeometry (GtpVisibility::HierarchyNode * node)`
- 3.5.3.6 `bool Ogre::SceneNodeHierarchyInterface::HasGreaterDistance (GtpVisibility::HierarchyNode * node1, GtpVisibility::HierarchyNode * node2)`
- 3.5.3.7 `void Ogre::SceneNodeHierarchyInterface::SetNodeVisible (GtpVisibility::HierarchyNode * node, const bool visible)`
- 3.5.3.8 `void Ogre::SceneNodeHierarchyInterface::SetLastVisited (GtpVisibility::HierarchyNode * node, const int frameId)`
- 3.5.3.9 `bool Ogre::SceneNodeHierarchyInterface::IsNodeVisible (GtpVisibility::HierarchyNode * node)`
- 3.5.3.10 `int Ogre::SceneNodeHierarchyInterface::LastVisited (GtpVisibility::HierarchyNode * node)`
- 3.5.3.11 `AxisAlignedBox * Ogre::SceneNodeHierarchyInterface::GetBoundingBox (GtpVisibility::HierarchyNode * node) [virtual]`

Returns pointer to bounding box of node.

Parameters:

node current hierarchy node

Returns:

bounding box of current node

Implements [Ogre::PlatformHierarchyInterface](#).

The documentation for this class was generated from the following files:

- [OgreSceneNodeHierarchyInterface.h](#)
- [OgreSceneNodeHierarchyInterface.cpp](#)

3.6 Ogre::SolidHalfBoundingBox Class Reference

```
#include <Ogre/include/OgreSolidHalfBoundingBox.h>
```

Public Member Functions

- [SolidHalfBoundingBox](#) (bool isFirstHalf)
- void [setupBoundingBox](#) (const [AxisAlignedBox](#) &aabb)
- void [getWorldTransforms](#) (Matrix4 *xform) const

Protected Member Functions

- void [setupBoundingBoxVertices](#) (const [AxisAlignedBox](#) &aab)
- void [setOcclusionQueryMaterial](#) ()

Protected Attributes

- bool [mIsFirstHalf](#)

3.6.1 Detailed Description

Allows the rendering of one half of a solid bounding box.

Remarks:

This class builds a wireframe renderable from a given aabb. A pointer to this class can be added to a render queue to display the bounding box of an object.

3.6.2 Constructor & Destructor Documentation

3.6.2.1 Ogre::SolidHalfBoundingBox::SolidHalfBoundingBox (bool isFirstHalf)

Here is the call graph for this function:



3.6.3 Member Function Documentation

3.6.3.1 void Ogre::SolidHalfBoundingBox::setupBoundingBox (const [AxisAlignedBox](#) &aabb)

Here is the call graph for this function:



3.6.3.2 void Ogre::SolidHalfBoundingBox::getWorldTransforms (Matrix4 * *xform*) const

Override this method to prevent parent transforms (rotation,translation,scale) and to make it public.

3.6.3.3 void Ogre::SolidHalfBoundingBox::setupBoundingBoxVertices (const AxisAlignedBox & *aab*) [protected]

Builds the wireframe line list.

Parameters:

aab the axis aligned bounding box for setting up the list.

3.6.3.4 void Ogre::SolidHalfBoundingBox::setOcclusionQueryMaterial () [protected]

Sets the material used for occlusion queries.

Remarks:

the material is called "OcclusionQuery" and uses no lighting, no depth write, and no colours

3.6.4 Member Data Documentation**3.6.4.1 bool Ogre::SolidHalfBoundingBox::mIsFirstHalf [protected]**

Whether this half box is the first or the second half of the bounding box.

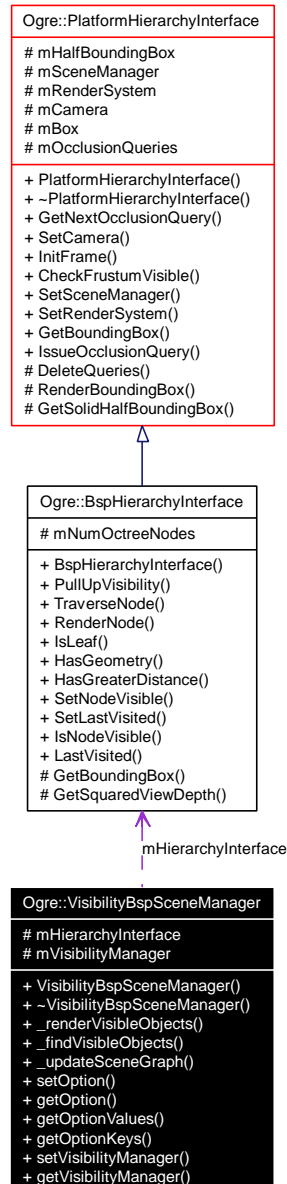
The documentation for this class was generated from the following files:

- [OgreSolidHalfBoundingBox.h](#)
- [OgreSolidHalfBoundingBox.cpp](#)

3.7 Ogre::VisibilityBspSceneManager Class Reference

```
#include <Ogre/include/OgreVisibilityBspSceneManager.h>
```

Collaboration diagram for Ogre::VisibilityBspSceneManager:



Public Member Functions

- [VisibilityBspSceneManager](#) (GtpVisibility::Manager *visManager)
- [~VisibilityBspSceneManager](#) ()
- void [_renderVisibleObjects](#) ()
- void [_findVisibleObjects](#) (Camera *cam, bool onlyShadowCasters)
- void [_updateSceneGraph](#) (Camera *cam)

- virtual bool [setOption](#) (const String &, const void *)
- virtual bool [getOption](#) (const String &, void *)
- bool [getOptionValues](#) (const String &key, StringVector &refValueList)
- bool [getOptionKeys](#) (StringVector &refKeys)
- void [setVisibilityManager](#) (GtpVisibility::Manager *visManager)
- GtpVisibility::Manager * [getVisibilityManager](#) (void)

Protected Attributes

- [BspHierarchyInterface](#) * [mHierarchyInterface](#)
- GtpVisibility::Manager * [mVisibilityManager](#)

3.7.1 Detailed Description

This class extends the octree scene manager, using occlusion queries for visibility culling.

3.7.2 Constructor & Destructor Documentation

3.7.2.1 `Ogre::VisibilityBspSceneManager::VisibilityBspSceneManager (GtpVisibility::Manager * visManager)`

3.7.2.2 `Ogre::VisibilityBspSceneManager::~~VisibilityBspSceneManager ()`

3.7.3 Member Function Documentation

3.7.3.1 `void Ogre::VisibilityBspSceneManager::_renderVisibleObjects ()`

Here is the call graph for this function:



3.7.3.2 `void Ogre::VisibilityBspSceneManager::_findVisibleObjects (Camera * cam, bool onlyShadowCasters)`

3.7.3.3 `void Ogre::VisibilityBspSceneManager::_updateSceneGraph (Camera * cam)`

Here is the call graph for this function:



3.7.3.4 `bool Ogre::VisibilityBspSceneManager::setOption (const String &, const void *) [virtual]`

Sets the given option for the SceneManager

Remarks:

Options are: "Algorithm", int *;

3.7.3.5 `bool Ogre::VisibilityBspSceneManager::getOption (const String &, void *)` [virtual]

Gets the given option for the Scene Manager.

Remarks:

See setOption

3.7.3.6 `bool Ogre::VisibilityBspSceneManager::getOptionValues (const String & key, StringVector & refValueList)`**3.7.3.7** `bool Ogre::VisibilityBspSceneManager::getOptionKeys (StringVector & refKeys)`**3.7.3.8** `void Ogre::VisibilityBspSceneManager::setVisibilityManager (GtpVisibility::Manager * visManager)`

Sets the visibility manager.

Parameters:

visManager the visibility manager

3.7.3.9 `GtpVisibility::Manager * Ogre::VisibilityBspSceneManager::getVisibilityManager (void)`

See set.

3.7.4 Member Data Documentation**3.7.4.1** `BspHierarchyInterface* Ogre::VisibilityBspSceneManager::mHierarchyInterface`
[protected]**3.7.4.2** `GtpVisibility::Manager* Ogre::VisibilityBspSceneManager::mVisibilityManager`
[protected]

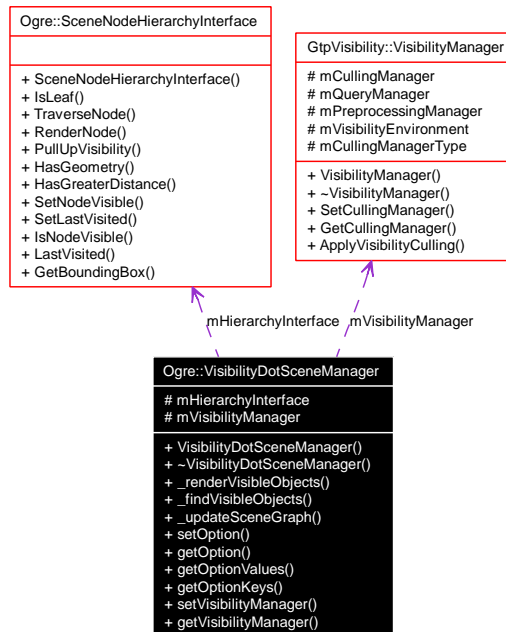
The documentation for this class was generated from the following files:

- [OgreVisibilityBspSceneManager.h](#)
- [OgreVisibilityBspSceneManager.cpp](#)

3.8 Ogre::VisibilityDotSceneManager Class Reference

```
#include <Ogre/include/OgreVisibilityDotSceneManager.h>
```

Collaboration diagram for Ogre::VisibilityDotSceneManager:



Public Member Functions

- [VisibilityDotSceneManager](#) ([GtpVisibility::VisibilityManager](#) *visManager)
- [~VisibilityDotSceneManager](#) ()
- void [_renderVisibleObjects](#) ()
- void [_findVisibleObjects](#) ([Camera](#) *cam, bool onlyShadowCasters)
- void [_updateSceneGraph](#) ([Camera](#) *cam)
- virtual bool [setOption](#) (const String &, const void *)
- virtual bool [getOption](#) (const String &, void *)
- bool [getOptionValues](#) (const String &key, StringVector &refValueList)
- bool [getOptionKeys](#) (StringVector &refKeys)
- void [setVisibilityManager](#) ([GtpVisibility::VisibilityManager](#) *visManager)
- [GtpVisibility::VisibilityManager](#) * [getVisibilityManager](#) ()

Protected Attributes

- [Ogre::SceneNodeHierarchyInterface](#) * mHierarchyInterface
- [GtpVisibility::VisibilityManager](#) * mVisibilityManager

3.8.1 Detailed Description

This class extends the dot scene manager, using occlusion queries for visibility culling.

Remarks:

the scene manager can operate on [Ogre](#) scene descriptions in XML defined by the ".scene" format

3.8.2 Constructor & Destructor Documentation

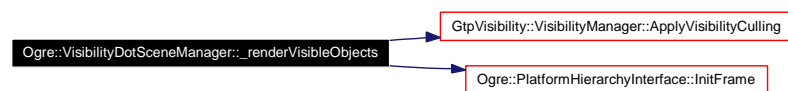
3.8.2.1 `Ogre::VisibilityDotSceneManager::VisibilityDotSceneManager`
([GtpVisibility::VisibilityManager](#) * *visManager*)

3.8.2.2 `Ogre::VisibilityDotSceneManager::~~VisibilityDotSceneManager` ()

3.8.3 Member Function Documentation

3.8.3.1 `void Ogre::VisibilityDotSceneManager::_renderVisibleObjects` ()

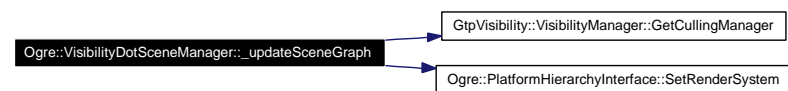
Here is the call graph for this function:



3.8.3.2 `void Ogre::VisibilityDotSceneManager::_findVisibleObjects` ([Camera](#) * *cam*, `bool` *onlyShadowCasters*)

3.8.3.3 `void Ogre::VisibilityDotSceneManager::_updateSceneGraph` ([Camera](#) * *cam*)

Here is the call graph for this function:



3.8.3.4 `bool Ogre::VisibilityDotSceneManager::setOption` (`const String &`, `const void *`)
[virtual]

Sets the given option for the SceneManager

Remarks:

Options are: "Algorithm", int *;

3.8.3.5 `bool Ogre::VisibilityDotSceneManager::getOption` (`const String &`, `void *`) [virtual]

Gets the given option for the Scene VisibilityManager.

Remarks:

See setOption

3.8.3.6 `bool Ogre::VisibilityDotSceneManager::getOptionValues (const String & key, StringVector & refValueList)`

3.8.3.7 `bool Ogre::VisibilityDotSceneManager::getOptionKeys (StringVector & refKeys)`

3.8.3.8 `void Ogre::VisibilityDotSceneManager::setVisibilityManager (GtpVisibility::VisibilityManager * visManager)`

Sets the visibility manager.

Parameters:

visManager the visibility manager

3.8.3.9 `GtpVisibility::VisibilityManager * Ogre::VisibilityDotSceneManager::getVisibilityManager ()`

See set.

3.8.4 Member Data Documentation

3.8.4.1 `Ogre::SceneNodeHierarchyInterface* Ogre::VisibilityDotSceneManager::mHierarchyInterface` [protected]

3.8.4.2 `GtpVisibility::VisibilityManager* Ogre::VisibilityDotSceneManager::mVisibilityManager` [protected]

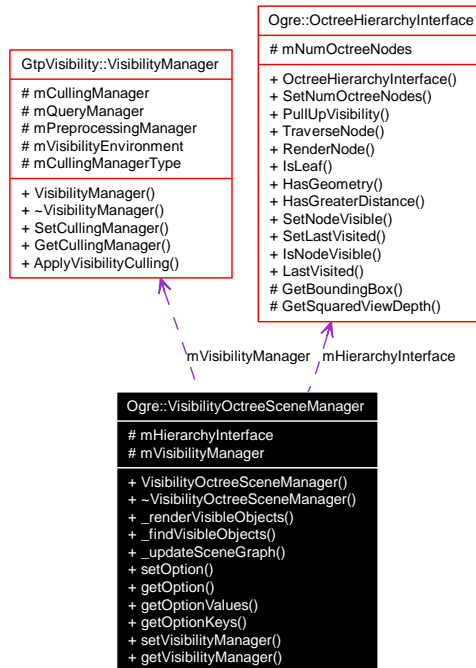
The documentation for this class was generated from the following files:

- [OgreVisibilityDotSceneManager.h](#)
- [OgreVisibilityDotSceneManager.cpp](#)

3.9 Ogre::VisibilityOctreeSceneManager Class Reference

```
#include <Ogre/include/OgreVisibilityOctreeSceneManager.h>
```

Collaboration diagram for Ogre::VisibilityOctreeSceneManager:



Public Member Functions

- [VisibilityOctreeSceneManager](#) ([GtpVisibility::VisibilityManager](#) *visManager)
- [~VisibilityOctreeSceneManager](#) ()
- void [_renderVisibleObjects](#) ()
- void [_findVisibleObjects](#) ([Camera](#) *cam, bool onlyShadowCasters)
- void [_updateSceneGraph](#) ([Camera](#) *cam)
- virtual bool [setOption](#) (const [String](#) &, const void *)
- virtual bool [getOption](#) (const [String](#) &, void *)
- bool [getOptionValues](#) (const [String](#) &key, [StringVector](#) &refValueList)
- bool [getOptionKeys](#) ([StringVector](#) &refKeys)
- void [setVisibilityManager](#) ([GtpVisibility::VisibilityManager](#) *visManager)
- [GtpVisibility::VisibilityManager](#) * [getVisibilityManager](#) (void)

Protected Attributes

- [OctreeHierarchyInterface](#) * mHierarchyInterface
- [GtpVisibility::VisibilityManager](#) * mVisibilityManager

3.9.1 Detailed Description

This class extends the octree scene manager, using occlusion queries for visibility culling.

3.9.2 Constructor & Destructor Documentation

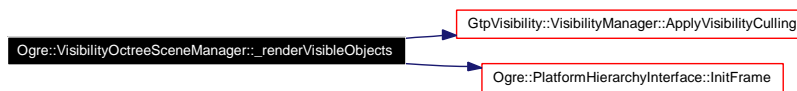
3.9.2.1 **Ogre::VisibilityOctreeSceneManager::VisibilityOctreeSceneManager**
(**GtpVisibility::VisibilityManager** * *visManager*)

3.9.2.2 **Ogre::VisibilityOctreeSceneManager::~VisibilityOctreeSceneManager** ()

3.9.3 Member Function Documentation

3.9.3.1 **void Ogre::VisibilityOctreeSceneManager::_renderVisibleObjects** ()

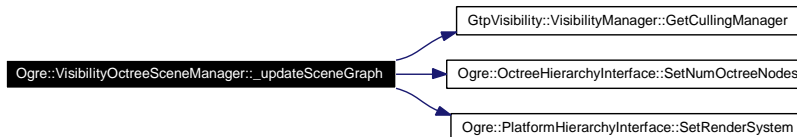
Here is the call graph for this function:



3.9.3.2 **void Ogre::VisibilityOctreeSceneManager::_findVisibleObjects** (**Camera** * *cam*, **bool** *onlyShadowCasters*)

3.9.3.3 **void Ogre::VisibilityOctreeSceneManager::_updateSceneGraph** (**Camera** * *cam*)

Here is the call graph for this function:



3.9.3.4 **bool Ogre::VisibilityOctreeSceneManager::setOption** (**const String &**, **const void ***)
[virtual]

Sets the given option for the SceneManager

Remarks:

Options are: "Algorithm", int *;

3.9.3.5 **bool Ogre::VisibilityOctreeSceneManager::getOption** (**const String &**, **void ***)
[virtual]

Gets the given option for the Scene VisibilityManager.

Remarks:

See setOption

3.9.3.6 `bool Ogre::VisibilityOctreeSceneManager::getOptionValues (const String & key, StringVector & refValueList)`

3.9.3.7 `bool Ogre::VisibilityOctreeSceneManager::getOptionKeys (StringVector & refKeys)`

3.9.3.8 `void Ogre::VisibilityOctreeSceneManager::setVisibilityManager (GtpVisibility::VisibilityManager * visManager)`

Sets the visibility manager.

Parameters:

visManager the visibility manager

3.9.3.9 `GtpVisibility::VisibilityManager * Ogre::VisibilityOctreeSceneManager::getVisibilityManager (void)`

See set.

3.9.4 Member Data Documentation

3.9.4.1 `OctreeHierarchyInterface* Ogre::VisibilityOctreeSceneManager::mHierarchyInterface` [protected]

3.9.4.2 `GtpVisibility::VisibilityManager* Ogre::VisibilityOctreeSceneManager::mVisibilityManager` [protected]

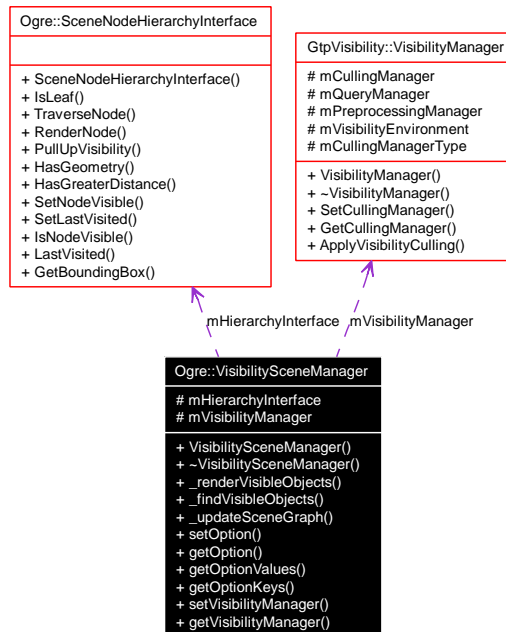
The documentation for this class was generated from the following files:

- [OgreVisibilityOctreeSceneManager.h](#)
- [OgreVisibilityOctreeSceneManager.cpp](#)

3.10 Ogre::VisibilitySceneManager Class Reference

```
#include <Ogre/include/OgreVisibilitySceneManager.h>
```

Collaboration diagram for Ogre::VisibilitySceneManager:



Public Member Functions

- [VisibilitySceneManager](#) ([GtpVisibility::VisibilityManager](#) *visManager)
- [~VisibilitySceneManager](#) ()
- void [_renderVisibleObjects](#) ()
- void [_findVisibleObjects](#) ([Camera](#) *cam, bool onlyShadowCasters)
- void [_updateSceneGraph](#) ([Camera](#) *cam)
- virtual bool [setOption](#) (const String &, const void *)
- virtual bool [getOption](#) (const String &, void *)
- bool [getOptionValues](#) (const String &key, StringVector &refValueList)
- bool [getOptionKeys](#) (StringVector &refKeys)
- void [setVisibilityManager](#) ([GtpVisibility::VisibilityManager](#) *visManager)
- [GtpVisibility::VisibilityManager](#) * [getVisibilityManager](#) ()

Protected Attributes

- [SceneNodeHierarchyInterface](#) * mHierarchyInterface
- [GtpVisibility::VisibilityManager](#) * mVisibilityManager

3.10.1 Detailed Description

This class implements the default scene manager, using occlusion queries for visibility culling.

3.10.2 Constructor & Destructor Documentation

3.10.2.1 `Ogre::VisibilitySceneManager::VisibilitySceneManager (GtpVisibility::VisibilityManager * visManager)`

3.10.2.2 `Ogre::VisibilitySceneManager::~~VisibilitySceneManager ()`

3.10.3 Member Function Documentation

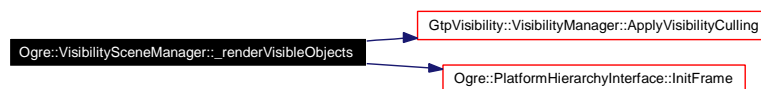
3.10.3.1 `void Ogre::VisibilitySceneManager::_renderVisibleObjects ()`

Overriden from SceneManager. Renders the scene using occlusion culling.

Remarks:

the type of algorithm is specified by the occlusion culling manager type using by the visibility manager.

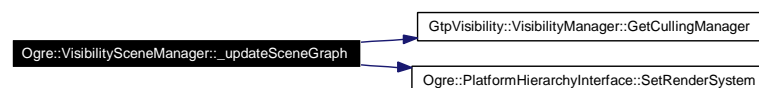
Here is the call graph for this function:



3.10.3.2 `void Ogre::VisibilitySceneManager::_findVisibleObjects (Camera * cam, bool onlyShadowCasters)`

3.10.3.3 `void Ogre::VisibilitySceneManager::_updateSceneGraph (Camera * cam)`

Here is the call graph for this function:



3.10.3.4 `bool Ogre::VisibilitySceneManager::setOption (const String &, const void *) [virtual]`

Sets the given option for the SceneManager

Remarks:

Options are: "Algorithm", int *;

3.10.3.5 `bool Ogre::VisibilitySceneManager::getOption (const String &, void *) [virtual]`

Gets the given option for the Scene VisibilityManager.

Remarks:

See setOption

3.10.3.6 `bool Ogre::VisibilitySceneManager::getOptionValues (const String & key, StringVector & refValueList)`

3.10.3.7 `bool Ogre::VisibilitySceneManager::getOptionKeys (StringVector & refKeys)`

3.10.3.8 `void Ogre::VisibilitySceneManager::setVisibilityManager (GtpVisibility::VisibilityManager * visManager)`

Sets the visibility manager.

Parameters:

visManager the visibility manager

3.10.3.9 `GtpVisibility::VisibilityManager * Ogre::VisibilitySceneManager::getVisibilityManager ()`

See set.

3.10.4 Member Data Documentation

3.10.4.1 `SceneNodeHierarchyInterface* Ogre::VisibilitySceneManager::mHierarchyInterface [protected]`

3.10.4.2 `GtpVisibility::VisibilityManager* Ogre::VisibilitySceneManager::mVisibilityManager [protected]`

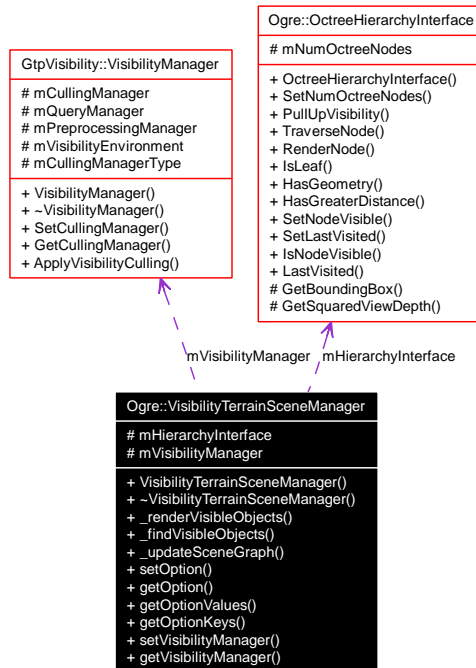
The documentation for this class was generated from the following files:

- [OgreVisibilitySceneManager.h](#)
- [OgreVisibilitySceneManager.cpp](#)

3.11 Ogre::VisibilityTerrainSceneManager Class Reference

```
#include <Ogre/include/OgreVisibilityTerrainSceneManager.h>
```

Collaboration diagram for Ogre::VisibilityTerrainSceneManager:



Public Member Functions

- [VisibilityTerrainSceneManager](#) ([GtpVisibility::VisibilityManager](#) *visManager)
- [~VisibilityTerrainSceneManager](#) ()
- [void _renderVisibleObjects](#) (void)
- [void _findVisibleObjects](#) ([Camera](#) *cam, bool onlyShadowCasters)
- [void _updateSceneGraph](#) ([Camera](#) *cam)
- virtual bool [setOption](#) (const [String](#) &, const void *)
- virtual bool [getOption](#) (const [String](#) &, void *)
- bool [getOptionValues](#) (const [String](#) &key, [StringVector](#) &refValueList)
- bool [getOptionKeys](#) ([StringVector](#) &refKeys)
- void [setVisibilityManager](#) ([GtpVisibility::VisibilityManager](#) *visManager)
- [GtpVisibility::VisibilityManager](#) * [getVisibilityManager](#) ()

Protected Attributes

- [OctreeHierarchyInterface](#) * mHierarchyInterface
- [GtpVisibility::VisibilityManager](#) * mVisibilityManager

3.11.1 Detailed Description

This class extends the terrain scene manager, using occlusion queries for visibility culling.

3.11.2 Constructor & Destructor Documentation

3.11.2.1 `Ogre::VisibilityTerrainSceneManager::VisibilityTerrainSceneManager` (`GtpVisibility::VisibilityManager * visManager`)

Here is the call graph for this function:

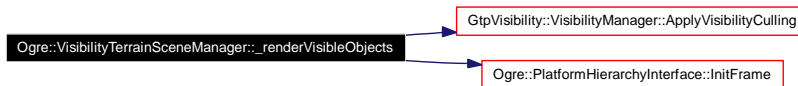


3.11.2.2 `Ogre::VisibilityTerrainSceneManager::~~VisibilityTerrainSceneManager` ()

3.11.3 Member Function Documentation

3.11.3.1 `void Ogre::VisibilityTerrainSceneManager::_renderVisibleObjects` (void)

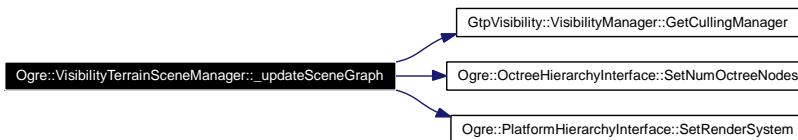
Here is the call graph for this function:



3.11.3.2 `void Ogre::VisibilityTerrainSceneManager::_findVisibleObjects` (`Camera * cam`, `bool onlyShadowCasters`)

3.11.3.3 `void Ogre::VisibilityTerrainSceneManager::_updateSceneGraph` (`Camera * cam`)

Here is the call graph for this function:



3.11.3.4 `bool Ogre::VisibilityTerrainSceneManager::setOption` (`const String &`, `const void *`) [virtual]

Sets the given option for the SceneManager

Remarks:

Options are: "Algorithm", int *;

3.11.3.5 `bool Ogre::VisibilityTerrainSceneManager::getOption` (`const String &`, `void *`) [virtual]

Gets the given option for the Scene VisibilityManager.

Remarks:

See `setOption`

3.11.3.6 `bool Ogre::VisibilityTerrainSceneManager::getOptionValues (const String & key, StringVector & refValueList)`

3.11.3.7 `bool Ogre::VisibilityTerrainSceneManager::getOptionKeys (StringVector & refKeys)`

3.11.3.8 `void Ogre::VisibilityTerrainSceneManager::setVisibilityManager (GtpVisibility::VisibilityManager * visManager)`

Sets the visibility manager.

Parameters:

visManager the visibility manager

3.11.3.9 `GtpVisibility::VisibilityManager * Ogre::VisibilityTerrainSceneManager::getVisibilityManager ()`

See `set`.

3.11.4 Member Data Documentation

3.11.4.1 `OctreeHierarchyInterface* Ogre::VisibilityTerrainSceneManager::mHierarchyInterface` [protected]

3.11.4.2 `GtpVisibility::VisibilityManager* Ogre::VisibilityTerrainSceneManager::mVisibilityManager` [protected]

The documentation for this class was generated from the following files:

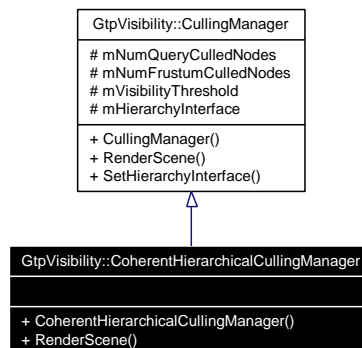
- [OgreVisibilityTerrainSceneManager.h](#)
- [OgreVisibilityTerrainSceneManager.cpp](#)

3.12 GtpVisibility::CoherentHierarchicalCullingManager Class Reference

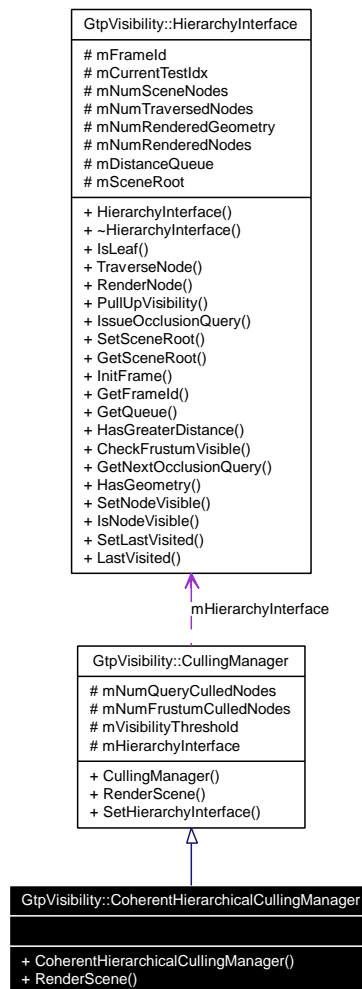
```
#include <GtpVisibility/include/CoherentHierarchicalCullingManager.h>
```

Inherits [GtpVisibility::CullingManager](#).

Inheritance diagram for GtpVisibility::CoherentHierarchicalCullingManager:



Collaboration diagram for GtpVisibility::CoherentHierarchicalCullingManager:



Public Member Functions

- [CoherentHierarchicalCullingManager](#) ([HierarchyInterface](#) *hierarchyInterface)
- void [RenderScene](#) ()

3.12.1 Detailed Description

Renders the scene with the coherent hierarchical culling algorithm.

3.12.2 Constructor & Destructor Documentation

3.12.2.1 GtpVisibility::CoherentHierarchicalCullingManager::CoherentHierarchicalCullingManager ([HierarchyInterface](#) * *hierarchyInterface*)

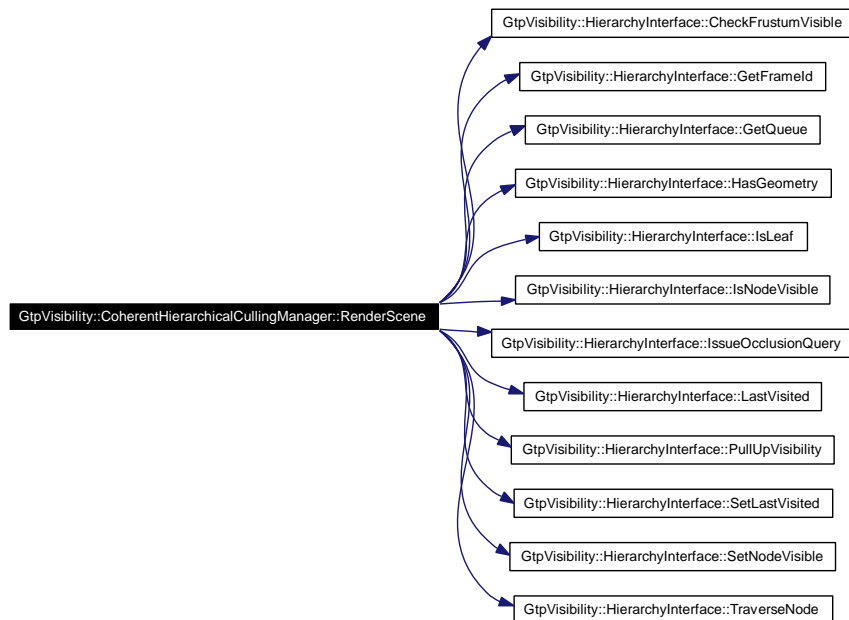
3.12.3 Member Function Documentation

3.12.3.1 void GtpVisibility::CoherentHierarchicalCullingManager::RenderScene () [virtual]

Renders the scene using a specific occlusion culling algorithm, e.g., coherent hierarchical culling or stop and wait.

Implements [GtpVisibility::CullingManager](#).

Here is the call graph for this function:



The documentation for this class was generated from the following files:

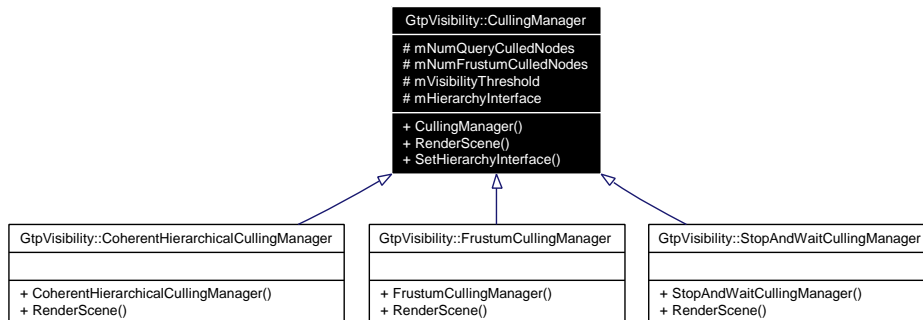
- [CoherentHierarchicalCullingManager.h](#)
- [CoherentHierarchicalCullingManager.cpp](#)

3.13 GtpVisibility::CullingManager Class Reference

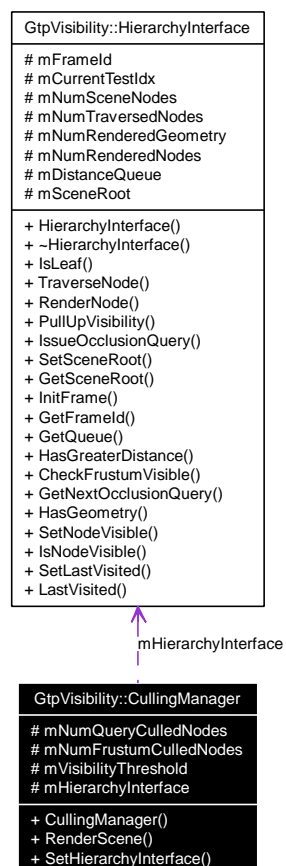
```
#include <GtpVisibility/include/CullingManager.h>
```

Inherited by [GtpVisibility::CoherentHierarchicalCullingManager](#), [GtpVisibility::FrustumCullingManager](#), and [GtpVisibility::StopAndWaitCullingManager](#).

Inheritance diagram for GtpVisibility::CullingManager:



Collaboration diagram for GtpVisibility::CullingManager:



Public Member Functions

- [CullingManager](#) ([HierarchyInterface](#) *hierarchyInterface)
- virtual void [RenderScene](#) ()=0
- void [SetHierarchyInterface](#) ([HierarchyInterface](#) *hierarchyInterface)

Protected Attributes

- unsigned int [mNumQueryCulledNodes](#)
- unsigned int [mNumFrustumCulledNodes](#)
- unsigned int [mVisibilityThreshold](#)
- [HierarchyInterface](#) * [mHierarchyInterface](#)

3.13.1 Detailed Description

This abstract class implements an interface for a specific culling algorithm. The algorithm is either used to render a scene or to make a visibility query.

3.13.2 Constructor & Destructor Documentation

3.13.2.1 [GtpVisibility::CullingManager::CullingManager](#) ([HierarchyInterface](#) * *hierarchyInterface*)

Constructor taking a scene traverser for a specific type of hierarchy as argument.

3.13.3 Member Function Documentation

3.13.3.1 virtual void [GtpVisibility::CullingManager::RenderScene](#) () [pure virtual]

Renders the scene using a specific occlusion culling algorithm, e.g., coherent hierarchical culling or stop and wait.

Implemented in [GtpVisibility::CoherentHierarchicalCullingManager](#), [GtpVisibility::FrustumCullingManager](#), and [GtpVisibility::StopAndWaitCullingManager](#).

3.13.3.2 void [GtpVisibility::CullingManager::SetHierarchyInterface](#) ([HierarchyInterface](#) * *hierarchyInterface*)

Sets the hierarchy interface.

Parameters:

hierarchyInterface

Remarks:

the hierarchy interface encapsulates the hierarchy we are working on

3.13.4 Member Data Documentation

3.13.4.1 **unsigned int** [GtpVisibility::CullingManager::mNumQueryCulledNodes](#) [protected]

3.13.4.2 **unsigned int** [GtpVisibility::CullingManager::mNumFrustumCulledNodes](#)
[protected]

3.13.4.3 **unsigned int** [GtpVisibility::CullingManager::mVisibilityThreshold](#) [protected]

3.13.4.4 **HierarchyInterface*** [GtpVisibility::CullingManager::mHierarchyInterface](#)
[protected]

The documentation for this class was generated from the following files:

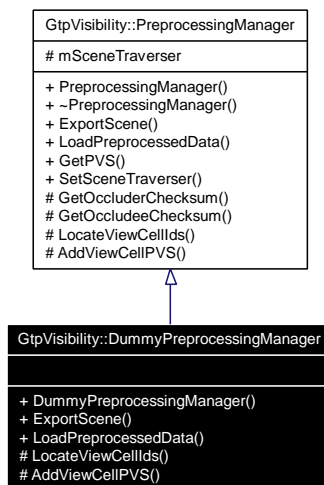
- [CullingManager.h](#)
- [CullingManager.cpp](#)

3.14 GtpVisibility::DummyPreprocessingManager Class Reference

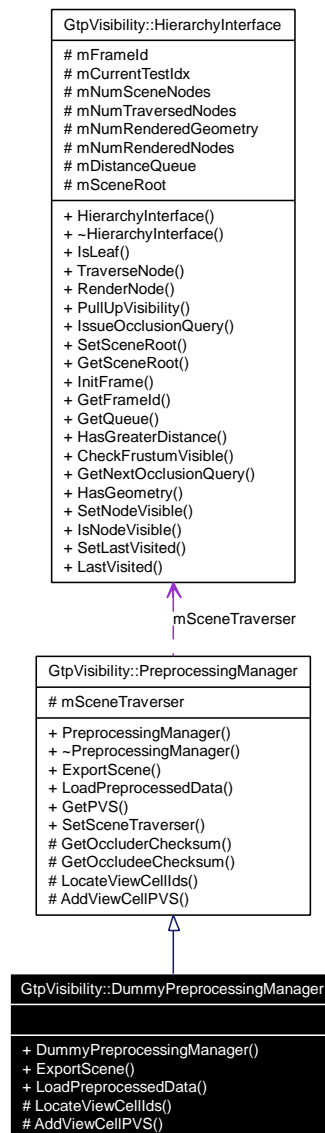
```
#include <GtpVisibility/include/DummyPreprocessingManager.h>
```

Inherits [GtpVisibility::PreprocessingManager](#).

Inheritance diagram for GtpVisibility::DummyPreprocessingManager:



Collaboration diagram for GtpVisibility::DummyPreprocessingManager:



Public Member Functions

- `DummyPreprocessingManager` (`HierarchyInterface *hierarchyInterface`)
- virtual bool `ExportScene` (const string filename)
- virtual bool `LoadPreprocessedData` (const string filename)

Protected Member Functions

- virtual bool `LocateViewCellIds` (const `Vector3` ¢er, const float radius, vector< int > *viewCellIds)
- virtual int `AddViewCellPVS` (const int cellID, InfoContainer< `NodeInfo` > *visibleNodes, InfoContainer< `MeshInfo` > *visibleMeshes)

3.14.1 Detailed Description

Implements a dummy interface to the external visibility preprocessing.

3.14.2 Constructor & Destructor Documentation

3.14.2.1 GtpVisibility::DummyPreprocessingManager::DummyPreprocessingManager ([HierarchyInterface](#) * *hierarchyInterface*)

Constructor taking a scene traverser for a specific type of hierarchyInterface as argument.

3.14.3 Member Function Documentation

3.14.3.1 bool GtpVisibility::DummyPreprocessingManager::ExportScene (const string *filename*) [virtual]

Export the scene for visibility preprocessing. Exports the hierarchyInterface including its bounding boxes + mesh data for occluders. The viewcell data will either be supplied directly to the visibility preprocessing standalone module

Implements [GtpVisibility::PreprocessingManager](#).

3.14.3.2 bool GtpVisibility::DummyPreprocessingManager::LoadPreprocessedData (const string *filename*) [virtual]

Load preprocessed visibility information

Implements [GtpVisibility::PreprocessingManager](#).

3.14.3.3 bool GtpVisibility::DummyPreprocessingManager::LocateViewCellIds (const [Vector3](#) & *center*, const float *radius*, vector< int > * *viewCellIds*) [protected, virtual]

Find viewcells intersecting a spherical neighborhood of a point. Returns false if no viewcell was found.

Implements [GtpVisibility::PreprocessingManager](#).

3.14.3.4 int GtpVisibility::DummyPreprocessingManager::AddViewCellPVS (const int *cellID*, [InfoContainer](#)< [NodeInfo](#) > * *visibleNodes*, [InfoContainer](#)< [MeshInfo](#) > * *visibleMeshes*) [protected, virtual]

Add a PVS of the given viewcell to the already evaluated PVS by computing a union with visibleNodes and visibleMeshes. Returns the number of added entries.

Implements [GtpVisibility::PreprocessingManager](#).

The documentation for this class was generated from the following files:

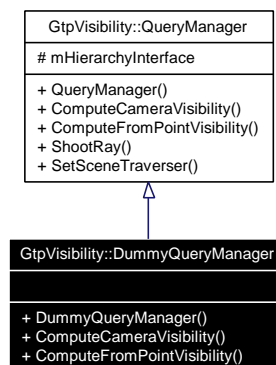
- [DummyPreprocessingManager.h](#)
- [DummyPreprocessingManager.cpp](#)

3.15 GtpVisibility::DummyQueryManager Class Reference

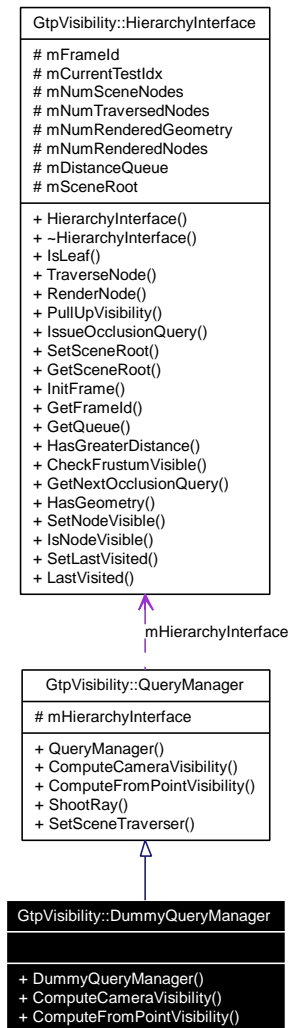
```
#include <GtpVisibility/include/DummyQueryManager.h>
```

Inherits [GtpVisibility::QueryManager](#).

Inheritance diagram for GtpVisibility::DummyQueryManager:



Collaboration diagram for GtpVisibility::DummyQueryManager:



Public Member Functions

- [DummyQueryManager](#) ([HierarchyInterface](#) *hierarchyInterface)
- virtual void [ComputeCameraVisibility](#) (const [Camera](#) &camera, InfoContainer< [NodeInfo](#) > *visibleNodes, InfoContainer< [MeshInfo](#) > *visibleGeometry, bool relativeVisibility=false)
- virtual void [ComputeFromPointVisibility](#) (const [Vector3](#) &point, InfoContainer< [NodeInfo](#) > *visibleNodes, InfoContainer< [MeshInfo](#) > *visibleGeometry, bool relativeVisibility=false)

3.15.1 Detailed Description

This implements dummy visibility queries. The queries return only the root of the hierarchy as visible node.

3.15.2 Constructor & Destructor Documentation

3.15.2.1 GtpVisibility::DummyQueryManager::DummyQueryManager ([HierarchyInterface](#) * *hierarchyInterface*) [inline]

Constructor taking a scene traverser for a specific type of hierarchyInterface as argument.

3.15.3 Member Function Documentation

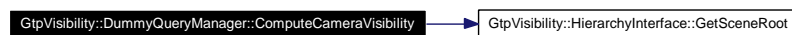
3.15.3.1 void GtpVisibility::DummyQueryManager::ComputeCameraVisibility (const [Camera](#) & *camera*, [InfoContainer](#)< [NodeInfo](#) > * *visibleNodes*, [InfoContainer](#)< [MeshInfo](#) > * *visibleGeometry*, bool *relativeVisibility* = false) [virtual]

See also:

[QueryManager::ComputeCameraVisibility\(\)](#)

Implements [GtpVisibility::QueryManager](#).

Here is the call graph for this function:



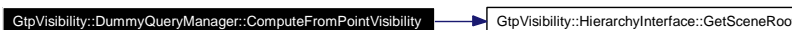
3.15.3.2 void GtpVisibility::DummyQueryManager::ComputeFromPointVisibility (const [Vector3](#) & *point*, [InfoContainer](#)< [NodeInfo](#) > * *visibleNodes*, [InfoContainer](#)< [MeshInfo](#) > * *visibleGeometry*, bool *relativeVisibility* = false) [virtual]

See also:

[QueryManager::ComputeFromPointVisibility\(\)](#)

Implements [GtpVisibility::QueryManager](#).

Here is the call graph for this function:



The documentation for this class was generated from the following files:

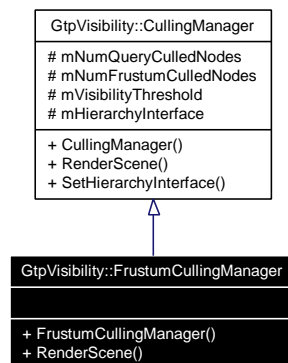
- [DummyQueryManager.h](#)
- [DummyQueryManager.cpp](#)

3.16 GtpVisibility::FrustumCullingManager Class Reference

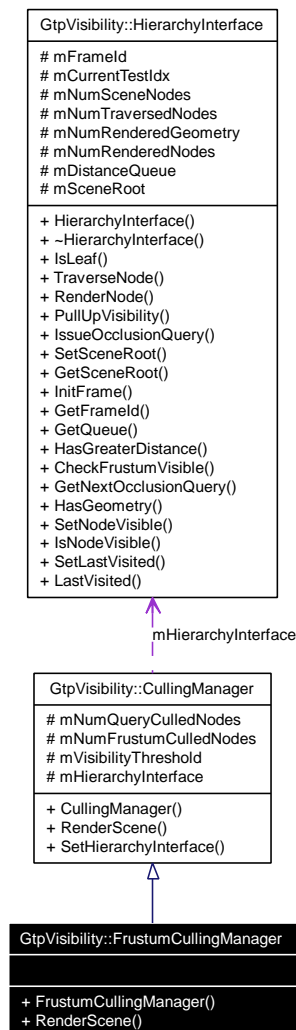
```
#include <GtpVisibility/include/FrustumCullingManager.h>
```

Inherits [GtpVisibility::CullingManager](#).

Inheritance diagram for GtpVisibility::FrustumCullingManager:



Collaboration diagram for GtpVisibility::FrustumCullingManager:



Public Member Functions

- [FrustumCullingManager](#) ([HierarchyInterface](#) *hierarchyInterface)
- void [RenderScene](#) ()

3.16.1 Detailed Description

Renders the scene, applies only view frustum culling.

3.16.2 Constructor & Destructor Documentation

3.16.2.1 GtpVisibility::FrustumCullingManager::FrustumCullingManager ([HierarchyInterface](#) * *hierarchyInterface*)

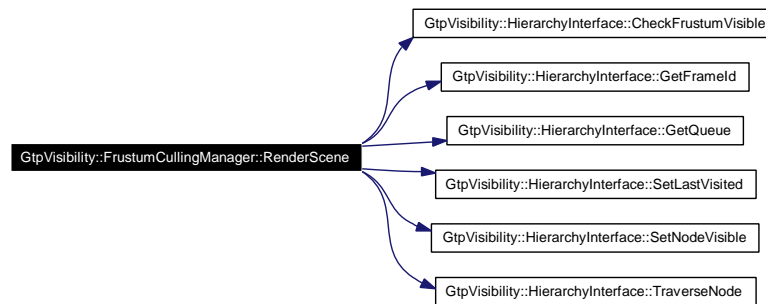
3.16.3 Member Function Documentation

3.16.3.1 void GtpVisibility::FrustumCullingManager::RenderScene () [virtual]

Renders the scene using a specific occlusion culling algorithm, e.g., coherent hierarchical culling or stop and wait.

Implements [GtpVisibility::CullingManager](#).

Here is the call graph for this function:



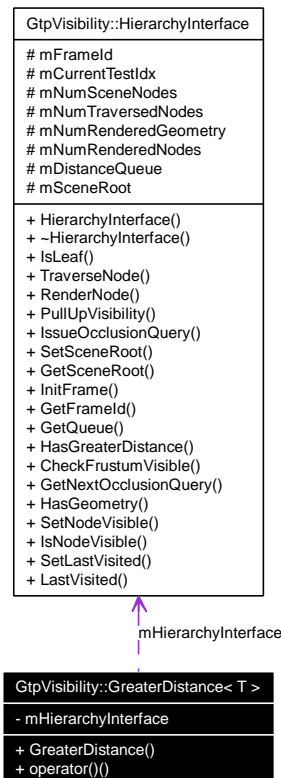
The documentation for this class was generated from the following files:

- [FrustumCullingManager.h](#)
- [FrustumCullingManager.cpp](#)

3.17 GtpVisibility::GreaterDistance< T > Class Template Reference

```
#include <GtpVisibility/include/DistanceQueue.h>
```

Collaboration diagram for GtpVisibility::GreaterDistance< T >:



Public Member Functions

- `GreaterDistance` (`HierarchyInterface *hierarchyInterface`)
- `bool operator()` (`T v1, T v2`) `const`

Private Attributes

- `HierarchyInterface * mHierarchyInterface`

3.17.1 Detailed Description

```
template<typename T> class GtpVisibility::GreaterDistance< T >
```

This class implements the less operator for the priority queue, i.e., a greater distance has a lower priority in the queue.

3.17.2 Constructor & Destructor Documentation

3.17.2.1 `template<typename T> GtpVisibility::GreaterDistance< T >::GreaterDistance (HierarchyInterface * hierarchyInterface) [inline]`

3.17.3 Member Function Documentation

3.17.3.1 `template<typename T> bool GtpVisibility::GreaterDistance< T >::operator() (T v1, T v2) const [inline]`

Here is the call graph for this function:



3.17.4 Member Data Documentation

3.17.4.1 `template<typename T> HierarchyInterface* GtpVisibility::GreaterDistance< T >::mHierarchyInterface [private]`

The documentation for this class was generated from the following file:

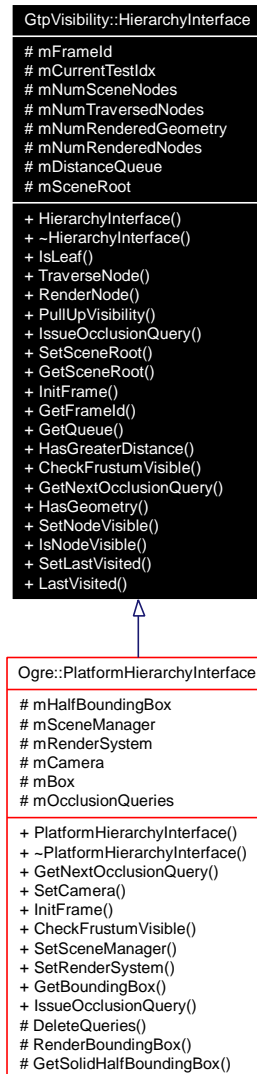
- [DistanceQueue.h](#)

3.18 GtpVisibility::HierarchyInterface Class Reference

```
#include <GtpVisibility/include/HierarchyInterface.h>
```

Inherited by [Ogre::PlatformHierarchyInterface](#).

Inheritance diagram for GtpVisibility::HierarchyInterface:



Public Member Functions

- [HierarchyInterface](#) ()
- virtual [~HierarchyInterface](#) ()
- virtual bool [IsLeaf](#) ([HierarchyNode](#) *node)=0
- virtual void [TraverseNode](#) ([HierarchyNode](#) *node)=0
- virtual void [RenderNode](#) ([HierarchyNode](#) *node)=0
- virtual void [PullUpVisibility](#) ([HierarchyNode](#) *node)=0
- virtual [OcclusionQuery](#) * [IssueOcclusionQuery](#) ([HierarchyNode](#) *node)=0

- void [SetSceneRoot](#) ([HierarchyNode](#) *root)
- [HierarchyNode](#) * [GetSceneRoot](#) () const
- void [InitFrame](#) ([HierarchyNode](#) *root)
- int [GetFrameId](#) ()
- [DistanceQueue](#) * [GetQueue](#) ()
- virtual bool [HasGreaterDistance](#) ([HierarchyNode](#) *node1, [HierarchyNode](#) *node2)=0
- virtual bool [CheckFrustumVisible](#) ([HierarchyNode](#) *node, bool &intersects)=0
- virtual [OcclusionQuery](#) * [GetNextOcclusionQuery](#) ()=0
- virtual bool [HasGeometry](#) ([HierarchyNode](#) *node)=0
- virtual void [SetNodeVisible](#) ([HierarchyNode](#) *node, const bool visible)=0
- virtual bool [IsNodeVisible](#) ([HierarchyNode](#) *node)=0
- virtual void [SetLastVisited](#) ([HierarchyNode](#) *node, const int frameId)=0
- virtual int [LastVisited](#) ([HierarchyNode](#) *node)=0

Protected Attributes

- unsigned int [mFrameId](#)
- int [mCurrentTestIdx](#)
- unsigned int [mNumSceneNodes](#)
- unsigned int [mNumTraversedNodes](#)
- unsigned int [mNumRenderedGeometry](#)
- unsigned int [mNumRenderedNodes](#)
- [DistanceQueue](#) * [mDistanceQueue](#)
- [HierarchyNode](#) * [mSceneRoot](#)

3.18.1 Detailed Description

Class which implements a hierarchy interface for a scene hierarchy.

3.18.2 Constructor & Destructor Documentation

3.18.2.1 [GtpVisibility::HierarchyInterface::HierarchyInterface](#) ()

Default constructor.

3.18.2.2 [GtpVisibility::HierarchyInterface::~~HierarchyInterface](#) () [virtual]

3.18.3 Member Function Documentation

3.18.3.1 virtual bool [GtpVisibility::HierarchyInterface::IsLeaf](#) ([HierarchyNode](#) * *node*) [pure virtual]

Returns true if current node is leaf of the hierarchy.

Parameters:

node hierarchy node

Returns:

true if node is leaf

3.18.3.2 `virtual void GtpVisibility::HierarchyInterface::TraverseNode (HierarchyNode * node)`
[pure virtual]

Traverses the given node.

Parameters:

node the hierarchy node

3.18.3.3 `virtual void GtpVisibility::HierarchyInterface::RenderNode (HierarchyNode * node)`
[pure virtual]

Renders current scene node .

Parameters:

node current scene node to be rendered

3.18.3.4 `virtual void GtpVisibility::HierarchyInterface::PullUpVisibility (HierarchyNode * node)`
[pure virtual]

Pulls up the visibility from the current node recursively to the parent nodes.

Parameters:

node the current node

3.18.3.5 `virtual OcclusionQuery* GtpVisibility::HierarchyInterface::IssueOcclusionQuery (HierarchyNode * node)` [pure virtual]

Issue a occlusion query for this node.

Parameters:

node the current hierarchy node

Returns:

occlusion query for this node

3.18.3.6 `void GtpVisibility::HierarchyInterface::SetSceneRoot (HierarchyNode * root)`

Sets the root of the scene hierarchy.

Parameters:

root the hierarchy root

3.18.3.7 `HierarchyNode* GtpVisibility::HierarchyInterface::GetSceneRoot () const` [inline]

Get the root of the scene hierarchy.

Returns:

the hierarchy root

3.18.3.8 void GtpVisibility::HierarchyInterface::InitFrame ([HierarchyNode](#) * *root*)

Sets the scene root and initialises this scene traverser for a traversal.

Parameters:

root current scene root

Remarks:

initialises some parameters, and also the statistics.

Here is the call graph for this function:



3.18.3.9 int GtpVisibility::HierarchyInterface::GetFrameId ()

Returns current frame id.

Returns:

frame id

3.18.3.10 [DistanceQueue](#) * GtpVisibility::HierarchyInterface::GetQueue ()

Returns the current distance queue.

Returns:

current distance queue

3.18.3.11 virtual bool GtpVisibility::HierarchyInterface::HasGreaterDistance ([HierarchyNode](#) * *node1*, [HierarchyNode](#) * *node2*) [pure virtual]

Returns true if node 1 has greater distance to the view plane than node 2.

Parameters:

node1 the first node to be compared

node2 the second node to be compared

3.18.3.12 virtual bool GtpVisibility::HierarchyInterface::CheckFrustumVisible ([HierarchyNode](#) * *node*, bool & *intersects*) [pure virtual]

Checks if the node is visible from the current view frustum.

Parameters:

node the current node

intersects returns true if the current node intersects the near plane

3.18.3.13 virtual [OcclusionQuery](#)* GtpVisibility::HierarchyInterface::GetNextOcclusionQuery ()
[pure virtual]

Returns next available occlusion query or creates new one.

Returns:

the next occlusion query

Implemented in [Ogre::PlatformHierarchyInterface](#).

3.18.3.14 virtual bool GtpVisibility::HierarchyInterface::HasGeometry ([HierarchyNode](#) * node)
[pure virtual]

Returns true if there is renderable geometry attached to this node

Parameters:

node the current node

Returns:

if the node has renderable geometry

3.18.3.15 virtual void GtpVisibility::HierarchyInterface::SetNodeVisible ([HierarchyNode](#) * node,
const bool *visible*) [pure virtual]

Sets the visible flag for this node.

Parameters:

node the current node

visible the visible flag

3.18.3.16 virtual bool GtpVisibility::HierarchyInterface::IsNodeVisible ([HierarchyNode](#) * node)
[pure virtual]

Returns true if node has the visible flag set. See set

3.18.3.17 virtual void GtpVisibility::HierarchyInterface::SetLastVisited ([HierarchyNode](#) * node,
const int *frameId*) [pure virtual]

Sets the last visited frame id for this node.

Parameters:

node the current node

frameId the current frame id

3.18.3.18 virtual int GtpVisibility::HierarchyInterface::LastVisited ([HierarchyNode](#) * node)
[pure virtual]

Returns frame id when this node was last visited by the traverser. See set

3.18.4 Member Data Documentation

- 3.18.4.1 **unsigned int** [GtpVisibility::HierarchyInterface::mFrameId](#) [protected]
- 3.18.4.2 **int** [GtpVisibility::HierarchyInterface::mCurrentTestIdx](#) [protected]
- 3.18.4.3 **unsigned int** [GtpVisibility::HierarchyInterface::mNumSceneNodes](#) [protected]
- 3.18.4.4 **unsigned int** [GtpVisibility::HierarchyInterface::mNumTraversedNodes](#) [protected]
- 3.18.4.5 **unsigned int** [GtpVisibility::HierarchyInterface::mNumRenderedGeometry](#) [protected]
- 3.18.4.6 **unsigned int** [GtpVisibility::HierarchyInterface::mNumRenderedNodes](#) [protected]
- 3.18.4.7 **DistanceQueue*** [GtpVisibility::HierarchyInterface::mDistanceQueue](#) [protected]
- 3.18.4.8 **HierarchyNode*** [GtpVisibility::HierarchyInterface::mSceneRoot](#) [protected]

The documentation for this class was generated from the following files:

- [HierarchyInterface.h](#)
- [HierarchyInterface.cpp](#)

3.19 GtpVisibility::MeshInfo Class Reference

```
#include <GtpVisibility/include/VisibilityInfo.h>
```

Public Member Functions

- [MeshInfo](#) ([Mesh](#) *mesh, const float v)

Protected Attributes

- [Mesh](#) * [mMesh](#)
- float [mVisibility](#)

3.19.1 Detailed Description

Class storing the visibility information of a mesh.

3.19.2 Constructor & Destructor Documentation

3.19.2.1 [GtpVisibility::MeshInfo::MeshInfo](#) ([Mesh](#) * *mesh*, const float v) [inline]

3.19.3 Member Data Documentation

3.19.3.1 [Mesh*](#) [GtpVisibility::MeshInfo::mMesh](#) [protected]

pointer to the scene node

3.19.3.2 float [GtpVisibility::MeshInfo::mVisibility](#) [protected]

node visibility can either be a number of visible pixels or relative number of visible pixels (if the hardware queries will provide the total number of rasterized pixels)

The documentation for this class was generated from the following file:

- [VisibilityInfo.h](#)

3.20 GtpVisibility::NodeInfo Class Reference

```
#include <GtpVisibility/include/VisibilityInfo.h>
```

Public Member Functions

- [NodeInfo](#) ([HierarchyNode](#) *node, const float v)

Protected Attributes

- [HierarchyNode](#) * mNode
- float [mVisibility](#)

3.20.1 Detailed Description

Class storing the visibility information of a scene node.

3.20.2 Constructor & Destructor Documentation

3.20.2.1 [GtpVisibility::NodeInfo::NodeInfo](#) ([HierarchyNode](#) * node, const float v) [inline]

3.20.3 Member Data Documentation

3.20.3.1 [HierarchyNode*](#) [GtpVisibility::NodeInfo::mNode](#) [protected]

pointer to the scene node

3.20.3.2 float [GtpVisibility::NodeInfo::mVisibility](#) [protected]

node visibility can either be a number of visible pixels or relative number of visible pixels (if the hardware queries will provide the total number of rasterized pixels)

The documentation for this class was generated from the following file:

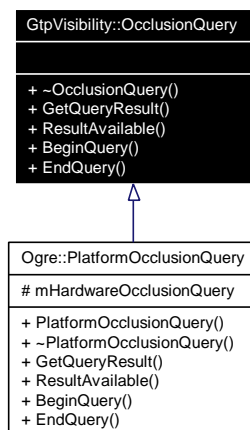
- [VisibilityInfo.h](#)

3.21 GtpVisibility::OcclusionQuery Class Reference

```
#include <GtpVisibility/include/OcclusionQuery.h>
```

Inherited by [Ogre::PlatformOcclusionQuery](#).

Inheritance diagram for GtpVisibility::OcclusionQuery:



Public Member Functions

- virtual `~OcclusionQuery ()`
- virtual unsigned int `GetQueryResult ()` const =0
- virtual bool `ResultAvailable ()` const =0
- virtual void `BeginQuery ()` const =0
- virtual void `EndQuery ()` const =0

3.21.1 Detailed Description

This class is an abstract interface for occlusion queries.

3.21.2 Constructor & Destructor Documentation

3.21.2.1 `virtual GtpVisibility::OcclusionQuery::~~OcclusionQuery ()` [`inline`, `virtual`]

3.21.3 Member Function Documentation

3.21.3.1 `virtual unsigned int GtpVisibility::OcclusionQuery::GetQueryResult ()` const [`pure virtual`]

Returns the result of an occlusion query in terms of visible pixels.

Returns:

number of visible pixels

Implemented in [Ogre::PlatformOcclusionQuery](#).

3.21.3.2 `virtual bool GtpVisibility::OcclusionQuery::ResultAvailable () const` [pure virtual]

Returns true if the result of the query is available, false otherwise.

Returns:

if result is available

Implemented in [Ogre::PlatformOcclusionQuery](#).

3.21.3.3 `virtual void GtpVisibility::OcclusionQuery::BeginQuery () const` [pure virtual]

Begins occlusion query.

Remarks:

the query counts the number of visible pixels between it's begin and end

Implemented in [Ogre::PlatformOcclusionQuery](#).

3.21.3.4 `virtual void GtpVisibility::OcclusionQuery::EndQuery () const` [pure virtual]

Ends occlusion query.

Implemented in [Ogre::PlatformOcclusionQuery](#).

The documentation for this class was generated from the following file:

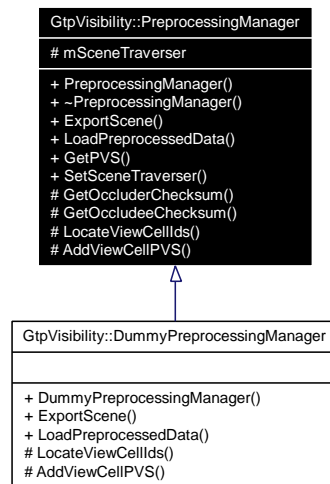
- [OcclusionQuery.h](#)

3.22 GtpVisibility::PreprocessingManager Class Reference

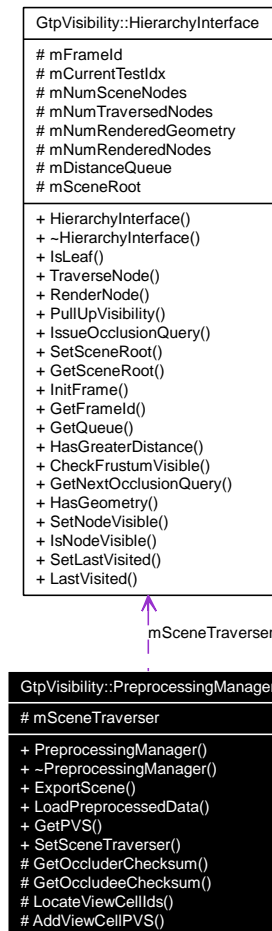
```
#include <GtpVisibility/include/PreprocessingManager.h>
```

Inherited by [GtpVisibility::DummyPreprocessingManager](#).

Inheritance diagram for GtpVisibility::PreprocessingManager:



Collaboration diagram for GtpVisibility::PreprocessingManager:



Public Member Functions

- [PreprocessingManager](#) ([HierarchyInterface](#) *hierarchyInterface)
- virtual [~PreprocessingManager](#) ()
- virtual bool [ExportScene](#) (const string filename)=0
- virtual bool [LoadPreprocessedData](#) (const string filename)=0
- virtual bool [GetPVS](#) (const [Vector3](#) &point, const float radius, [InfoContainer](#)< [NodeInfo](#) > *visibleNodes, [InfoContainer](#)< [MeshInfo](#) > *visibleMeshes)
- virtual void [SetSceneTraverser](#) ([HierarchyInterface](#) *hierarchyInterface)

Protected Member Functions

- long [GetOccluderChecksum](#) () const
- long [GetOccludeeChecksum](#) () const
- virtual bool [LocateViewCellIds](#) (const [Vector3](#) ¢er, const float radius, [vector](#)< int > *viewCellIds)=0
- virtual int [AddViewCellPVS](#) (const int cellID, [InfoContainer](#)< [NodeInfo](#) > *visibleNodes, [InfoContainer](#)< [MeshInfo](#) > *visibleMeshes)=0

Protected Attributes

- [HierarchyInterface](#) * `mSceneTraverser`

3.22.1 Detailed Description

This class defines an interface to the external visibility preprocessor. It allows to export the static part of the scene to a file in the XML format understood by the preprocessor. By default all the exported meshes are considered as scene occluders, whereas occludees are formed by their bounding boxes, and bounding boxes of the scene hierarchy.

This class also allows to import the preprocessed data with PVS information for the viewcells (note that the viewcells are either generated automatically by the preprocessor or loaded from a polyhedral definition stored in a file (see documentation for the Preprocessor class).

3.22.2 Constructor & Destructor Documentation

3.22.2.1 GtpVisibility::PreprocessingManager::PreprocessingManager ([HierarchyInterface](#) * *hierarchyInterface*)

Constructor taking a [HierarchyInterface](#) as argument. The [HierarchyInterface](#) makes the [PreprocessingManager](#) independent from the actual scene representation as long as it supports a required set of methods.

3.22.2.2 virtual GtpVisibility::PreprocessingManager::~~PreprocessingManager () [virtual]

Destructor which deletes all data describing static scene visibility.

3.22.3 Member Function Documentation

3.22.3.1 virtual bool GtpVisibility::PreprocessingManager::ExportScene (const string *filename*) [pure virtual]

Export the scene for visibility preprocessing. Exports the hierarchyInterface including its bounding boxes + mesh data. Note that the bounding boxes can be used as occludees by the external preprocessor. The viewcell data will either be supplied directly to the visibility preprocessing standalone module.

Parameters:

filename name of the file to export.

Returns:

true if the export was succesful.

Implemented in [GtpVisibility::DummyPreprocessingManager](#).

3.22.3.2 virtual bool GtpVisibility::PreprocessingManager::LoadPreprocessedData (const string *filename*) [pure virtual]

Load preprocessed visibility information. The loaded data is matched with the current scene graph. The topology of the current scene graph has to match with the loaded data. There is also geometrical check of

the bounding boxes. Once loading is successful the [PreprocessingManager](#) establishes links from its internal visibility representation to the scene graph: no change of this part of the scene graph is allowed; this would violate the static scene assumption!

Parameters:

filename name of the file to load.

Returns:

true if the loading was successful.

Implemented in [GtpVisibility::DummyPreprocessingManager](#).

3.22.3.3 bool GtpVisibility::PreprocessingManager::GetPVS (const [Vector3](#) & *point*, const float *radius*, [InfoContainer](#)< [NodeInfo](#) > * *visibleNodes*, [InfoContainer](#)< [MeshInfo](#) > * *visibleMeshes*) [virtual]

Retrieve a PVS corresponding to the given spherical neighborhood of the point. Typically the implementation of this method will first locate all viewcells intersecting the sphere using efficient logarithmic search enhanced with caching the last query. Then it computes a union of the PVS for the found viewcells.

Parameters:

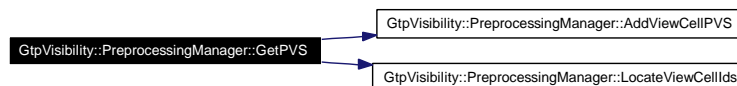
point the center point of the spherical neighborhood

radius the radius of the spherical neighborhood. Note that if radius==0 a more efficient implementation of the method for this special case can be used.

visibleNodes if not NULL a set of visible hierarchy nodes is added to the visibleNodes container. This set is formed of visible leafs or fully visible interior nodes.

visibleMeshes if not NULL the set of visible meshes is added to the container. Returns true if the corresponding PVS exists.

Here is the call graph for this function:



3.22.3.4 virtual void GtpVisibility::PreprocessingManager::SetSceneTraverser ([HierarchyInterface](#) * *hierarchyInterface*) [inline, virtual]

Sets the scene traverser.

Remarks:

the scene traverser is dependent on the type of hierarchyInterface the scene consists of.

3.22.3.5 long GtpVisibility::PreprocessingManager::GetOccluderChecksum () const [inline, protected]

Get checksum of the current occluder set in the scene graph. This method is used to check if the preprocessed data matches the current scene graph -> \$\$ could be moved to VisibilitySceneTraverser

3.22.3.6 `long GtpVisibility::PreprocessingManager::GetOccludeeChecksum () const` [`inline`, `protected`]

Get checksum of the current occludee set in the scene graph. This method is used to check if the preprocessed data matches the current scene graph -> \$\$ could be moved to VisibilitySceneTraverser

3.22.3.7 `virtual bool GtpVisibility::PreprocessingManager::LocateViewCellIds (const Vector3 & center, const float radius, vector< int > * viewCellIds)` [`protected`, `pure virtual`]

Find viewcells intersecting a spherical neighborhood of a point. Returns false if no viewcell was found.

Implemented in [GtpVisibility::DummyPreprocessingManager](#).

3.22.3.8 `virtual int GtpVisibility::PreprocessingManager::AddViewCellPVS (const int cellID, InfoContainer< NodeInfo > * visibleNodes, InfoContainer< MeshInfo > * visibleMeshes)` [`protected`, `pure virtual`]

Add a PVS of the given viewcell to the already evaluated PVS by computing a union with visibleNodes and visibleMeshes. Returns the number of added entries.

Implemented in [GtpVisibility::DummyPreprocessingManager](#).

3.22.4 Member Data Documentation

3.22.4.1 `HierarchyInterface* GtpVisibility::PreprocessingManager::mSceneTraverser` [`protected`]

The documentation for this class was generated from the following files:

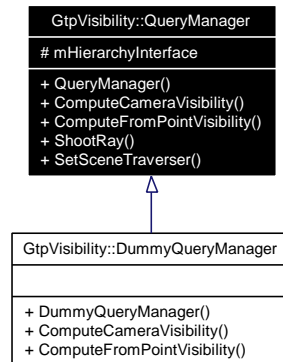
- [PreprocessingManager.h](#)
- [PreprocessingManager.cpp](#)

3.23 GtpVisibility::QueryManager Class Reference

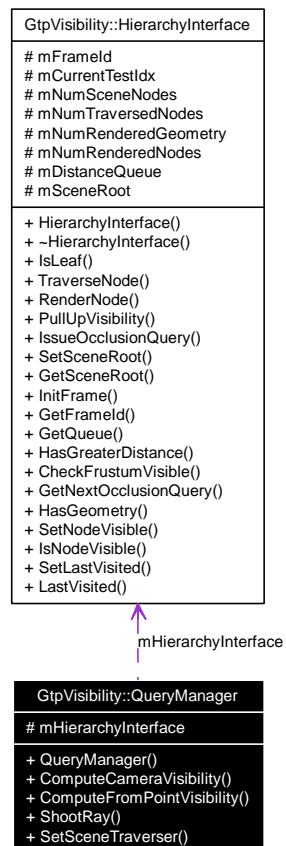
```
#include <GtpVisibility/include/QueryManager.h>
```

Inherited by [GtpVisibility::DummyQueryManager](#).

Inheritance diagram for GtpVisibility::QueryManager:



Collaboration diagram for GtpVisibility::QueryManager:



Public Member Functions

- [QueryManager](#) ([HierarchyInterface](#) *hierarchyInterface)
- virtual void [ComputeCameraVisibility](#) (const [Camera](#) &camera, [InfoContainer](#)< [NodeInfo](#) > *visibleNodes, [InfoContainer](#)< [MeshInfo](#) > *visibleGeometry, bool relativeVisibility=false)=0
- virtual void [ComputeFromPointVisibility](#) (const [Vector3](#) &point, [InfoContainer](#)< [NodeInfo](#) > *visibleNodes, [InfoContainer](#)< [MeshInfo](#) > *visibleGeometry, bool relativeVisibility=false)=0
- virtual bool [ShootRay](#) (const [Ray](#) &ray, [std::vector](#)< [Mesh](#) * > *visibleMeshes, bool isGlobalLine=false)
- void [SetSceneTraverser](#) ([HierarchyInterface](#) *hierarchyInterface)

Protected Attributes

- [HierarchyInterface](#) * mHierarchyInterface

3.23.1 Detailed Description

This abstract class defines interface for a specific visibility query algorithm. The interface supports two from point visibility queries and the ray shooting query. The output of the queries consists of list of visible meshes and hierarchy nodes. The from point queries will be implemented either with item buffering or based purely on occlusion queries. Note that the actual implementation can also exploit the output of the visibility preprocessor.

3.23.2 Constructor & Destructor Documentation

3.23.2.1 GtpVisibility::QueryManager::QueryManager ([HierarchyInterface](#) * hierarchyInterface)

Constructor taking a hierarchy interface as an argument. This allows to operate onm different hierarchy types, while reusing the implementation of the query methods.

3.23.3 Member Function Documentation

3.23.3.1 virtual void GtpVisibility::QueryManager::ComputeCameraVisibility (const [Camera](#) & camera, [InfoContainer](#)< [NodeInfo](#) > * visibleNodes, [InfoContainer](#)< [MeshInfo](#) > * visibleGeometry, bool relativeVisibility = false) [pure virtual]

Computes restricted visibility from point by using an explicit camera to execute the visibility query.

Parameters:

camera The camera to be used

visibleNodes Pointer to the container where visible nodes should be added. This set is formed of visible leafs or fully visible interior nodes. If NULL no visible nodes are not evaluated.

visibleGeometry Pointer to the container where visible meshes should be added. If NULL no visible meshes are not evaluated.

relativeVisibility If true the visibility member for [NodeInfo](#) and [MeshInfo](#) represent relative visibility; i.e. the number of visible pixels divided by the the number of projected pixels.

Returns:

true if the corresponding PVS exists.

Implemented in [GtpVisibility::DummyQueryManager](#).

3.23.3.2 `virtual void GtpVisibility::QueryManager::ComputeFromPointVisibility (const Vector3 & point, InfoContainer< NodeInfo > * visibleNodes, InfoContainer< MeshInfo > * visibleGeometry, bool relativeVisibility = false) [pure virtual]`

Uses the specified point to execute the visibility query in all directions.

See also:

[ComputeCameraVisibility\(\)](#)

Implemented in [GtpVisibility::DummyQueryManager](#).

3.23.3.3 `bool GtpVisibility::QueryManager::ShootRay (const Ray & ray, std::vector< Mesh * > * visibleMeshes, bool isGlobalLine = false) [virtual]`

Ray shooting interface: finds an intersection with objects in the scene.

Parameters:

ray The given input ray (assuming the ray direction is normalized)

visibleMeshes List of meshes intersecting the ray

isGlobalLine If false only first intersection with opaque object is returned. Otherwise all intersections of the ray with the scene are found.

Returns:

true if there is any intersection.

3.23.3.4 `void GtpVisibility::QueryManager::SetSceneTraverser (HierarchyInterface * hierarchyInterface)`

Sets the scene traverser.

Remarks:

the scene traverser depends on the type of hierarchyInterface the scene consists of.

3.23.4 Member Data Documentation

3.23.4.1 `HierarchyInterface* GtpVisibility::QueryManager::mHierarchyInterface [protected]`

The documentation for this class was generated from the following files:

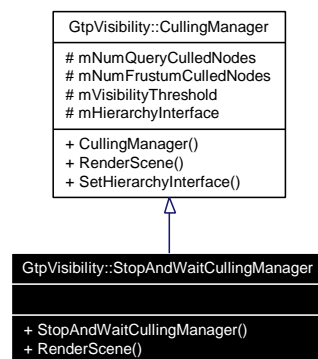
- [QueryManager.h](#)
- [QueryManager.cpp](#)

3.24 GtpVisibility::StopAndWaitCullingManager Class Reference

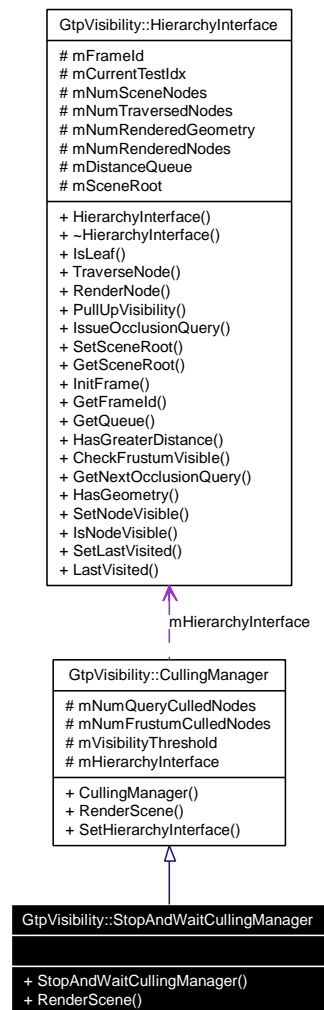
```
#include <GtpVisibility/include/StopAndWaitCullingManager.h>
```

Inherits [GtpVisibility::CullingManager](#).

Inheritance diagram for GtpVisibility::StopAndWaitCullingManager:



Collaboration diagram for GtpVisibility::StopAndWaitCullingManager:



Public Member Functions

- `StopAndWaitCullingManager` (`HierarchyInterface *hierarchyInterface`)
- `void RenderScene ()`

3.24.1 Detailed Description

Renders the scene with the hierarchical stop and wait algorithm.

3.24.2 Constructor & Destructor Documentation

3.24.2.1 GtpVisibility::StopAndWaitCullingManager::StopAndWaitCullingManager (HierarchyInterface * hierarchyInterface)

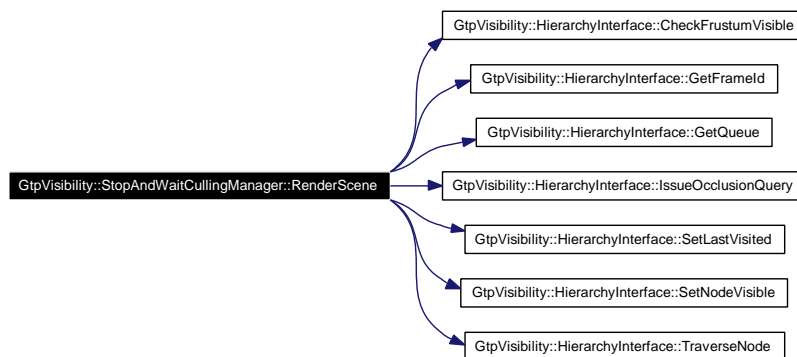
3.24.3 Member Function Documentation

3.24.3.1 void GtpVisibility::StopAndWaitCullingManager::RenderScene () [virtual]

Renders the scene using a specific occlusion culling algorithm, e.g., coherent hierarchical culling or stop and wait.

Implements [GtpVisibility::CullingManager](#).

Here is the call graph for this function:



The documentation for this class was generated from the following files:

- [StopAndWaitCullingManager.h](#)
- [StopAndWaitCullingManager.cpp](#)

3.25 GtpVisibility::VisibilityEnvironment Class Reference

```
#include <GtpVisibility/include/VisibilityEnvironment.h>
```

Public Types

- enum [CullingManagerType](#) { [FRUSTUM_CULLING](#), [STOP_AND_WAIT](#), [COHERENT_HIERARCHICAL_CULLING](#) }

Public Member Functions

- [VisibilityEnvironment](#) ()
- void [LoadEnvironment](#) ()

3.25.1 Detailed Description

This class provides different parameters for the visibility manager.

3.25.2 Member Enumeration Documentation

3.25.2.1 enum [GtpVisibility::VisibilityEnvironment::CullingManagerType](#)

Different types of occlusion culling algorithms

Enumeration values:

FRUSTUM_CULLING

STOP_AND_WAIT

COHERENT_HIERARCHICAL_CULLING

3.25.3 Constructor & Destructor Documentation

3.25.3.1 [GtpVisibility::VisibilityEnvironment::VisibilityEnvironment](#) ()

3.25.4 Member Function Documentation

3.25.4.1 void [GtpVisibility::VisibilityEnvironment::LoadEnvironment](#) ()

Loads an environment from disk.

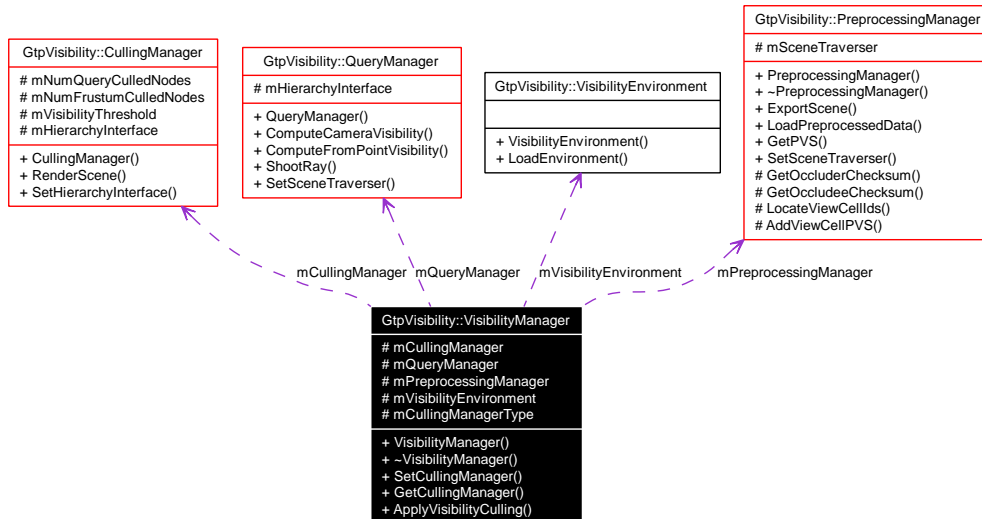
The documentation for this class was generated from the following files:

- [VisibilityEnvironment.h](#)
- [VisibilityEnvironment.cpp](#)

3.26 GtpVisibility::VisibilityManager Class Reference

```
#include <GtpVisibility/include/VisibilityManager.h>
```

Collaboration diagram for GtpVisibility::VisibilityManager:



Public Member Functions

- [VisibilityManager \(VisibilityEnvironment *visEnvironment\)](#)
- [~VisibilityManager \(\)](#)
- void [SetCullingManager \(VisibilityEnvironment::CullingManagerType ocmType\)](#)
- [CullingManager * GetCullingManager \(\)](#)
- void [ApplyVisibilityCulling \(\)](#)

Protected Attributes

- [CullingManager * mCullingManager](#)
- [QueryManager * mQueryManager](#)
- [PreprocessingManager * mPreprocessingManager](#)
- [VisibilityEnvironment * mVisibilityEnvironment](#)
- [VisibilityEnvironment::CullingManagerType mCullingManagerType](#)

3.26.1 Detailed Description

This class manages all forms of visibility. It is the main class of our visibility module and manages online occlusion culling, offline culling, and visibility queries.

3.26.2 Constructor & Destructor Documentation

3.26.2.1 GtpVisibility::VisibilityManager::VisibilityManager ([VisibilityEnvironment](#) * *visEnvironment*)

Constructor taking the visibility environment object as parameter

Parameters:

visEnvironment the visibility environment

3.26.2.2 GtpVisibility::VisibilityManager::~~VisibilityManager ()

3.26.3 Member Function Documentation

3.26.3.1 void GtpVisibility::VisibilityManager::SetCullingManager (VisibilityEnvironment::CullingManagerType *ocmType*)

Sets the current online occlusion culling manager, e.g., the stop and wait algorithm or coherent hierarchical culling.

Parameters:

ocmType the online occlusion culling manager type

3.26.3.2 CullingManager * GtpVisibility::VisibilityManager::GetCullingManager ()

Returns the current online occlusion culling manager. See set

3.26.3.3 void GtpVisibility::VisibilityManager::ApplyVisibilityCulling ()

Applies the online visibility culling algorithm on a scene.

Remarks:

the algorithm depends on the current culling manager.

Here is the call graph for this function:



3.26.4 Member Data Documentation

3.26.4.1 CullingManager* GtpVisibility::VisibilityManager::mCullingManager [protected]

3.26.4.2 QueryManager* GtpVisibility::VisibilityManager::mQueryManager [protected]

3.26.4.3 PreprocessingManager* GtpVisibility::VisibilityManager::mPreprocessingManager [protected]

3.26.4.4 VisibilityEnvironment* GtpVisibility::VisibilityManager::mVisibilityEnvironment [protected]

3.26.4.5 VisibilityEnvironment::CullingManagerType GtpVisibility::VisibilityManager::mCullingManagerType [protected]

The documentation for this class was generated from the following files:

- [VisibilityManager.h](#)
- [VisibilityManager.cpp](#)

3.27 GtpVisibilityPreprocessor::AxisAlignedBox3 Class Reference

```
#include <GtpVisibilityPreprocessor/include/AxisAlignedBox3.h>
```

Protected Attributes

- [Vector3 min](#)
- [Vector3 max](#)

3.27.1 Detailed Description

Axis aligned box

3.27.2 Member Data Documentation

3.27.2.1 [Vector3 GtpVisibilityPreprocessor::AxisAlignedBox3::min](#) [protected]

3.27.2.2 [Vector3 GtpVisibilityPreprocessor::AxisAlignedBox3::max](#) [protected]

The documentation for this class was generated from the following file:

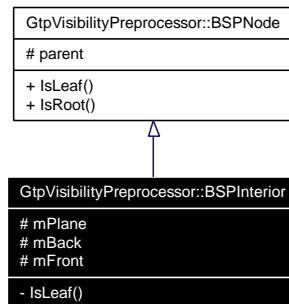
- [AxisAlignedBox3.h](#)

3.28 GtpVisibilityPreprocessor::BSPInterior Class Reference

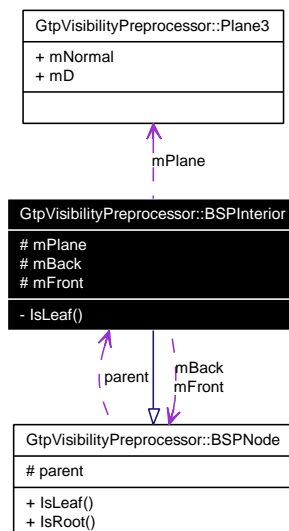
```
#include <GtpVisibilityPreprocessor/include/ViewCellBSP.h>
```

Inherits [GtpVisibilityPreprocessor::BSPNode](#).

Inheritance diagram for GtpVisibilityPreprocessor::BSPInterior:



Collaboration diagram for GtpVisibilityPreprocessor::BSPInterior:



Protected Attributes

- [Plane3 mPlane](#)
Splitting plane corresponding to this node.
- [BSPNode * mBack](#)
back node
- [BSPNode * mFront](#)
front node

Private Member Functions

- virtual bool [IsLeaf](#) () const

3.28.1 Detailed Description

BSP interior node implementation

3.28.2 Member Function Documentation

3.28.2.1 virtual bool [GtpVisibilityPreprocessor::BSPInterior::IsLeaf](#) () const [inline, private, virtual]

Returns:

false since it is an interior node

Implements [GtpVisibilityPreprocessor::BSPNode](#).

3.28.3 Member Data Documentation

3.28.3.1 [Plane3](#) [GtpVisibilityPreprocessor::BSPInterior::mPlane](#) [protected]

Splitting plane corresponding to this node.

3.28.3.2 [BSPNode*](#) [GtpVisibilityPreprocessor::BSPInterior::mBack](#) [protected]

back node

3.28.3.3 [BSPNode*](#) [GtpVisibilityPreprocessor::BSPInterior::mFront](#) [protected]

front node

The documentation for this class was generated from the following file:

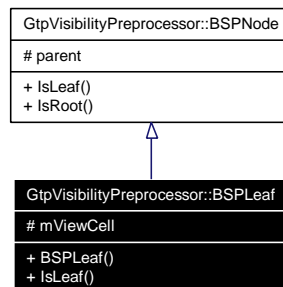
- [ViewCellBSP.h](#)

3.29 GtpVisibilityPreprocessor::BSPLeaf Class Reference

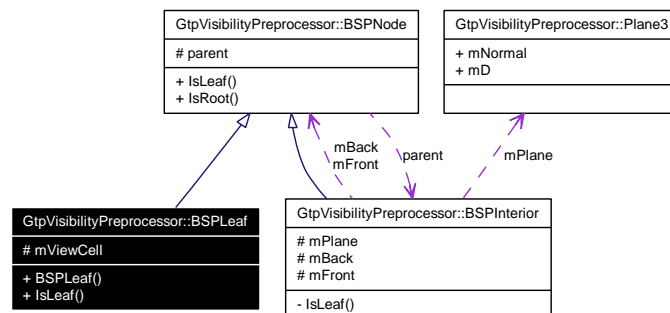
```
#include <GtpVisibilityPreprocessor/include/ViewCellBSP.h>
```

Inherits [GtpVisibilityPreprocessor::BSPNode](#).

Inheritance diagram for GtpVisibilityPreprocessor::BSPLeaf:



Collaboration diagram for GtpVisibilityPreprocessor::BSPLeaf:



Public Member Functions

- `BSPLeaf` (`ViewCell *viewCell=NULL`)
- virtual bool `IsLeaf` () const

Protected Attributes

- `ViewCell * mViewCell`

3.29.1 Detailed Description

BSP leaf node implementation

3.29.2 Constructor & Destructor Documentation

3.29.2.1 `GtpVisibilityPreprocessor::BSPLeaf::BSPLeaf (ViewCell * viewCell = NULL)`
[inline]

3.29.3 Member Function Documentation

3.29.3.1 `virtual bool GtpVisibilityPreprocessor::BSPLeaf::IsLeaf () const` [inline, virtual]

Returns:

true since it is an interior node

Implements [GtpVisibilityPreprocessor::BSPNode](#).

3.29.4 Member Data Documentation

3.29.4.1 `ViewCell* GtpVisibilityPreprocessor::BSPLeaf::mViewCell` [protected]

polygonal representation of this viewcell if NULL this note does not correspond to feasible viewcell

The documentation for this class was generated from the following file:

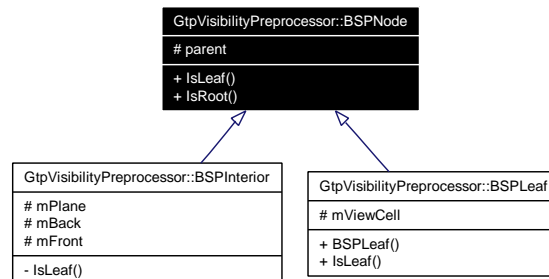
- [ViewCellBSP.h](#)

3.30 GtpVisibilityPreprocessor::BSPNode Class Reference

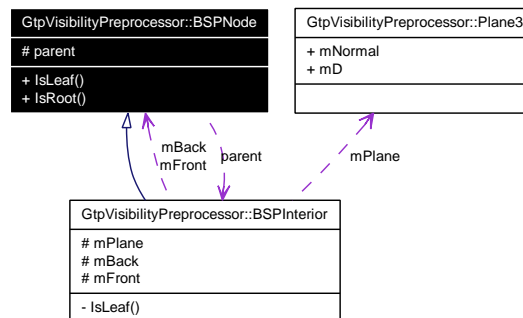
```
#include <GtpVisibilityPreprocessor/include/ViewCellBSP.h>
```

Inherited by [GtpVisibilityPreprocessor::BSPInterior](#), and [GtpVisibilityPreprocessor::BSPLeaf](#).

Inheritance diagram for GtpVisibilityPreprocessor::BSPNode:



Collaboration diagram for GtpVisibilityPreprocessor::BSPNode:



Public Member Functions

- virtual bool [IsLeaf](#) () const =0
- virtual bool [IsRoot](#) () const

Protected Attributes

- [BSPInterior](#) * *parent*
parent of this node

3.30.1 Detailed Description

[BSPNode](#) abstract class serving for interior and leaf node implementation

3.30.2 Member Function Documentation

3.30.2.1 `virtual bool GtpVisibilityPreprocessor::BSPNode::IsLeaf () const` [pure virtual]

Determines whether this node is a leaf or not

Returns:

true if leaf

Implemented in [GtpVisibilityPreprocessor::BSPInterior](#), and [GtpVisibilityPreprocessor::BSPLeaf](#).

3.30.2.2 `virtual bool GtpVisibilityPreprocessor::BSPNode::IsRoot () const` [inline, virtual]

Determines whether this node is a root

Returns:

true if root

3.30.3 Member Data Documentation

3.30.3.1 `BSPInterior* GtpVisibilityPreprocessor::BSPNode::parent` [protected]

parent of this node

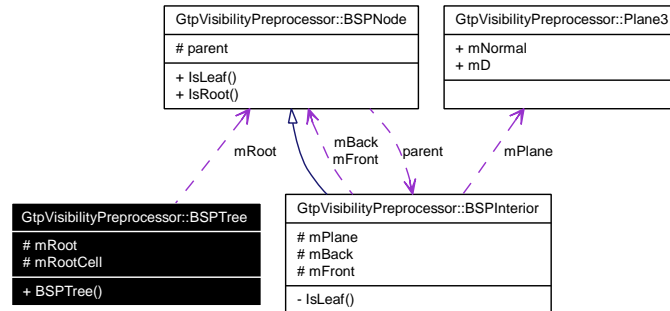
The documentation for this class was generated from the following file:

- [ViewCellBSP.h](#)

3.31 GtpVisibilityPreprocessor::BSPTree Class Reference

```
#include <GtpVisibilityPreprocessor/include/ViewCellBSP.h>
```

Collaboration diagram for GtpVisibilityPreprocessor::BSPTree:



Public Member Functions

- [BSPTree](#) (ViewCell *cell)

Protected Attributes

- [BSPNode](#) * [mRoot](#)
Pointer to the root of the tree.
- ViewCell * [mRootCell](#)
*Pointer to the root cell of the viewspace */.*

3.31.1 Detailed Description

Implementation of the ViewCell BSP tree

3.31.2 Constructor & Destructor Documentation

3.31.2.1 GtpVisibilityPreprocessor::BSPTree::BSPTree (ViewCell * cell) [inline]

Constructor takes a pointer to the cell corresponding to the whole viewspace

3.31.3 Member Data Documentation

3.31.3.1 [BSPNode](#)* [GtpVisibilityPreprocessor::BSPTree::mRoot](#) [protected]

Pointer to the root of the tree.

3.31.3.2 ViewCell* [GtpVisibilityPreprocessor::BSPTree::mRootCell](#) [protected]

Pointer to the root cell of the viewspace */.

The documentation for this class was generated from the following file:

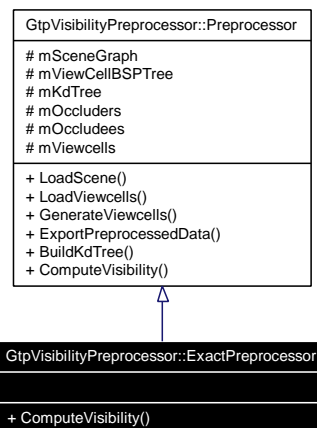
- [ViewCellBSP.h](#)

3.32 GtpVisibilityPreprocessor::ExactPreprocessor Class Reference

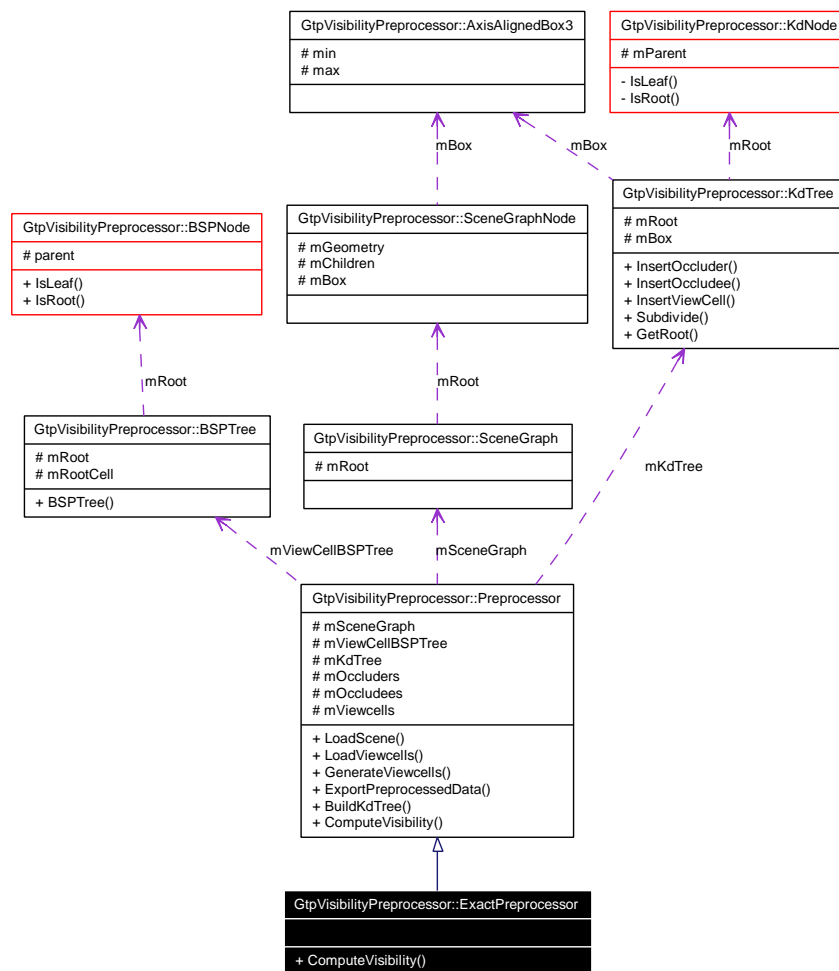
```
#include <GtpVisibilityPreprocessor/include/ExactPreprocessor.h>
```

Inherits [GtpVisibilityPreprocessor::Preprocessor](#).

Inheritance diagram for GtpVisibilityPreprocessor::ExactPreprocessor:



Collaboration diagram for GtpVisibilityPreprocessor::ExactPreprocessor:



Public Member Functions

- virtual bool [ComputeVisibility](#) ()

3.32.1 Detailed Description

Exact visibility preprocessing. The implementation is based on 6D BSP and Plucker coordinates

3.32.2 Member Function Documentation

3.32.2.1 bool GtpVisibilityPreprocessor::ExactPreprocessor::ComputeVisibility () [virtual]

Compute visibility method. This method has to be reimplemented by the actual [Preprocessor](#) implementation (e.g. [SamplingPreprocessor](#), [ExactPreprocessor](#), [GlobalSamplingpreprocessor](#))

Implements [GtpVisibilityPreprocessor::Preprocessor](#).

The documentation for this class was generated from the following files:

- [ExactPreprocessor.h](#)

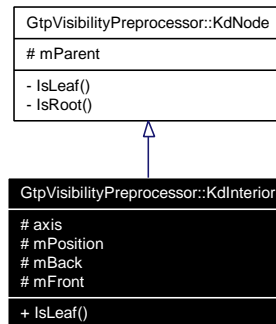
- [ExactPreprocessor.cpp](#)

3.33 GtpVisibilityPreprocessor::KdInterior Class Reference

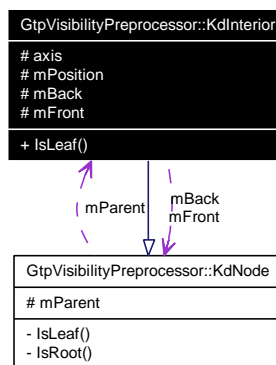
```
#include <GtpVisibilityPreprocessor/include/KdTree.h>
```

Inherits [GtpVisibilityPreprocessor::KdNode](#).

Inheritance diagram for GtpVisibilityPreprocessor::KdInterior:



Collaboration diagram for GtpVisibilityPreprocessor::KdInterior:



Public Member Functions

- virtual bool [IsLeaf](#) () const

Protected Attributes

- int [axis](#)
- float [mPosition](#)
- [KdNode](#) * [mBack](#)
- [KdNode](#) * [mFront](#)

3.33.1 Detailed Description

Implementation of the kd-tree interior node

3.33.2 Member Function Documentation

3.33.2.1 `virtual bool GtpVisibilityPreprocessor::KdInterior::IsLeaf () const` [`inline`, `virtual`]

See also:

[KdNode::IsLeaf\(\)](#)

Implements [GtpVisibilityPreprocessor::KdNode](#).

3.33.3 Member Data Documentation

3.33.3.1 `int GtpVisibilityPreprocessor::KdInterior::axis` [`protected`]

splitting axis

3.33.3.2 `float GtpVisibilityPreprocessor::KdInterior::mPosition` [`protected`]

splitting position, absolute position within the bounding box of this node

3.33.3.3 `KdNode* GtpVisibilityPreprocessor::KdInterior::mBack` [`protected`]

back node

3.33.3.4 `KdNode* GtpVisibilityPreprocessor::KdInterior::mFront` [`protected`]

front node

The documentation for this class was generated from the following file:

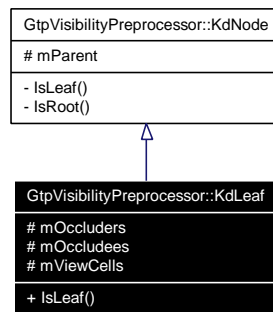
- [KdTree.h](#)

3.34 GtpVisibilityPreprocessor::KdLeaf Class Reference

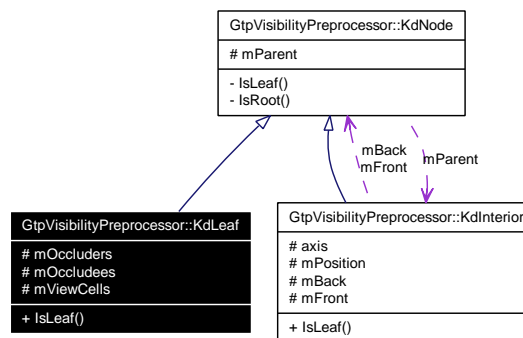
```
#include <GtpVisibilityPreprocessor/include/KdTree.h>
```

Inherits [GtpVisibilityPreprocessor::KdNode](#).

Inheritance diagram for GtpVisibilityPreprocessor::KdLeaf:



Collaboration diagram for GtpVisibilityPreprocessor::KdLeaf:



Public Member Functions

- virtual bool [IsLeaf](#) () const

Protected Attributes

- [MeshContainer](#) `mOccluders`
- [MeshContainer](#) `mOccludees`
- [ViewCellContainer](#) `mViewCells`

3.34.1 Detailed Description

Implementation of the kd-tree leaf node

3.34.2 Member Function Documentation

3.34.2.1 `virtual bool GtpVisibilityPreprocessor::KdLeaf::IsLeaf () const` [inline, virtual]

See also:

[KdNode::IsLeaf\(\)](#)

Implements [GtpVisibilityPreprocessor::KdNode](#).

3.34.3 Member Data Documentation

3.34.3.1 `MeshContainer GtpVisibilityPreprocessor::KdLeaf::mOccluders` [protected]

pointers to occluders contained in this node

3.34.3.2 `MeshContainer GtpVisibilityPreprocessor::KdLeaf::mOccludees` [protected]

pointers to occludees contained in this node

3.34.3.3 `ViewCellContainer GtpVisibilityPreprocessor::KdLeaf::mViewCells` [protected]

pointers to viewcells contained in this node

The documentation for this class was generated from the following file:

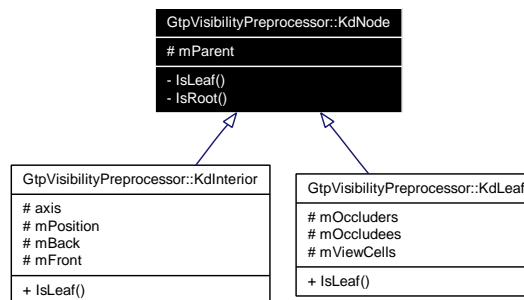
- [KdTree.h](#)

3.35 GtpVisibilityPreprocessor::KdNode Class Reference

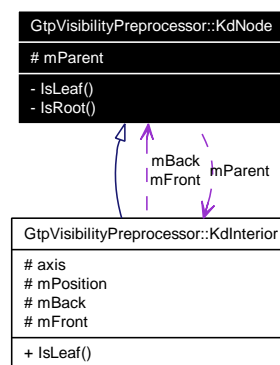
```
#include <GtpVisibilityPreprocessor/include/KdTree.h>
```

Inherited by [GtpVisibilityPreprocessor::KdInterior](#), and [GtpVisibilityPreprocessor::KdLeaf](#).

Inheritance diagram for GtpVisibilityPreprocessor::KdNode:



Collaboration diagram for GtpVisibilityPreprocessor::KdNode:



Protected Attributes

- [KdInterior](#) * `mParent`

Private Member Functions

- virtual bool `IsLeaf()` const =0
- virtual bool `IsRoot()` const

3.35.1 Detailed Description

Abstract class for kd-tree node

3.35.2 Member Function Documentation

3.35.2.1 `virtual bool GtpVisibilityPreprocessor::KdNode::IsLeaf () const` [private, pure virtual]

Determines whether this node is a leaf or interior node

Returns:

true if leaf

Implemented in [GtpVisibilityPreprocessor::KdInterior](#), and [GtpVisibilityPreprocessor::KdLeaf](#).

3.35.2.2 `virtual bool GtpVisibilityPreprocessor::KdNode::IsRoot () const` [inline, private, virtual]

Determines whether this node is the root of the tree

Returns:

true if root

3.35.3 Member Data Documentation

3.35.3.1 `KdInterior* GtpVisibilityPreprocessor::KdNode::mParent` [protected]

Parent of the node - the parent is a little overhead for maintenance of the tree, but allows various optimizations of tree traversal algorithms

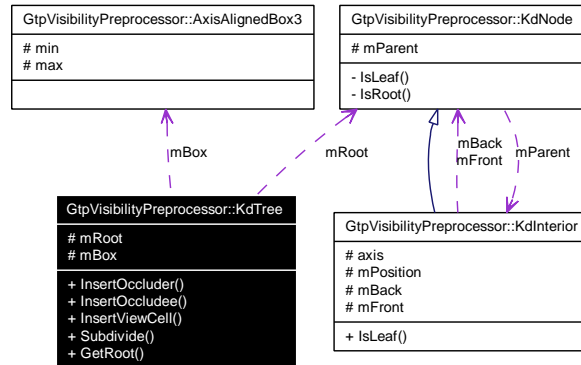
The documentation for this class was generated from the following file:

- [KdTree.h](#)

3.36 GtpVisibilityPreprocessor::KdTree Class Reference

```
#include <GtpVisibilityPreprocessor/include/KdTree.h>
```

Collaboration diagram for GtpVisibilityPreprocessor::KdTree:



Public Member Functions

- virtual void [InsertOccluder](#) ([Mesh](#) *occluder)
- virtual void [InsertOccludee](#) ([Mesh](#) *occludee)
- virtual void [InsertViewCell](#) ([ViewCell](#) *viewCell)
- virtual bool [Subdivide](#) ([KdNode](#) *subtree)
- [KdNode](#) * [GetRoot](#) () const

Protected Attributes

- [KdNode](#) * [mRoot](#)
root of the tree
- [AxisAlignedBox3](#) [mBox](#)
bounding box of the tree root

3.36.1 Detailed Description

[KdTree](#) for indexing scene entities - occluders/occludees/viewcells

3.36.2 Member Function Documentation

3.36.2.1 virtual void GtpVisibilityPreprocessor::KdTree::InsertOccluder ([Mesh](#) * occluder) [inline, virtual]

Insert occluder into the tree

3.36.2.2 `virtual void GtpVisibilityPreprocessor::KdTree::InsertOccludee (Mesh * occludee)`
[inline, virtual]

Insert occludee into the tree

3.36.2.3 `virtual void GtpVisibilityPreprocessor::KdTree::InsertViewCell (ViewCell * viewCell)`
[inline, virtual]

Insert view cell into the tree

3.36.2.4 `bool GtpVisibilityPreprocessor::KdTree::Subdivide (KdNode * subtree)` [virtual]

Check whether subdivision criteria are met for the given subtree. If not subdivide the leafs of the subtree. The criteria are specified in the environment as well as the subdivision method. By default surface area heuristics is used.

Parameters:

subtree root of the subtree

Returns:

true if subdivision was performed, false if subdivision criteria were already met

3.36.2.5 `KdNode* GtpVisibilityPreprocessor::KdTree::GetRoot () const` [inline]

Get the root of the tree

3.36.3 Member Data Documentation

3.36.3.1 `KdNode* GtpVisibilityPreprocessor::KdTree::mRoot` [protected]

root of the tree

3.36.3.2 `AxisAlignedBox3 GtpVisibilityPreprocessor::KdTree::mBox` [protected]

bounding box of the tree root

The documentation for this class was generated from the following files:

- [KdTree.h](#)
- [KdTree.cpp](#)

3.37 GtpVisibilityPreprocessor::Mesh Class Reference

```
#include <GtpVisibilityPreprocessor/include/Mesh.h>
```

Public Types

- typedef std::vector< [Vector3](#) > [VertexContainer](#)
default vertex container for [Mesh](#)
- typedef std::vector< [Patch *](#) > [PatchContainer](#)
default patch container for [Mesh](#)

Public Member Functions

- [Mesh](#) ()
Default constructor.
- [Mesh](#) (const int vertices, const int patches)
Constructor with container preallocation.

Protected Attributes

- [VertexContainer](#) mVertices
- [PatchContainer](#) mPatches

3.37.1 Detailed Description

[Mesh](#) containing polygonal patches

3.37.2 Member Typedef Documentation

3.37.2.1 typedef std::vector<[Vector3](#)> [GtpVisibilityPreprocessor::Mesh::VertexContainer](#)

default vertex container for [Mesh](#)

3.37.2.2 typedef std::vector<[Patch *](#)> [GtpVisibilityPreprocessor::Mesh::PatchContainer](#)

default patch container for [Mesh](#)

3.37.3 Constructor & Destructor Documentation

3.37.3.1 [GtpVisibilityPreprocessor::Mesh::Mesh](#) () [inline]

Default constructor.

3.37.3.2 `GtpVisibilityPreprocessor::Mesh::Mesh (const int vertices, const int patches)` [inline]

Constructor with container preallocation.

3.37.4 Member Data Documentation

3.37.4.1 `VertexContainer GtpVisibilityPreprocessor::Mesh::mVertices` [protected]

Vertices forming the mesh

3.37.4.2 `PatchContainer GtpVisibilityPreprocessor::Mesh::mPatches` [protected]

Patches forming the mesh

The documentation for this class was generated from the following file:

- [Mesh.h](#)

3.38 GtpVisibilityPreprocessor::Patch Class Reference

```
#include <GtpVisibilityPreprocessor/include/Mesh.h>
```

Public Member Functions

- [Patch \(\)](#)

Protected Attributes

- `vector< Vector3 * > mVertices`
list of vertex pointers

3.38.1 Detailed Description

[Patch](#) used as an element of the mesh

3.38.2 Constructor & Destructor Documentation

3.38.2.1 [GtpVisibilityPreprocessor::Patch::Patch \(\)](#) [inline]

3.38.3 Member Data Documentation

3.38.3.1 `vector<Vector3 * > GtpVisibilityPreprocessor::Patch::mVertices` [protected]

list of vertex pointers

The documentation for this class was generated from the following file:

- [Mesh.h](#)

3.39 GtpVisibilityPreprocessor::Plane3 Class Reference

```
#include <GtpVisibilityPreprocessor/include/Plane3.h>
```

Public Attributes

- [Vector3 mNormal](#)
- [float mD](#)

3.39.1 Detailed Description

3D Plane

3.39.2 Member Data Documentation

3.39.2.1 [Vector3 GtpVisibilityPreprocessor::Plane3::mNormal](#)

3.39.2.2 [float GtpVisibilityPreprocessor::Plane3::mD](#)

The documentation for this class was generated from the following file:

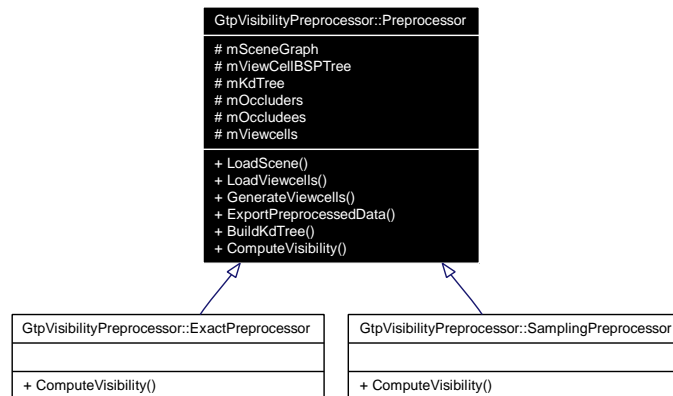
- [Plane3.h](#)

3.40 GtpVisibilityPreprocessor::Preprocessor Class Reference

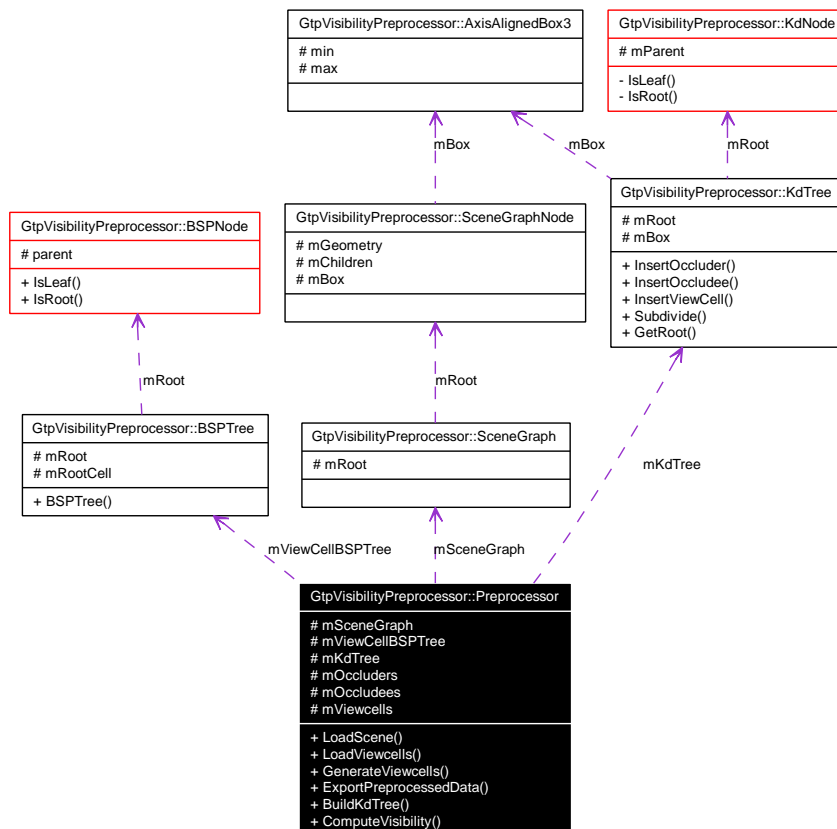
```
#include <GtpVisibilityPreprocessor/include/Preprocessor.h>
```

Inherited by [GtpVisibilityPreprocessor::ExactPreprocessor](#), and [GtpVisibilityPreprocessor::SamplingPreprocessor](#).

Inheritance diagram for GtpVisibilityPreprocessor::Preprocessor:



Collaboration diagram for GtpVisibilityPreprocessor::Preprocessor:



Public Member Functions

- virtual bool [LoadScene](#) (const string filename)
- virtual bool [LoadViewcells](#) (const string filename)
- virtual bool [GenerateViewcells](#) ()
- virtual bool [ExportPreprocessedData](#) (const string filename)
- virtual bool [BuildKdTree](#) ()
- virtual bool [ComputeVisibility](#) ()=0

Protected Attributes

- [SceneGraph](#) * [mSceneGraph](#)
scene graph loaded from file
- [BSPTree](#) * [mViewCellBSPTree](#)
BSP tree representing the viewcells.
- [KdTree](#) * [mKdTree](#)
kD-tree organizing the scene graph (occluders + occludees) + viewcells
- [MeshContainer](#) [mOccluders](#)
list of all loaded occluders
- [MeshContainer](#) [mOccludees](#)
list of all loaded occludees
- [ViewCellContainer](#) [mViewcells](#)
list of all loaded/generated viewcells

3.40.1 Detailed Description

Main class of the visibility preprocessor. Responsible for loading and saving of the input and output files. Initiates construction of the kD-tree, viewcell loading/generation and the visibility computation itself.

3.40.2 Member Function Documentation

3.40.2.1 bool [GtpVisibilityPreprocessor::Preprocessor::LoadScene](#) (const string *filename*) [virtual]

Load the input scene.

Parameters:

filename file to load

Returns:

true on success

3.40.2.2 `bool GtpVisibilityPreprocessor::Preprocessor::LoadViewcells (const string filename)` `[virtual]`

Load the input viewcells. The input viewcells should be given as a collection of meshes. Each mesh is assume to form a bounded polyhedron defining the interior of the viewcell. The method then builds a BSP tree of these view cells.

Parameters:

filename file to load

Returns:

true on success

3.40.2.3 `bool GtpVisibilityPreprocessor::Preprocessor::GenerateViewcells ()` `[virtual]`

Generate the viewCells automatically. The particular algorithm to be used depends on the environment setting. Initially the generated viewcells will cover the whole bounding volume of the scene. They can be pruned later depending on the results of visibility computations.

Returns:

true on successful viewcell generation.

3.40.2.4 `bool GtpVisibilityPreprocessor::Preprocessor::ExportPreprocessedData (const string filename)` `[virtual]`

Export all preprocessed data in a XML format understandable by the PreprocessingInterface of the [Gtp-VisibilityPreprocessor](#) Module. The file can be compressed depending on the environment settings.

Returns:

true on successful export

3.40.2.5 `bool GtpVisibilityPreprocessor::Preprocessor::BuildKdTree ()` `[virtual]`

Build the [KdTree](#) of currently loaded occluders/occludees/viewcells. The construction is driven by the environment settings, which also sais which of the three types of entities should be used to drive the heuristical construction (only occluders by default)

Here is the call graph for this function:



3.40.2.6 `virtual bool GtpVisibilityPreprocessor::Preprocessor::ComputeVisibility ()` `[pure virtual]`

Compute visibility method. This method has to be reimplemented by the actual [Preprocessor](#) implementation (e.g. [SamplingPreprocessor](#), [ExactPreprocessor](#), [GlobalSamplingpreprocessor](#))

Implemented in [GtpVisibilityPreprocessor::ExactPreprocessor](#), and [GtpVisibilityPreprocessor::Sampling-Preprocessor](#).

3.40.3 Member Data Documentation

3.40.3.1 [SceneGraph*](#) [GtpVisibilityPreprocessor::Preprocessor::mSceneGraph](#) [protected]

scene graph loaded from file

3.40.3.2 [BSPTree*](#) [GtpVisibilityPreprocessor::Preprocessor::mViewCellBSPTree](#) [protected]

BSP tree representing the viewcells.

3.40.3.3 [KdTree*](#) [GtpVisibilityPreprocessor::Preprocessor::mKdTree](#) [protected]

kD-tree organizing the scene graph (occluders + occludees) + viewcells

3.40.3.4 [MeshContainer](#) [GtpVisibilityPreprocessor::Preprocessor::mOccluders](#) [protected]

list of all loaded occluders

3.40.3.5 [MeshContainer](#) [GtpVisibilityPreprocessor::Preprocessor::mOccludees](#) [protected]

list of all loaded occludees

3.40.3.6 [ViewCellContainer](#) [GtpVisibilityPreprocessor::Preprocessor::mViewcells](#) [protected]

list of all loaded/generated viewcells

The documentation for this class was generated from the following files:

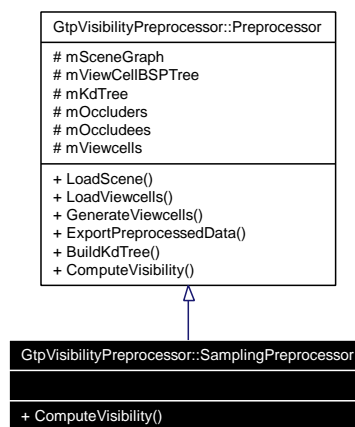
- [Preprocessor.h](#)
- [Preprocessor.cpp](#)

3.41 GtpVisibilityPreprocessor::SamplingPreprocessor Class Reference

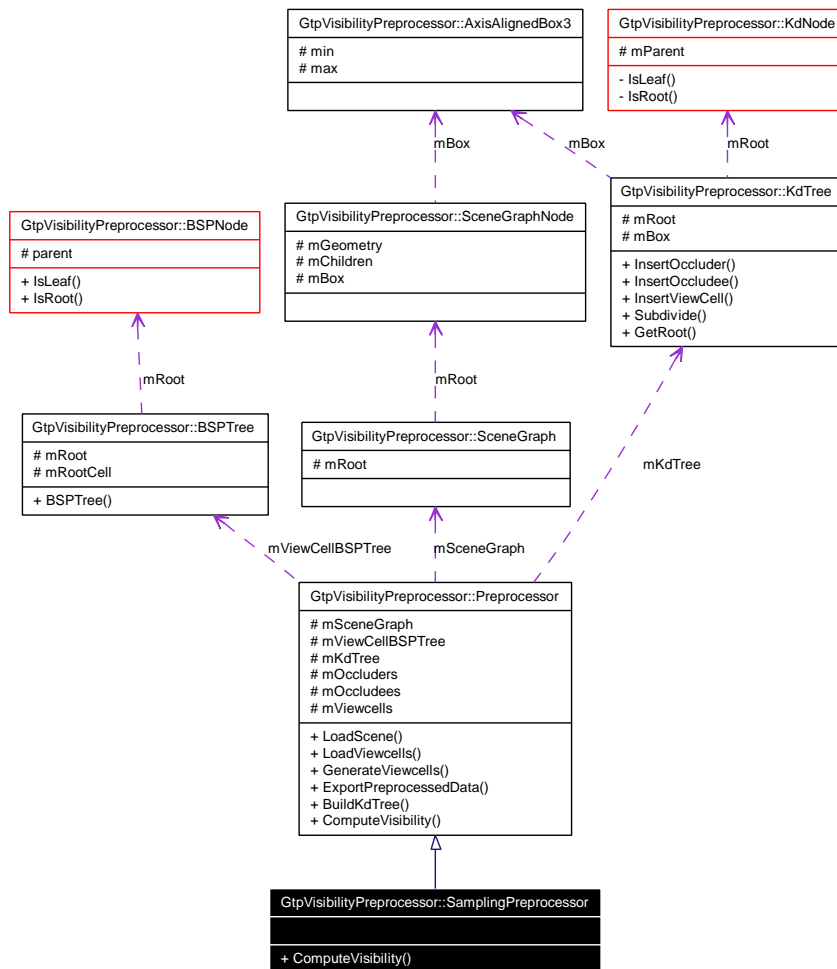
```
#include <GtpVisibilityPreprocessor/include/SamplingPreprocessor.h>
```

Inherits [GtpVisibilityPreprocessor::Preprocessor](#).

Inheritance diagram for GtpVisibilityPreprocessor::SamplingPreprocessor:



Collaboration diagram for GtpVisibilityPreprocessor::SamplingPreprocessor:



Public Member Functions

- virtual bool [ComputeVisibility](#) ()

3.41.1 Detailed Description

Sampling based visibility preprocessing. The implementation is based on heuristical sampling of view space

3.41.2 Member Function Documentation

3.41.2.1 bool [GtpVisibilityPreprocessor::SamplingPreprocessor::ComputeVisibility](#) () [virtual]

Compute visibility method. This method has to be reimplemented by the actual [Preprocessor](#) implementation (e.g. [SamplingPreprocessor](#), [ExactPreprocessor](#), [GlobalSamplingpreprocessor](#))

Implements [GtpVisibilityPreprocessor::Preprocessor](#).

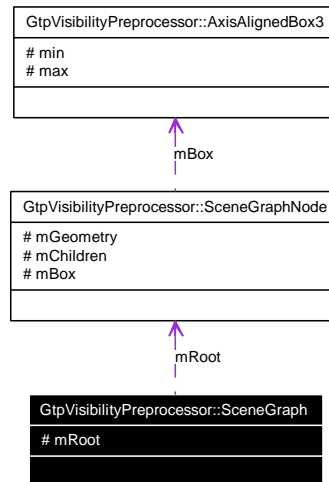
The documentation for this class was generated from the following files:

- [SamplingPreprocessor.h](#)
- [SamplingPreprocessor.cpp](#)

3.42 GtpVisibilityPreprocessor::SceneGraph Class Reference

```
#include <GtpVisibilityPreprocessor/include/SceneGraph.h>
```

Collaboration diagram for GtpVisibilityPreprocessor::SceneGraph:



Protected Attributes

- [SceneGraphNode](#) * [mRoot](#)

3.42.1 Detailed Description

Scene graph class

3.42.2 Member Data Documentation

3.42.2.1 [SceneGraphNode](#)* [GtpVisibilityPreprocessor::SceneGraph::mRoot](#) [protected]

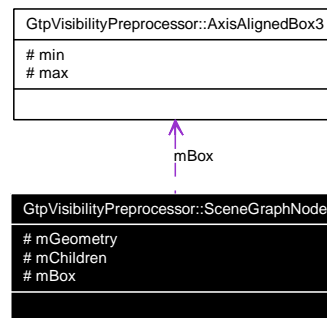
The documentation for this class was generated from the following file:

- [SceneGraph.h](#)

3.43 GtpVisibilityPreprocessor::SceneGraphNode Class Reference

```
#include <GtpVisibilityPreprocessor/include/SceneGraph.h>
```

Collaboration diagram for GtpVisibilityPreprocessor::SceneGraphNode:



Protected Attributes

- [MeshContainer](#) `mGeometry`
- [NodeContainer](#) `mChildren`
- [AxisAlignedBox3](#) `mBox`

3.43.1 Detailed Description

Basic scene graph node, we are interested only in bounding boxes and topology of the scene graph

3.43.2 Member Data Documentation

3.43.2.1 [MeshContainer](#) `GtpVisibilityPreprocessor::SceneGraphNode::mGeometry`
[protected]

3.43.2.2 [NodeContainer](#) `GtpVisibilityPreprocessor::SceneGraphNode::mChildren`
[protected]

3.43.2.3 [AxisAlignedBox3](#) `GtpVisibilityPreprocessor::SceneGraphNode::mBox` [protected]

The documentation for this class was generated from the following file:

- [SceneGraph.h](#)

3.44 GtpVisibilityPreprocessor::Vector3 Class Reference

```
#include <GtpVisibilityPreprocessor/include/Vector3.h>
```

Public Attributes

- float [x](#)
- float [y](#)
- float [z](#)

3.44.1 Detailed Description

3D vector

3.44.2 Member Data Documentation

3.44.2.1 float [GtpVisibilityPreprocessor::Vector3::x](#)

3.44.2.2 float [GtpVisibilityPreprocessor::Vector3::y](#)

3.44.2.3 float [GtpVisibilityPreprocessor::Vector3::z](#)

The documentation for this class was generated from the following file:

- [Vector3.h](#)

Chapter 4

GameTools Visibility Modules Namespace Documentation

4.1 GtpVisibility Namespace Reference

Classes

- class [CoherentHierarchicalCullingManager](#)
- class [CullingManager](#)
- class [GreaterDistance](#)
- class [DummyPreprocessingManager](#)
- class [DummyQueryManager](#)
- class [FrustumCullingManager](#)
- class [HierarchyInterface](#)
- class [OcclusionQuery](#)
- class [PreprocessingManager](#)
- class [QueryManager](#)
- class [StopAndWaitCullingManager](#)
- class [VisibilityEnvironment](#)
- class [NodeInfo](#)
- class [MeshInfo](#)
- class [VisibilityManager](#)

Typedefs

- typedef std::pair< [HierarchyNode](#) *, [OcclusionQuery](#) * > [QueryPair](#)
- typedef std::queue< [QueryPair](#) > [QueryQueue](#)
- typedef void [HierarchyNode](#)
- typedef std::priority_queue< [HierarchyNode](#) *, std::vector< [HierarchyNode](#) * >, [GreaterDistance](#)< std::vector< [HierarchyNode](#) * >::value_type > > [DistanceQueue](#)
- typedef [Ogre::AxisAlignedBox](#) [AxisAlignedBox](#)
- typedef [Ogre::Camera](#) [Camera](#)
- typedef [Ogre::Mesh](#) [Mesh](#)
- typedef [Ogre::Ray](#) [Ray](#)
- typedef [Ogre::Vector3](#) [Vector3](#)

4.1.1 Detailed Description

This namespace includes all classes which are created by the VUT (Vienna University of Technology for the Visibility module of the GTP (GameTools Project) (www.gametools.org), and are not directly derived from an [Ogre](#) class.

4.1.2 Typedef Documentation

4.1.2.1 `typedef std::pair<HierarchyNode *, OcclusionQuery *> GtpVisibility::QueryPair`

4.1.2.2 `typedef std::queue<QueryPair> GtpVisibility::QueryQueue`

4.1.2.3 `typedef void GtpVisibility::HierarchyNode`

4.1.2.4 `typedef std::priority_queue<HierarchyNode *, std::vector<HierarchyNode *>, GreaterDistance<std::vector<HierarchyNode *>::value_type> > GtpVisibility::DistanceQueue`

A priority queue where closer hierarchy nodes are given a higher priority.

4.1.2.5 `typedef Ogre::AxisAlignedBox GtpVisibility::AxisAlignedBox`

This class currently uses the native [Ogre](#) `AxisAlignedBox` when compiled with the [Ogre](#) platform

4.1.2.6 `typedef Ogre::Camera GtpVisibility::Camera`

Camera class currently uses the native [Ogre](#) camera when compiled with the [Ogre](#) platform

4.1.2.7 `typedef Ogre::Mesh GtpVisibility::Mesh`

4.1.2.8 `typedef Ogre::Ray GtpVisibility::Ray`

Ray class currently uses native [Ogre](#) ray when compiled with the [Ogre](#) platform

4.1.2.9 `typedef Ogre::Vector3 GtpVisibility::Vector3`

Vector3 class currently uses the native [Ogre](#) vector when compiled with the [Ogre](#) platform

4.2 GtpVisibilityPreprocessor Namespace Reference

Classes

- class [AxisAlignedBox3](#)
- class [ExactPreprocessor](#)
- class [KdTree](#)
- class [KdNode](#)
- class [KdInterior](#)
- class [KdLeaf](#)
- class [Patch](#)
- class [Mesh](#)
- class [Plane3](#)
- class [Preprocessor](#)
- class [SamplingPreprocessor](#)
- class [SceneGraphNode](#)
- class [SceneGraph](#)
- class [Vector3](#)
- class [BSPNode](#)
- class [BSPInterior](#)
- class [BSPLeaf](#)
- class [BSPTree](#)

Typedefs

- typedef vector< [Mesh](#) * > [MeshContainer](#)
- typedef vector< [ViewCell](#) * > [ViewCellContainer](#)
- typedef vector< [HierarchyNode](#) * > [NodeContainer](#)

4.2.1 Detailed Description

Namespace for the external visibility preprocessor

This namespace includes all classes which are created by the VUT (Vienna University of Technology) for the External Visibility [Preprocessor](#) of the GTP (GameTools Project) (www.gametools.org).

4.2.2 Typedef Documentation

4.2.2.1 typedef vector<[Mesh](#) * > [GtpVisibilityPreprocessor::MeshContainer](#)

Container for [Mesh](#) pointers primarily for the use within the kDTree and BSP hierarchies

4.2.2.2 typedef vector<[ViewCell](#) * > [GtpVisibilityPreprocessor::ViewCellContainer](#)

Container for [ViewCell](#) pointers primarily for the use within the kDTree and BSP hierarchies

4.2.2.3 typedef vector<[HierarchyNode](#) * > [GtpVisibilityPreprocessor::NodeContainer](#)

Container for [HierarchyNodes](#) pointers primarily for the use within the kDTree and BSP hierarchies

4.3 Ogre Namespace Reference

Classes

- class [BspHierarchyInterface](#)
- class [OctreeHierarchyInterface](#)
- class [PlatformHierarchyInterface](#)
- class [PlatformOcclusionQuery](#)
- class [SceneNodeHierarchyInterface](#)
- class [SolidHalfBoundingBox](#)
- class [VisibilityBspSceneManager](#)
- class [VisibilityDotSceneManager](#)
- class [VisibilityOctreeSceneManager](#)
- class [VisibilitySceneManager](#)
- class [VisibilityTerrainSceneManager](#)

Functions

- void [dllStartPlugin](#) (void)
- void [dllStopPlugin](#) (void)

Variables

- OcclusionCullingOctreeSceneManager * [cullingOctreePlugin](#)
- OcclusionCullingTerrainSceneManager * [cullingTerrainPlugin](#)
- HeightmapTerrainPageSource * [heightmapTerrainPageSource](#)

4.3.1 Function Documentation

4.3.1.1 void [Ogre::dllStartPlugin](#) (void)

4.3.1.2 void [Ogre::dllStopPlugin](#) (void)

4.3.2 Variable Documentation

4.3.2.1 OcclusionCullingOctreeSceneManager* [Ogre::cullingOctreePlugin](#)

4.3.2.2 OcclusionCullingTerrainSceneManager* [Ogre::cullingTerrainPlugin](#)

4.3.2.3 HeightmapTerrainPageSource* [Ogre::heightmapTerrainPageSource](#)

Chapter 5

GameTools Visibility Modules File Documentation

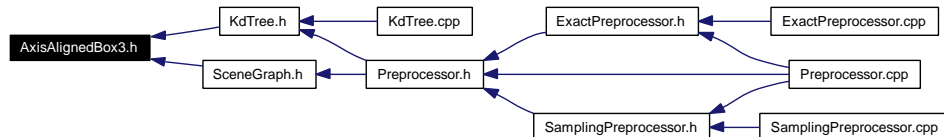
5.1 AxisAlignedBox3.h File Reference

```
#include "vector3.h"
```

Include dependency graph for AxisAlignedBox3.h:



This graph shows which files directly or indirectly include this file:



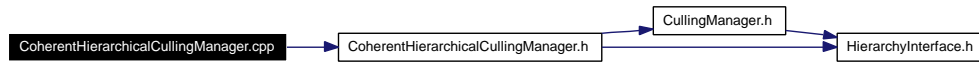
Namespaces

- namespace [GtpVisibilityPreprocessor](#)

5.2 CoherentHierarchicalCullingManager.cpp File Reference

```
#include "CoherentHierarchicalCullingManager.h"
```

Include dependency graph for CoherentHierarchicalCullingManager.cpp:



Namespaces

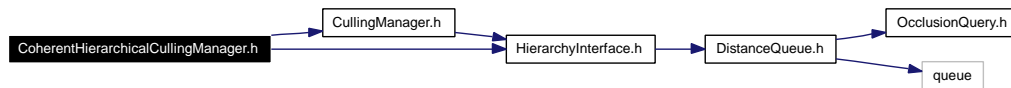
- namespace [GtpVisibility](#)

5.3 CoherentHierarchicalCullingManager.h File Reference

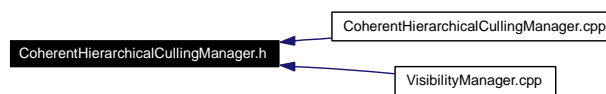
```
#include "CullingManager.h"
```

```
#include "HierarchyInterface.h"
```

Include dependency graph for CoherentHierarchicalCullingManager.h:



This graph shows which files directly or indirectly include this file:



Namespaces

- namespace [GtpVisibility](#)

Typedefs

- typedef std::pair< [HierarchyNode](#) *, [OcclusionQuery](#) * > [QueryPair](#)
- typedef std::queue< [QueryPair](#) > [QueryQueue](#)

5.3.1 Typedef Documentation

5.3.1.1 typedef std::pair<[HierarchyNode](#) *, [OcclusionQuery](#) * > [GtpVisibility::QueryPair](#)

5.3.1.2 typedef std::queue<[QueryPair](#)> [GtpVisibility::QueryQueue](#)

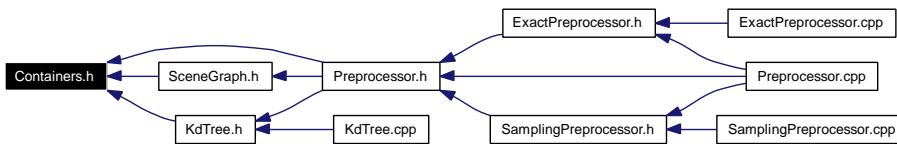
5.4 Containers.h File Reference

```
#include <vector>
```

Include dependency graph for Containers.h:



This graph shows which files directly or indirectly include this file:



Namespaces

- namespace [GtpVisibilityPreprocessor](#)

Typedefs

- typedef `vector< Mesh * >` [MeshContainer](#)
- typedef `vector< ViewCell * >` [ViewCellContainer](#)
- typedef `vector< HierarchyNode * >` [NodeContainer](#)

5.4.1 Typedef Documentation

5.4.1.1 typedef `vector<Mesh *>` [GtpVisibilityPreprocessor::MeshContainer](#)

Container for [Mesh](#) pointers primarily for the use within the kDTree and BSP hierarchies

5.4.1.2 typedef `vector<ViewCell *>` [GtpVisibilityPreprocessor::ViewCellContainer](#)

Container for [ViewCell](#) pointers primarily for the use within the kDTree and BSP hierarchies

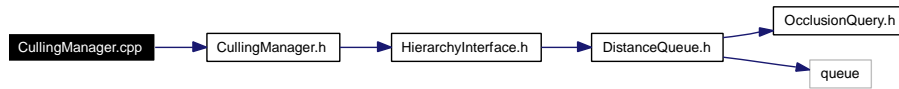
5.4.1.3 typedef `vector<HierarchyNode *>` [GtpVisibilityPreprocessor::NodeContainer](#)

Container for [HierarchyNodes](#) pointers primarily for the use within the kDTree and BSP hierarchies

5.5 CullingManager.cpp File Reference

```
#include "CullingManager.h"
```

Include dependency graph for CullingManager.cpp:



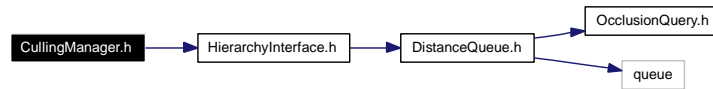
Namespaces

- namespace [GtpVisibility](#)

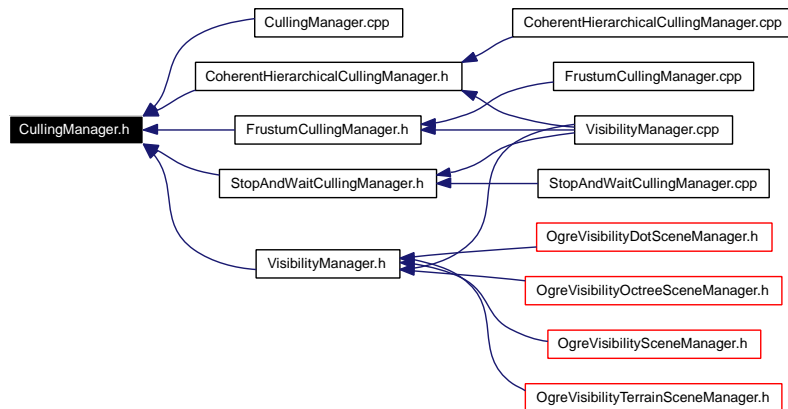
5.6 CullingManager.h File Reference

```
#include "HierarchyInterface.h"
```

Include dependency graph for CullingManager.h:



This graph shows which files directly or indirectly include this file:



Namespaces

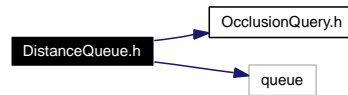
- namespace [GtpVisibility](#)

5.7 DistanceQueue.h File Reference

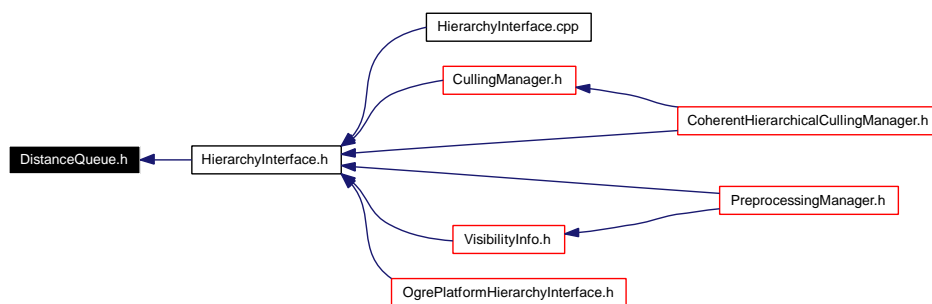
```
#include "OcclusionQuery.h"
```

```
#include <queue>
```

Include dependency graph for DistanceQueue.h:



This graph shows which files directly or indirectly include this file:



Namespaces

- namespace [GtpVisibility](#)

Typedefs

- typedef void [HierarchyNode](#)
- typedef `std::priority_queue< HierarchyNode *, std::vector< HierarchyNode * >, GreaterDistance< std::vector< HierarchyNode * >::value_type > >` [DistanceQueue](#)

5.7.1 Typedef Documentation

5.7.1.1 typedef void [GtpVisibility::HierarchyNode](#)

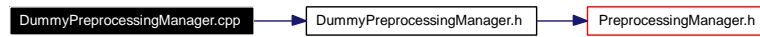
5.7.1.2 typedef `std::priority_queue< HierarchyNode *, std::vector< HierarchyNode * >, GreaterDistance< std::vector< HierarchyNode * >::value_type > >` [GtpVisibility::DistanceQueue](#)

A priority queue where closer hierarchy nodes are given a higher priority.

5.8 DummyPreprocessingManager.cpp File Reference

```
#include "DummyPreprocessingManager.h"
```

Include dependency graph for DummyPreprocessingManager.cpp:



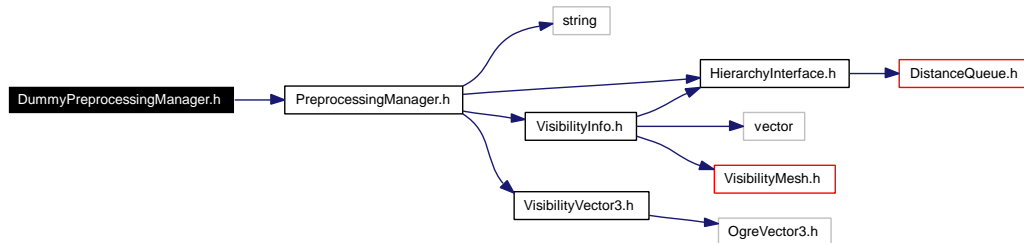
Namespaces

- namespace [GtpVisibility](#)

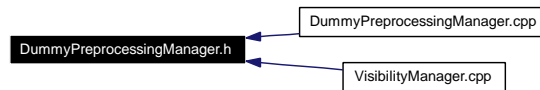
5.9 DummyPreprocessingManager.h File Reference

```
#include "PreprocessingManager.h"
```

Include dependency graph for DummyPreprocessingManager.h:



This graph shows which files directly or indirectly include this file:



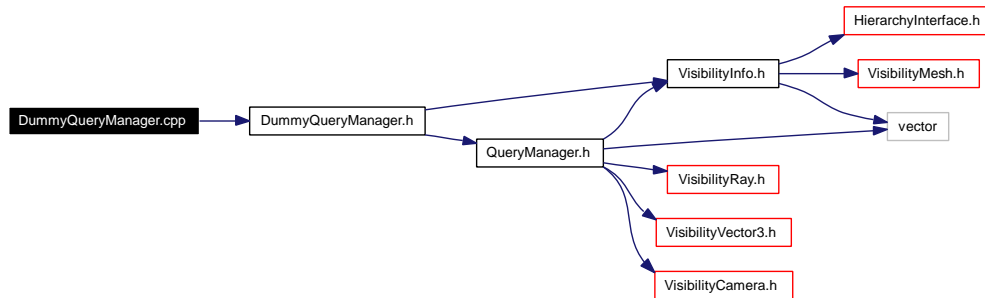
Namespaces

- namespace [GtpVisibility](#)

5.10 DummyQueryManager.cpp File Reference

```
#include "DummyQueryManager.h"
```

Include dependency graph for DummyQueryManager.cpp:



Namespaces

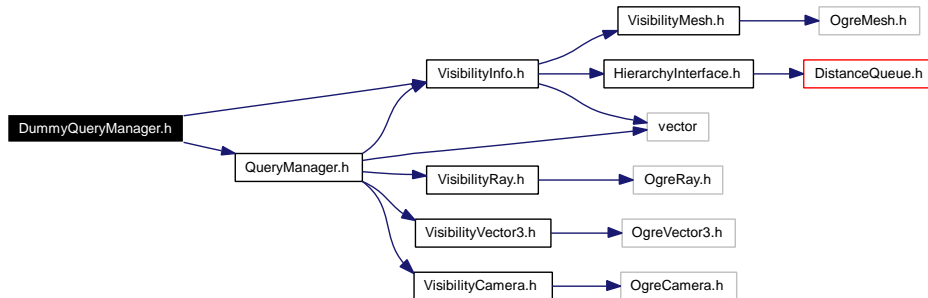
- namespace [GtpVisibility](#)

5.11 DummyQueryManager.h File Reference

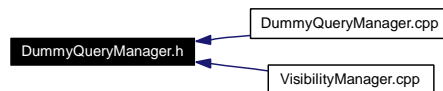
```
#include "VisibilityInfo.h"
```

```
#include "QueryManager.h"
```

Include dependency graph for DummyQueryManager.h:



This graph shows which files directly or indirectly include this file:



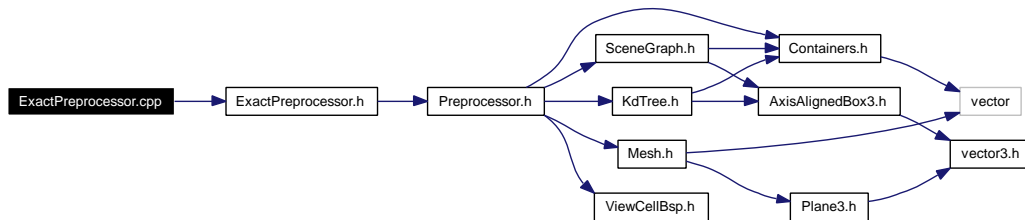
Namespaces

- namespace [GtpVisibility](#)

5.12 ExactPreprocessor.cpp File Reference

```
#include "ExactPreprocessor.h"
```

Include dependency graph for ExactPreprocessor.cpp:



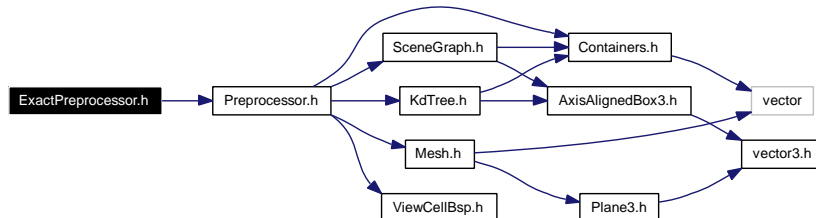
Namespaces

- namespace [GtpVisibilityPreprocessor](#)

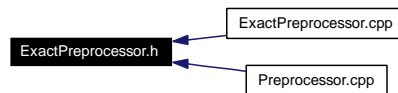
5.13 ExactPreprocessor.h File Reference

```
#include "Preprocessor.h"
```

Include dependency graph for ExactPreprocessor.h:



This graph shows which files directly or indirectly include this file:



Namespaces

- namespace [GtpVisibilityPreprocessor](#)

5.14 FrustumCullingManager.cpp File Reference

```
#include "FrustumCullingManager.h"
```

Include dependency graph for FrustumCullingManager.cpp:



Namespaces

- namespace [GtpVisibility](#)

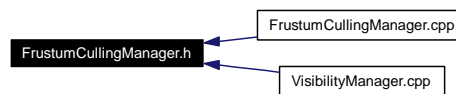
5.15 FrustumCullingManager.h File Reference

```
#include "CullingManager.h"
```

Include dependency graph for FrustumCullingManager.h:



This graph shows which files directly or indirectly include this file:



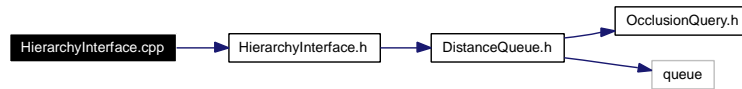
Namespaces

- namespace [GtpVisibility](#)

5.16 HierarchyInterface.cpp File Reference

```
#include "HierarchyInterface.h"
```

Include dependency graph for HierarchyInterface.cpp:



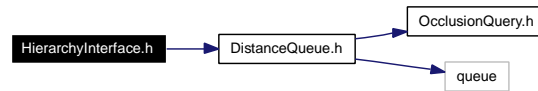
Namespaces

- namespace [GtpVisibility](#)

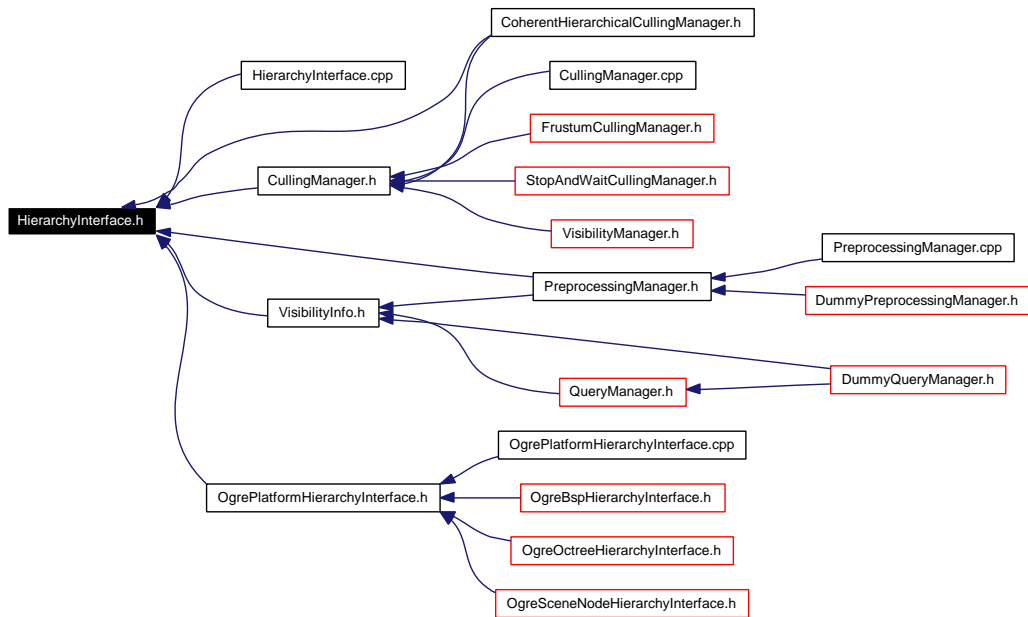
5.17 HierarchyInterface.h File Reference

```
#include "DistanceQueue.h"
```

Include dependency graph for HierarchyInterface.h:



This graph shows which files directly or indirectly include this file:



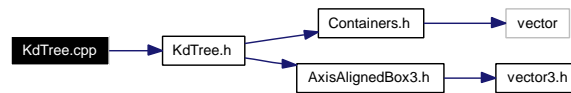
Namespaces

- namespace [GtpVisibility](#)

5.18 KdTree.cpp File Reference

```
#include "KdTree.h"
```

Include dependency graph for KdTree.cpp:



Namespaces

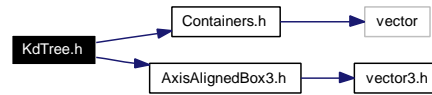
- namespace [GtpVisibilityPreprocessor](#)

5.19 KdTree.h File Reference

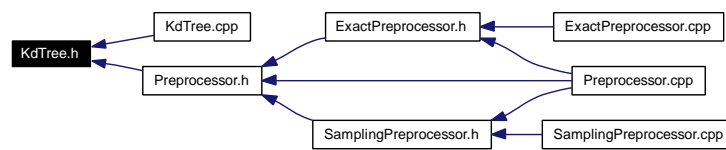
```
#include "Containers.h"
```

```
#include "AxisAlignedBox3.h"
```

Include dependency graph for KdTree.h:



This graph shows which files directly or indirectly include this file:



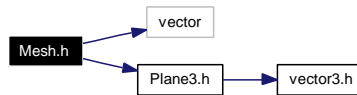
Namespaces

- namespace [GtpVisibilityPreprocessor](#)

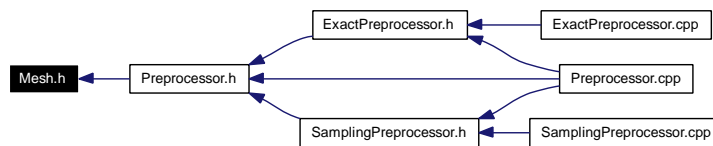
5.20 Mesh.h File Reference

```
#include <vector>
#include "Plane3.h"
```

Include dependency graph for Mesh.h:



This graph shows which files directly or indirectly include this file:

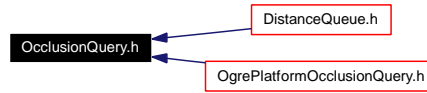


Namespaces

- namespace [GtpVisibilityPreprocessor](#)

5.21 OcclusionQuery.h File Reference

This graph shows which files directly or indirectly include this file:



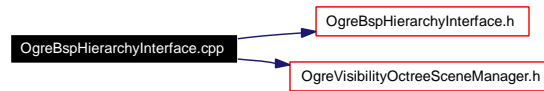
Namespaces

- namespace [GtpVisibility](#)

5.22 OgreBspHierarchyInterface.cpp File Reference

```
#include "OgreBspHierarchyInterface.h"  
#include "OgreVisibilityOctreeSceneManager.h"
```

Include dependency graph for OgreBspHierarchyInterface.cpp:



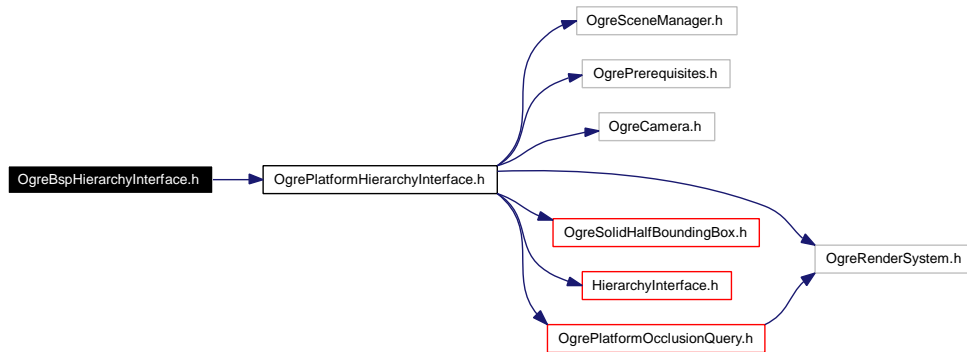
Namespaces

- namespace [Ogre](#)

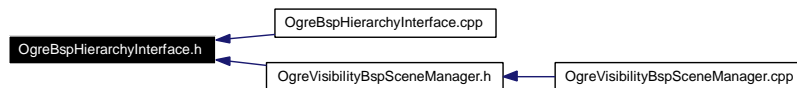
5.23 OgreBspHierarchyInterface.h File Reference

```
#include "OgrePlatformHierarchyInterface.h"
```

Include dependency graph for OgreBspHierarchyInterface.h:



This graph shows which files directly or indirectly include this file:



Namespaces

- namespace [Ogre](#)

5.24 OgreOctreeHierarchyInterface.cpp File Reference

```
#include "OgreOctreeHierarchyInterface.h"  
#include "OgreVisibilityOctreeSceneManager.h"  
#include <OgreOctree.h>
```

Include dependency graph for OgreOctreeHierarchyInterface.cpp:



Namespaces

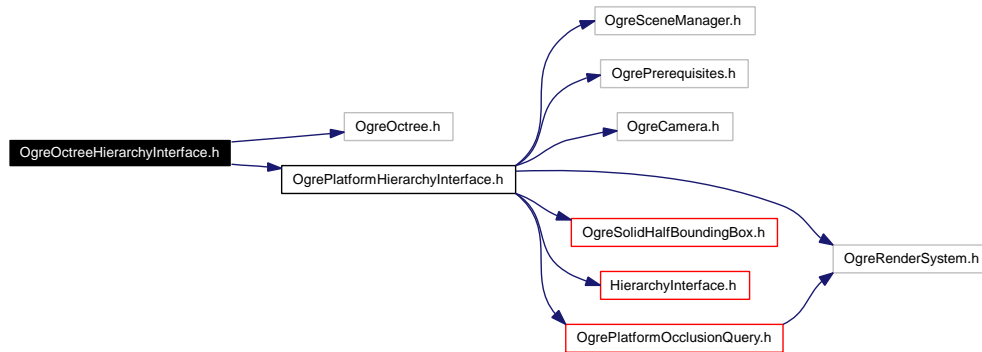
- namespace [Ogre](#)

5.25 OgreOctreeHierarchyInterface.h File Reference

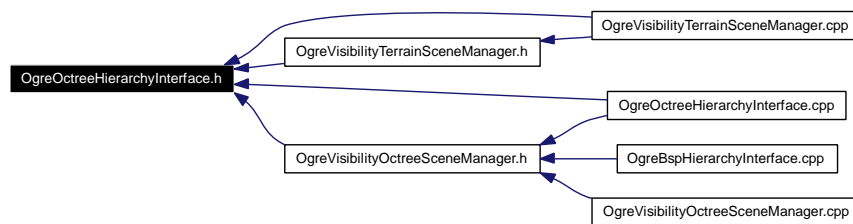
```
#include <OgreOctree.h>
```

```
#include "OgrePlatformHierarchyInterface.h"
```

Include dependency graph for OgreOctreeHierarchyInterface.h:



This graph shows which files directly or indirectly include this file:



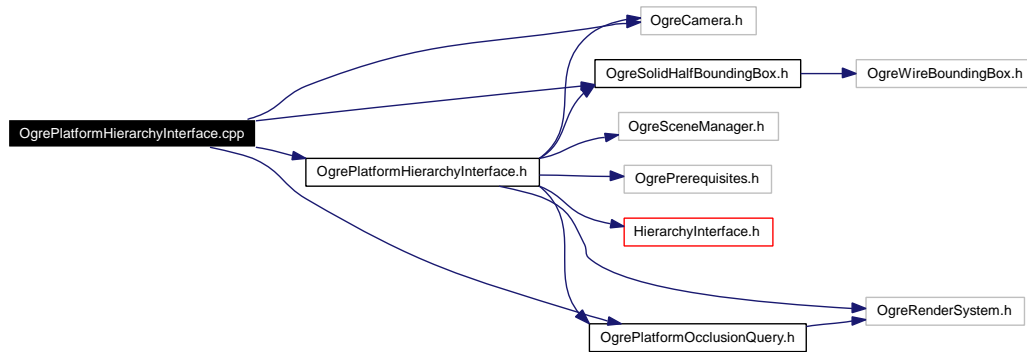
Namespaces

- namespace [Ogre](#)

5.26 OgrePlatformHierarchyInterface.cpp File Reference

```
#include <OgreCamera.h>
#include "OgreSolidHalfBoundingBox.h"
#include "OgrePlatformHierarchyInterface.h"
#include "OgrePlatformOcclusionQuery.h"
```

Include dependency graph for OgrePlatformHierarchyInterface.cpp:



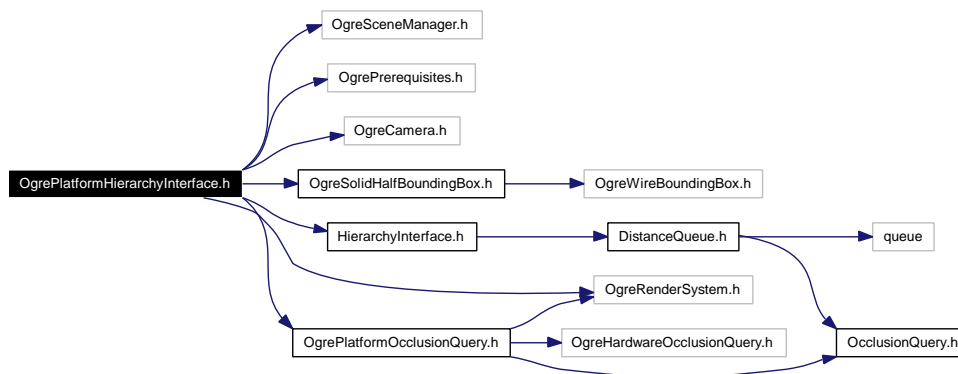
Namespaces

- namespace [Ogre](#)

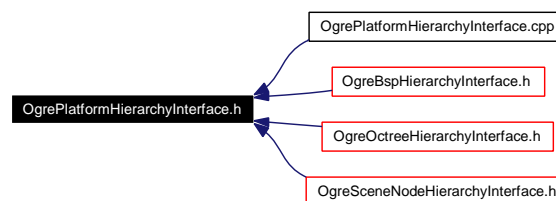
5.27 OgrePlatformHierarchyInterface.h File Reference

```
#include <OgreSceneManager.h>
#include <OgrePrerequisites.h>
#include <OgreCamera.h>
#include <OgreRenderSystem.h>
#include "OgreSolidHalfBoundingBox.h"
#include "HierarchyInterface.h"
#include "OgrePlatformOcclusionQuery.h"
```

Include dependency graph for OgrePlatformHierarchyInterface.h:



This graph shows which files directly or indirectly include this file:



Namespaces

- namespace [Ogre](#)

5.28 OgrePlatformOcclusionQuery.cpp File Reference

```
#include "OgrePlatformOcclusionQuery.h"
```

Include dependency graph for OgrePlatformOcclusionQuery.cpp:



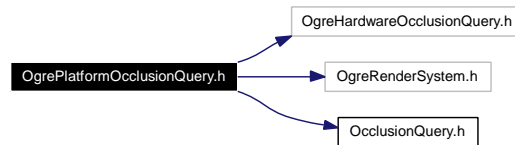
Namespaces

- namespace [Ogre](#)

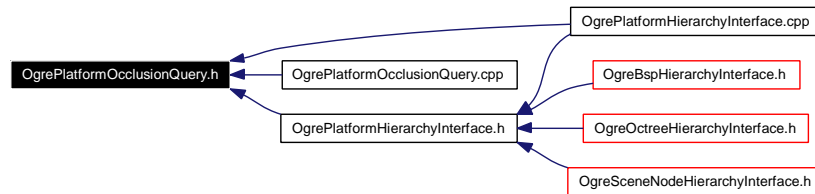
5.29 OgrePlatformOcclusionQuery.h File Reference

```
#include <OgreHardwareOcclusionQuery.h>
#include <OgreRenderSystem.h>
#include "OcclusionQuery.h"
```

Include dependency graph for OgrePlatformOcclusionQuery.h:



This graph shows which files directly or indirectly include this file:



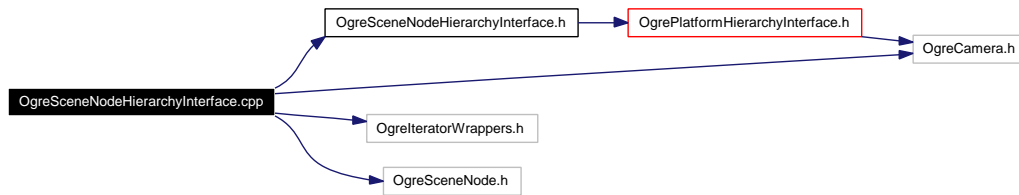
Namespaces

- namespace [Ogre](#)

5.30 OgreSceneNodeHierarchyInterface.cpp File Reference

```
#include "OgreSceneNodeHierarchyInterface.h"  
#include <OgreIteratorWrappers.h>  
#include <OgreCamera.h>  
#include <OgreSceneNode.h>
```

Include dependency graph for OgreSceneNodeHierarchyInterface.cpp:



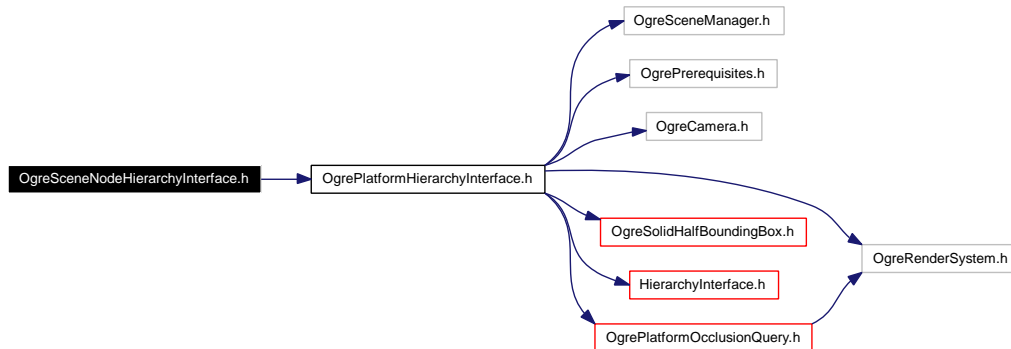
Namespaces

- namespace [Ogre](#)

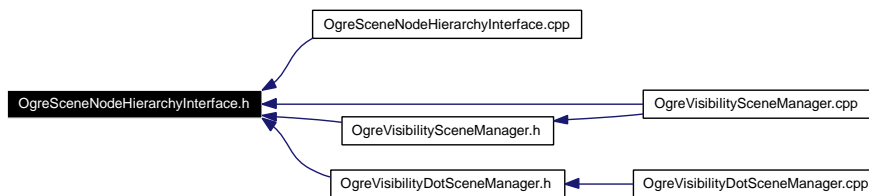
5.31 OgreSceneNodeHierarchyInterface.h File Reference

```
#include "OgrePlatformHierarchyInterface.h"
```

Include dependency graph for OgreSceneNodeHierarchyInterface.h:



This graph shows which files directly or indirectly include this file:



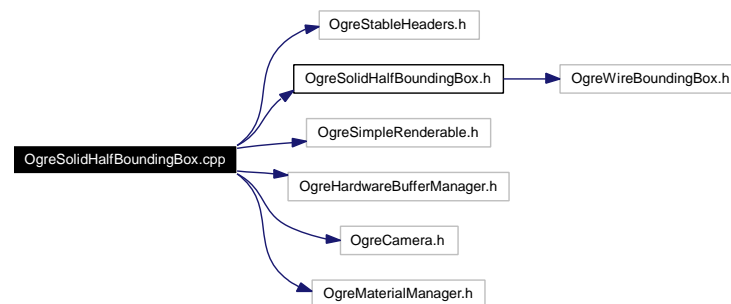
Namespaces

- namespace [Ogre](#)

5.32 OgreSolidHalfBoundingBox.cpp File Reference

```
#include "OgreStableHeaders.h"  
#include "OgreSolidHalfBoundingBox.h"  
#include "OgreSimpleRenderable.h"  
#include "OgreHardwareBufferManager.h"  
#include "OgreCamera.h"  
#include "OgreMaterialManager.h"
```

Include dependency graph for OgreSolidHalfBoundingBox.cpp:



Namespaces

- namespace [Ogre](#)

Defines

- `#define` [POSITION_BINDING](#) 0

5.32.1 Define Documentation

5.32.1.1 `#define` [POSITION_BINDING](#) 0

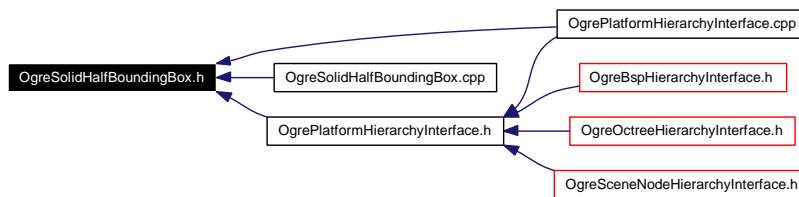
5.33 OgreSolidHalfBoundingBox.h File Reference

```
#include "OgreWireBoundingBox.h"
```

Include dependency graph for OgreSolidHalfBoundingBox.h:



This graph shows which files directly or indirectly include this file:



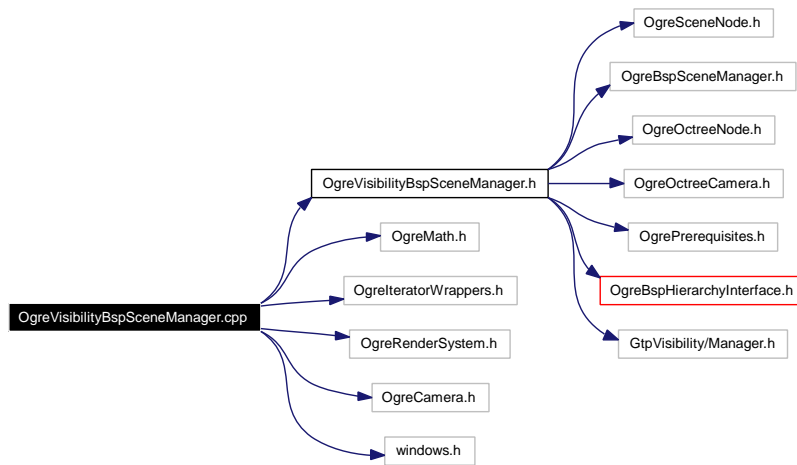
Namespaces

- namespace [Ogre](#)

5.34 OgreVisibilityBspSceneManager.cpp File Reference

```
#include "OgreVisibilityBspSceneManager.h"  
#include <OgreMath.h>  
#include <OgreIteratorWrappers.h>  
#include <OgreRenderSystem.h>  
#include <OgreCamera.h>  
#include <windows.h>
```

Include dependency graph for OgreVisibilityBspSceneManager.cpp:



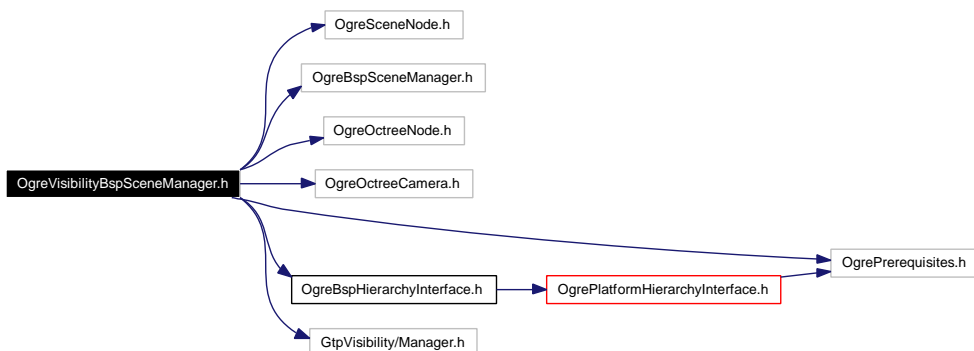
Namespaces

- namespace [Ogre](#)

5.35 OgreVisibilityBspSceneManager.h File Reference

```
#include <OgreSceneNode.h>
#include <OgreBspSceneManager.h>
#include <OgreOctreeNode.h>
#include <OgreOctreeCamera.h>
#include <OgrePrerequisites.h>
#include "OgreBspHierarchyInterface.h"
#include "GtpVisibility/Manager.h"
```

Include dependency graph for OgreVisibilityBspSceneManager.h:



This graph shows which files directly or indirectly include this file:



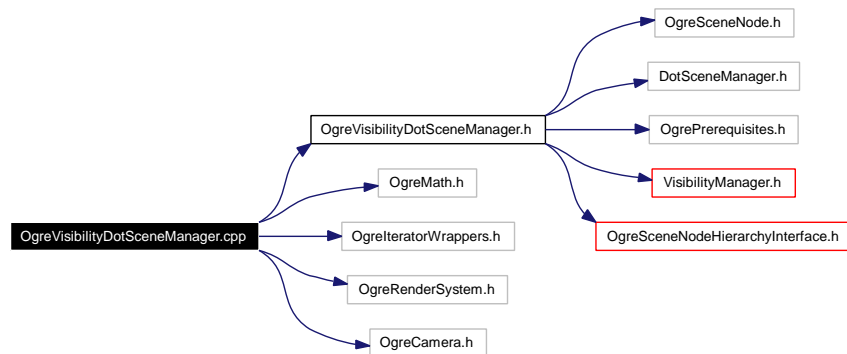
Namespaces

- namespace `Ogre`

5.36 OgreVisibilityDotSceneManager.cpp File Reference

```
#include <OgreVisibilityDotSceneManager.h>
#include <OgreMath.h>
#include <OgreIteratorWrappers.h>
#include <OgreRenderSystem.h>
#include <OgreCamera.h>
```

Include dependency graph for OgreVisibilityDotSceneManager.cpp:



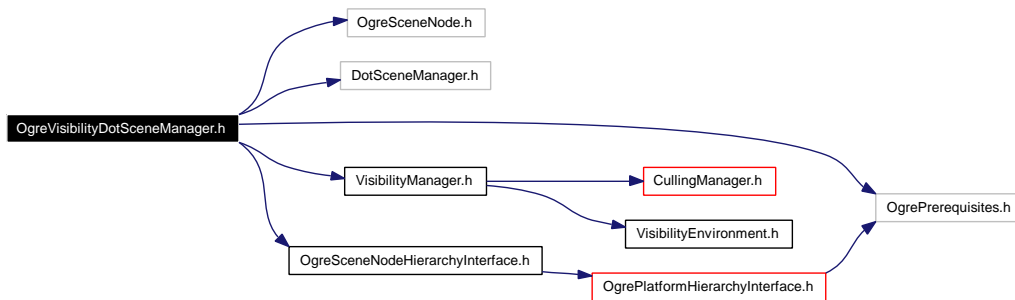
Namespaces

- namespace [Ogre](#)

5.37 OgreVisibilityDotSceneManager.h File Reference

```
#include <OgreSceneNode.h>
#include <DotSceneManager.h>
#include <OgrePrerequisites.h>
#include "VisibilityManager.h"
#include "OgreSceneNodeHierarchyInterface.h"
```

Include dependency graph for OgreVisibilityDotSceneManager.h:



This graph shows which files directly or indirectly include this file:



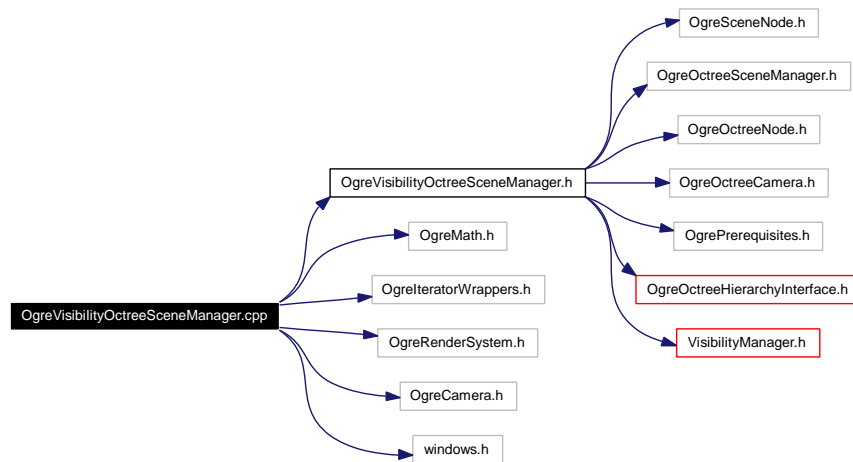
Namespaces

- namespace `Ogre`

5.38 OgreVisibilityOctreeSceneManager.cpp File Reference

```
#include "OgreVisibilityOctreeSceneManager.h"  
#include <OgreMath.h>  
#include <OgreIteratorWrappers.h>  
#include <OgreRenderSystem.h>  
#include <OgreCamera.h>  
#include <windows.h>
```

Include dependency graph for OgreVisibilityOctreeSceneManager.cpp:



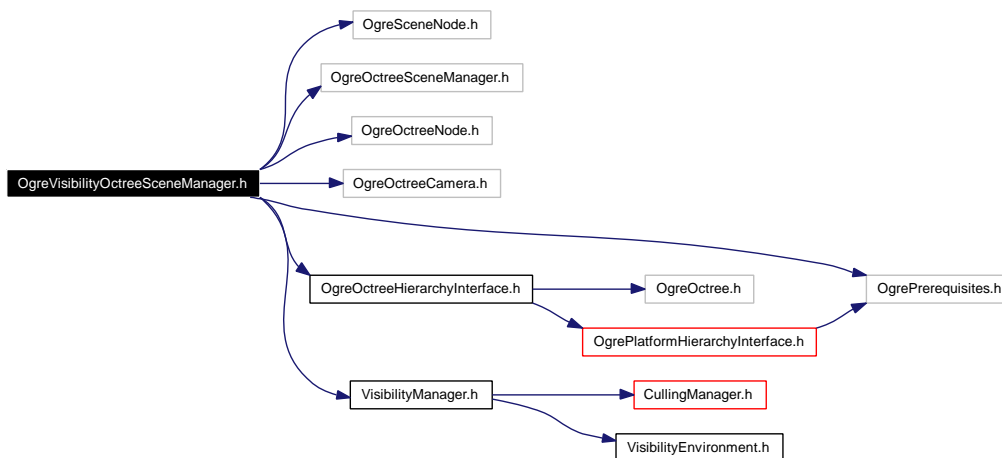
Namespaces

- namespace [Ogre](#)

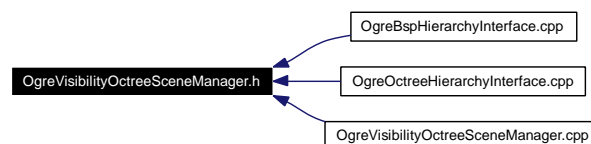
5.39 OgreVisibilityOctreeSceneManager.h File Reference

```
#include <OgreSceneNode.h>
#include <OgreOctreeSceneManager.h>
#include <OgreOctreeNode.h>
#include <OgreOctreeCamera.h>
#include <OgrePrerequisites.h>
#include "OgreOctreeHierarchyInterface.h"
#include "VisibilityManager.h"
```

Include dependency graph for OgreVisibilityOctreeSceneManager.h:



This graph shows which files directly or indirectly include this file:



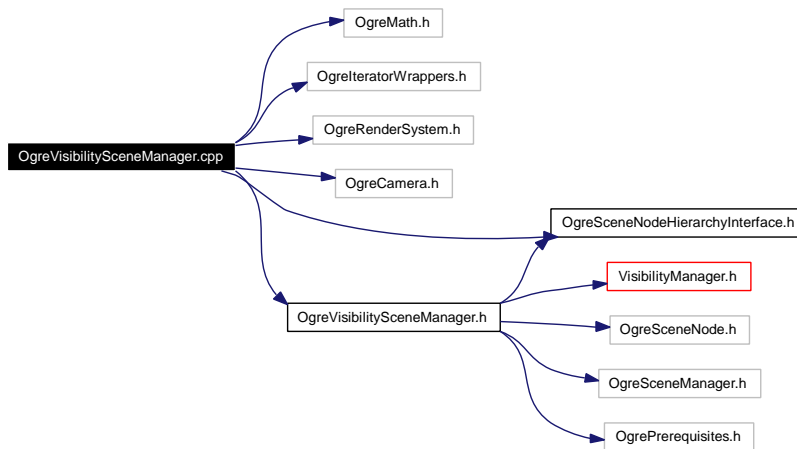
Namespaces

- namespace [Ogre](#)

5.40 OgreVisibilitySceneManager.cpp File Reference

```
#include <OgreMath.h>
#include <OgreIteratorWrappers.h>
#include <OgreRenderSystem.h>
#include <OgreCamera.h>
#include "OgreVisibilitySceneManager.h"
#include "OgreSceneNodeHierarchyInterface.h"
```

Include dependency graph for OgreVisibilitySceneManager.cpp:



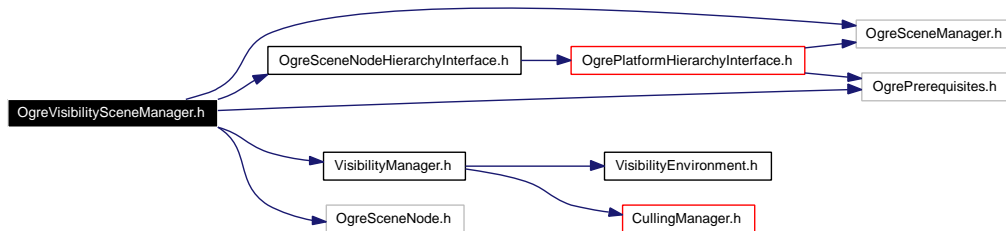
Namespaces

- namespace [Ogre](#)

5.41 OgreVisibilitySceneManager.h File Reference

```
#include "OgreSceneNodeHierarchyInterface.h"
#include "VisibilityManager.h"
#include <OgreSceneNode.h>
#include <OgreSceneManager.h>
#include <OgrePrerequisites.h>
```

Include dependency graph for OgreVisibilitySceneManager.h:



This graph shows which files directly or indirectly include this file:



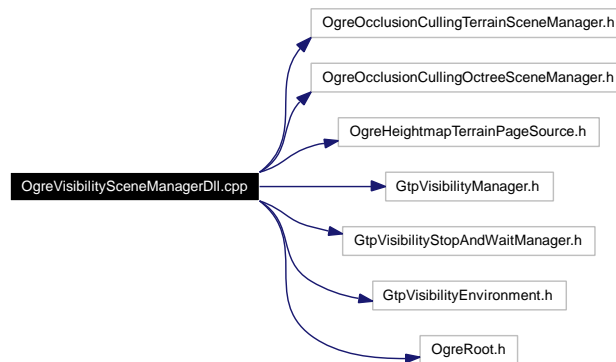
Namespaces

- namespace [Ogre](#)

5.42 OgreVisibilitySceneManagerDll.cpp File Reference

```
#include <OgreOcclusionCullingTerrainSceneManager.h>
#include <OgreOcclusionCullingOctreeSceneManager.h>
#include <OgreHeightmapTerrainPageSource.h>
#include "GtpVisibilityManager.h"
#include "GtpVisibilityStopAndWaitManager.h"
#include "GtpVisibilityEnvironment.h"
#include <OgreRoot.h>
```

Include dependency graph for OgreVisibilitySceneManagerDll.cpp:



Namespaces

- namespace [Ogre](#)

Functions

- void [dllStartPlugin](#) (void)
- void [dllStopPlugin](#) (void)

Variables

- GtpVisibility::Environment * [visEnv](#)
- GtpVisibility::Manager * [visManager](#)
- OcclusionCullingOctreeSceneManager * [cullingOctreePlugin](#)
- OcclusionCullingTerrainSceneManager * [cullingTerrainPlugin](#)
- HeightmapTerrainPageSource * [heightmapTerrainPageSource](#)

5.42.1 Function Documentation

5.42.1.1 void `Ogre::dllStartPlugin` (void)

5.42.1.2 void `Ogre::dllStopPlugin` (void)

5.42.2 Variable Documentation

5.42.2.1 `GtpVisibility::Environment*` [visEnv](#)

5.42.2.2 `GtpVisibility::Manager*` [visManager](#)

5.42.2.3 `OcclusionCullingOctreeSceneManager*` [Ogre::cullingOctreePlugin](#)

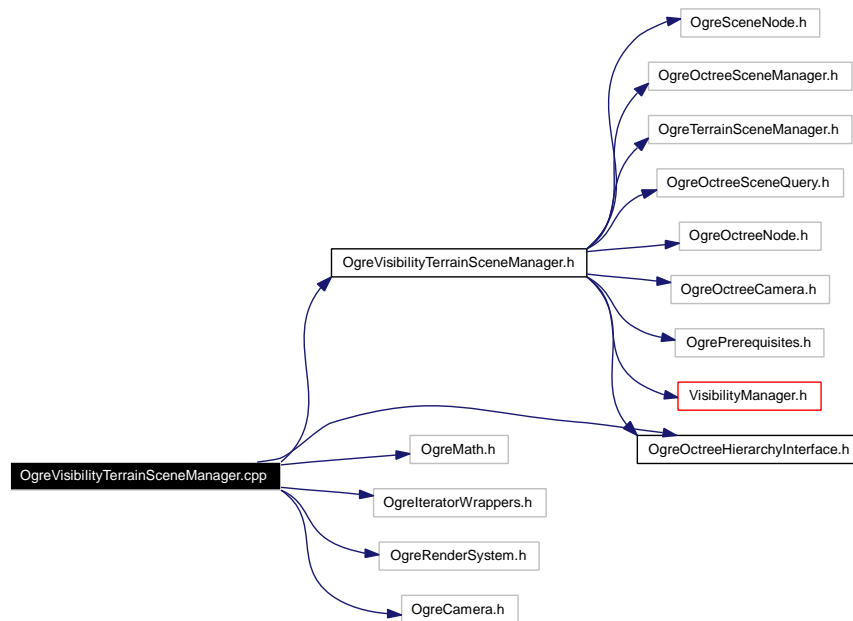
5.42.2.4 `OcclusionCullingTerrainSceneManager*` [Ogre::cullingTerrainPlugin](#)

5.42.2.5 `HeightmapTerrainPageSource*` [Ogre::heightmapTerrainPageSource](#)

5.43 OgreVisibilityTerrainSceneManager.cpp File Reference

```
#include "OgreVisibilityTerrainSceneManager.h"  
#include "OgreOctreeHierarchyInterface.h"  
#include <OgreMath.h>  
#include <OgreIteratorWrappers.h>  
#include <OgreRenderSystem.h>  
#include <OgreCamera.h>
```

Include dependency graph for OgreVisibilityTerrainSceneManager.cpp:



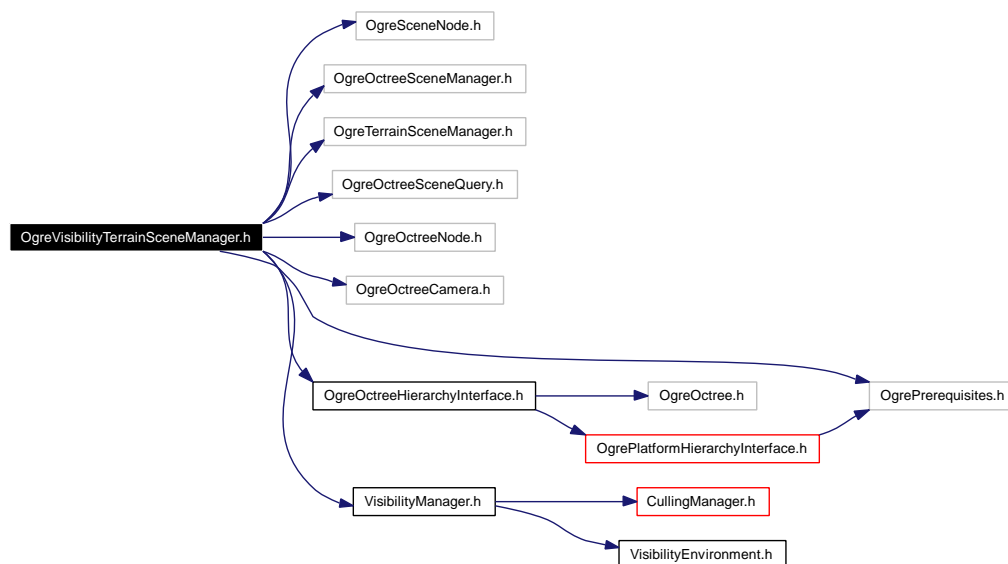
Namespaces

- namespace [Ogre](#)

5.44 OgreVisibilityTerrainSceneManager.h File Reference

```
#include <OgreSceneNode.h>
#include <OgreOctreeSceneManager.h>
#include <OgreTerrainSceneManager.h>
#include <OgreOctreeSceneQuery.h>
#include <OgreOctreeNode.h>
#include <OgreOctreeCamera.h>
#include <OgrePrerequisites.h>
#include "OgreOctreeHierarchyInterface.h"
#include "VisibilityManager.h"
```

Include dependency graph for OgreVisibilityTerrainSceneManager.h:



This graph shows which files directly or indirectly include this file:



Namespaces

- namespace [Ogre](#)

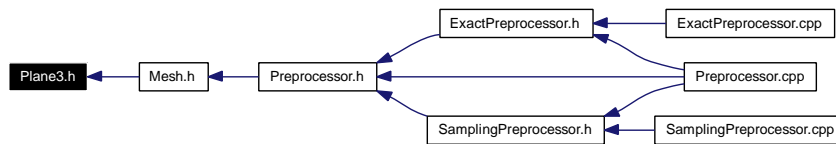
5.45 Plane3.h File Reference

```
#include "vector3.h"
```

Include dependency graph for Plane3.h:



This graph shows which files directly or indirectly include this file:



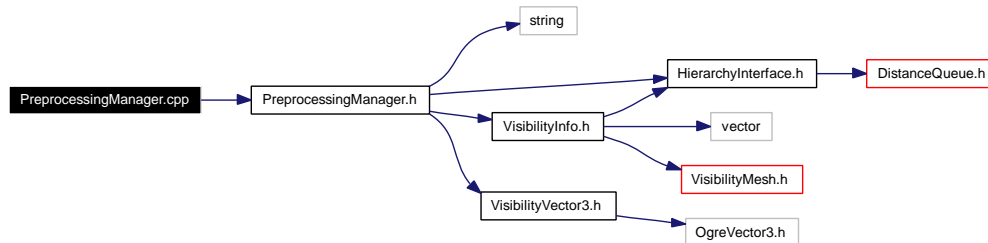
Namespaces

- namespace [GtpVisibilityPreprocessor](#)

5.46 PreprocessingManager.cpp File Reference

```
#include "PreprocessingManager.h"
```

Include dependency graph for PreprocessingManager.cpp:



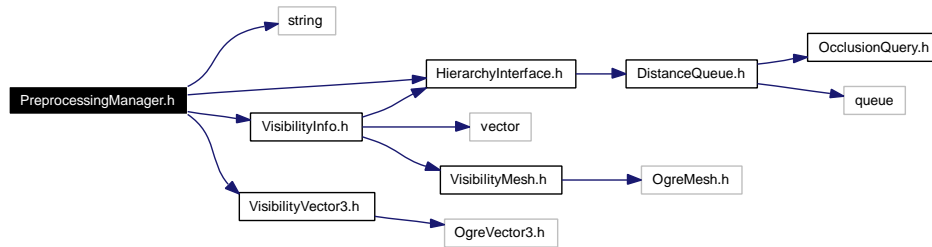
Namespaces

- namespace [GtpVisibility](#)

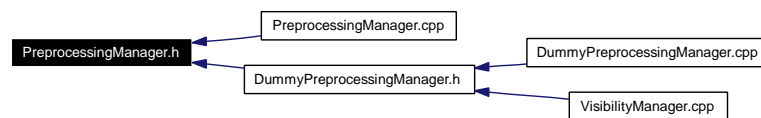
5.47 PreprocessingManager.h File Reference

```
#include <string>
#include "HierarchyInterface.h"
#include "VisibilityInfo.h"
#include "VisibilityVector3.h"
```

Include dependency graph for PreprocessingManager.h:



This graph shows which files directly or indirectly include this file:



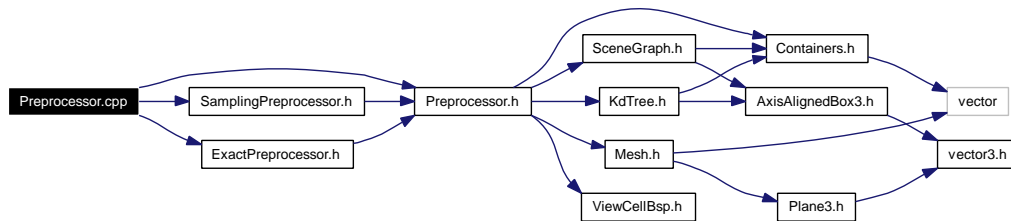
Namespaces

- namespace [GtpVisibility](#)
- namespace [std](#)

5.48 Preprocessor.cpp File Reference

```
#include "Preprocessor.h"
#include "SamplingPreprocessor.h"
#include "ExactPreprocessor.h"
```

Include dependency graph for Preprocessor.cpp:



Namespaces

- namespace [GtpVisibilityPreprocessor](#)

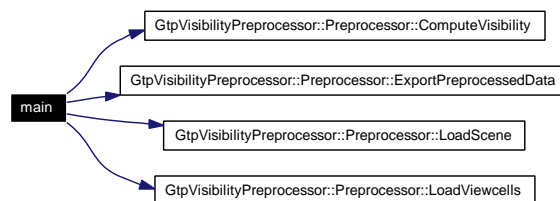
Functions

- int [main](#) (int argc, char **argv)

5.48.1 Function Documentation

5.48.1.1 int main (int argc, char ** argv)

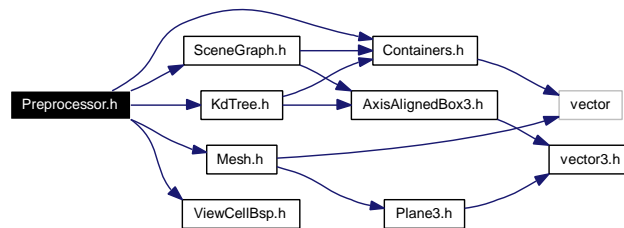
Here is the call graph for this function:



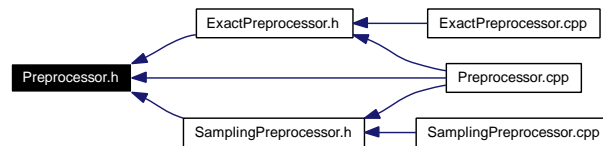
5.49 Preprocessor.h File Reference

```
#include "Containers.h"
#include "Mesh.h"
#include "KdTree.h"
#include "ViewCellBsp.h"
#include "SceneGraph.h"
```

Include dependency graph for Preprocessor.h:



This graph shows which files directly or indirectly include this file:



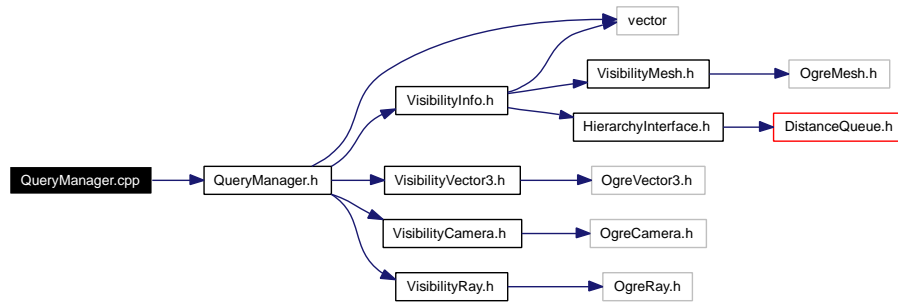
Namespaces

- namespace [GtpVisibilityPreprocessor](#)

5.50 QueryManager.cpp File Reference

```
#include "QueryManager.h"
```

Include dependency graph for QueryManager.cpp:



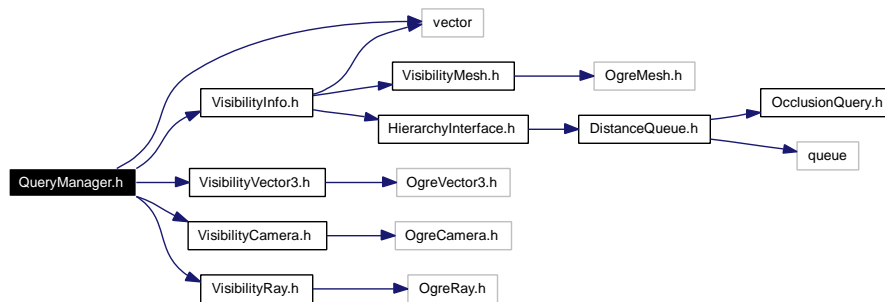
Namespaces

- namespace [GtpVisibility](#)

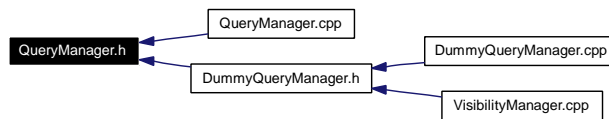
5.51 QueryManager.h File Reference

```
#include <vector>
#include "VisibilityInfo.h"
#include "VisibilityVector3.h"
#include "VisibilityCamera.h"
#include "VisibilityRay.h"
```

Include dependency graph for QueryManager.h:



This graph shows which files directly or indirectly include this file:



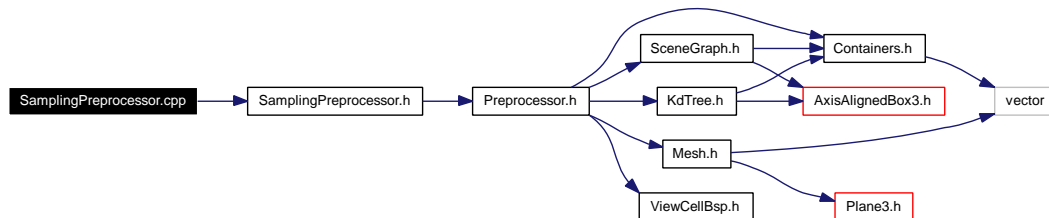
Namespaces

- namespace [GtpVisibility](#)

5.52 SamplingPreprocessor.cpp File Reference

```
#include "SamplingPreprocessor.h"
```

Include dependency graph for SamplingPreprocessor.cpp:



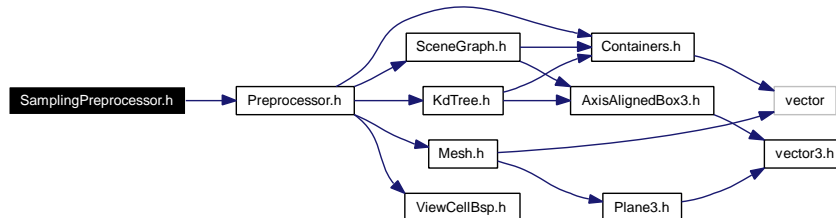
Namespaces

- namespace [GtpVisibilityPreprocessor](#)

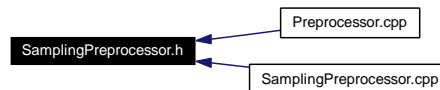
5.53 SamplingPreprocessor.h File Reference

```
#include "Preprocessor.h"
```

Include dependency graph for SamplingPreprocessor.h:



This graph shows which files directly or indirectly include this file:



Namespaces

- namespace [GtpVisibilityPreprocessor](#)

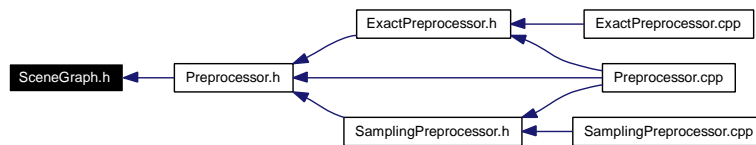
5.54 SceneGraph.h File Reference

```
#include "Containers.h"  
#include "AxisAlignedBox3.h"
```

Include dependency graph for SceneGraph.h:



This graph shows which files directly or indirectly include this file:



Namespaces

- namespace [GtpVisibilityPreprocessor](#)

5.55 StopAndWaitCullingManager.cpp File Reference

```
#include "StopAndWaitCullingManager.h"
```

Include dependency graph for StopAndWaitCullingManager.cpp:



Namespaces

- namespace [GtpVisibility](#)

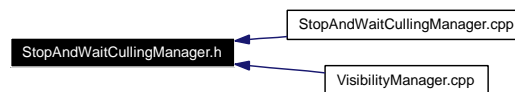
5.56 StopAndWaitCullingManager.h File Reference

```
#include "CullingManager.h"
```

Include dependency graph for StopAndWaitCullingManager.h:



This graph shows which files directly or indirectly include this file:

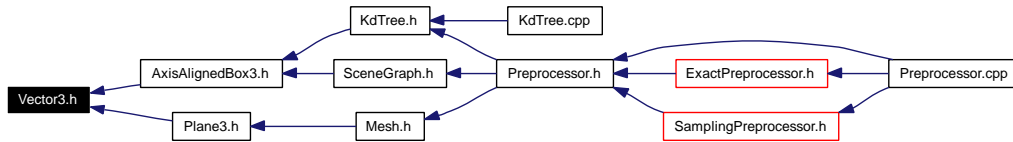


Namespaces

- namespace [GtpVisibility](#)

5.57 Vector3.h File Reference

This graph shows which files directly or indirectly include this file:

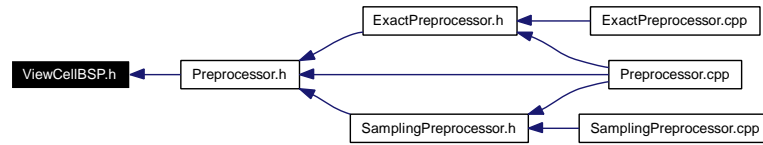


Namespaces

- namespace [GtpVisibilityPreprocessor](#)

5.58 ViewCellBSP.h File Reference

This graph shows which files directly or indirectly include this file:



Namespaces

- namespace [GtpVisibilityPreprocessor](#)

5.59 VisibilityAxisAlignedBox.h File Reference

```
#include "OgreAxisAlignedBox.h"
```

Include dependency graph for VisibilityAxisAlignedBox.h:



Namespaces

- namespace [GtpVisibility](#)

Typedefs

- typedef [Ogre::AxisAlignedBox](#) [AxisAlignedBox](#)

5.59.1 Typedef Documentation

5.59.1.1 typedef [Ogre::AxisAlignedBox](#) [GtpVisibility::AxisAlignedBox](#)

This class currently uses the native [Ogre](#) [AxisAlignedBox](#) when compiled with the [Ogre](#) platform

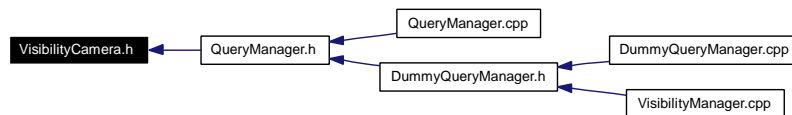
5.60 VisibilityCamera.h File Reference

```
#include "OgreCamera.h"
```

Include dependency graph for VisibilityCamera.h:



This graph shows which files directly or indirectly include this file:



Namespaces

- namespace [GtpVisibility](#)

Typedefs

- typedef [Ogre::Camera](#) [GtpVisibility::Camera](#)

5.60.1 Typedef Documentation

5.60.1.1 typedef [Ogre::Camera](#) [GtpVisibility::Camera](#)

Camera class currently uses the native [Ogre](#) camera when compiled with the [Ogre](#) platform

5.61 VisibilityEnvironment.cpp File Reference

```
#include "VisibilityEnvironment.h"
```

Include dependency graph for VisibilityEnvironment.cpp:

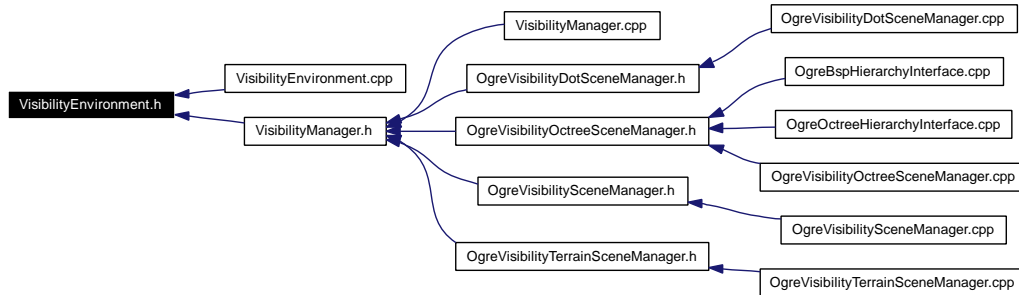


Namespaces

- namespace [GtpVisibility](#)

5.62 VisibilityEnvironment.h File Reference

This graph shows which files directly or indirectly include this file:

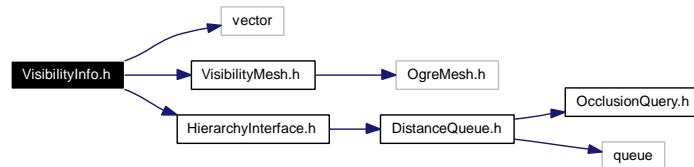


Namespaces

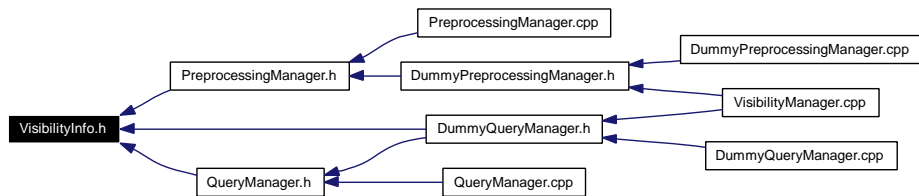
- namespace [GtpVisibility](#)

5.63 VisibilityInfo.h File Reference

```
#include <vector>
#include "VisibilityMesh.h"
#include "HierarchyInterface.h"
Include dependency graph for VisibilityInfo.h:
```



This graph shows which files directly or indirectly include this file:



Namespaces

- namespace [GtpVisibility](#)

Defines

- #define [InfoContainer](#) std::vector

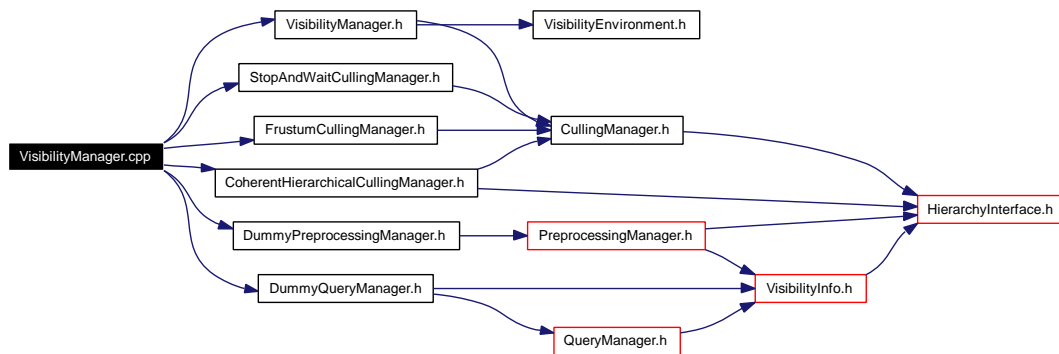
5.63.1 Define Documentation

5.63.1.1 #define InfoContainer std::vector

5.64 VisibilityManager.cpp File Reference

```
#include "VisibilityManager.h"  
#include "StopAndWaitCullingManager.h"  
#include "CoherentHierarchicalCullingManager.h"  
#include "FrustumCullingManager.h"  
#include "DummyPreprocessingManager.h"  
#include "DummyQueryManager.h"
```

Include dependency graph for VisibilityManager.cpp:



Namespaces

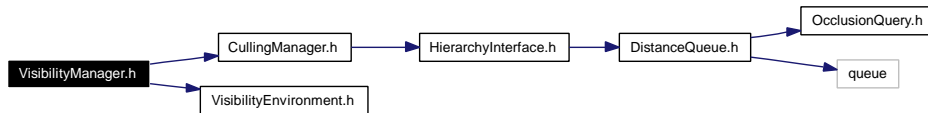
- namespace [GtpVisibility](#)

5.65 VisibilityManager.h File Reference

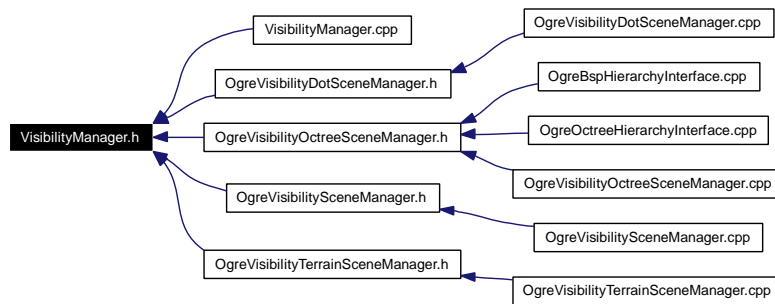
```
#include "CullingManager.h"
```

```
#include "VisibilityEnvironment.h"
```

Include dependency graph for VisibilityManager.h:



This graph shows which files directly or indirectly include this file:



Namespaces

- namespace [GtpVisibility](#)

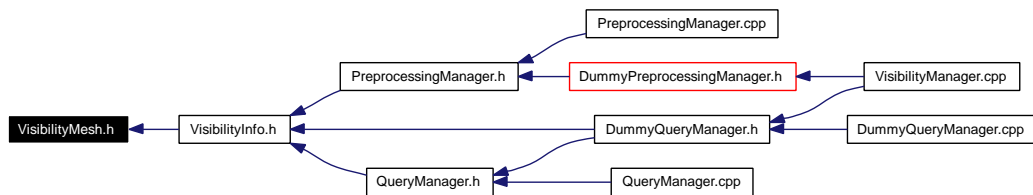
5.66 VisibilityMesh.h File Reference

```
#include "OgreMesh.h"
```

Include dependency graph for VisibilityMesh.h:



This graph shows which files directly or indirectly include this file:



Namespaces

- namespace [GtpVisibility](#)

Typedefs

- typedef [Ogre::Mesh Mesh](#)

5.66.1 Typedef Documentation

5.66.1.1 typedef [Ogre::Mesh GtpVisibility::Mesh](#)

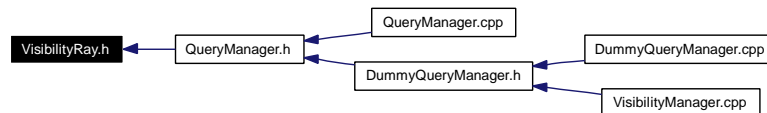
5.67 VisibilityRay.h File Reference

```
#include "OgreRay.h"
```

Include dependency graph for VisibilityRay.h:



This graph shows which files directly or indirectly include this file:



Namespaces

- namespace [GtpVisibility](#)

Typedefs

- typedef [Ogre::Ray Ray](#)

5.67.1 Typedef Documentation

5.67.1.1 typedef [Ogre::Ray GtpVisibility::Ray](#)

Ray class currently uses native [Ogre](#) ray when compiled with the [Ogre](#) platform

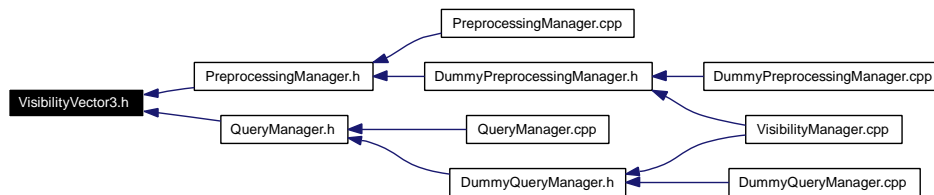
5.68 VisibilityVector3.h File Reference

```
#include "OgreVector3.h"
```

Include dependency graph for VisibilityVector3.h:



This graph shows which files directly or indirectly include this file:



Namespaces

- namespace [GtpVisibility](#)

Typedefs

- typedef [Ogre::Vector3](#) [Vector3](#)

5.68.1 Typedef Documentation

5.68.1.1 typedef [Ogre::Vector3](#) [GtpVisibility::Vector3](#)

Vector3 class currently uses the native [Ogre](#) vector when compiled with the [Ogre](#) platform

Chapter 6

GameTools Visibility Modules Class Index

6.1 GameTools Visibility Modules Class List

Here are the classes, structs, unions and interfaces with brief descriptions:

GtpVisibilityPreprocessor::AxisAlignedBox3	85
Ogre::BspHierarchyInterface	5
GtpVisibilityPreprocessor::BSPInterior	86
GtpVisibilityPreprocessor::BSPLeaf	88
GtpVisibilityPreprocessor::BSPNode	90
GtpVisibilityPreprocessor::BSPTree	92
GtpVisibility::CoherentHierarchicalCullingManager	44
GtpVisibility::CullingManager	47
GtpVisibility::DummyPreprocessingManager	50
GtpVisibility::DummyQueryManager	53
GtpVisibilityPreprocessor::ExactPreprocessor	94
GtpVisibility::FrustumCullingManager	56
GtpVisibility::GreaterDistance< T >	59
GtpVisibility::HierarchyInterface	61
GtpVisibilityPreprocessor::KdInterior	97
GtpVisibilityPreprocessor::KdLeaf	99
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GtpVisibility::QueryManager	76
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Ogre::VisibilityDotSceneManager	32
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Chapter 7

GameTools Visibility Modules Namespace Index

7.1 GameTools Visibility Modules Namespace List

Here is a list of all namespaces with brief descriptions:

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Ogre	122

Chapter 8

GameTools Visibility Modules File Index

8.1 GameTools Visibility Modules File List

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